

An Easy Exercise in Hoare's Logic: Imperative Expressions

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Background

- student's question:

Where does one put a loop invariant when the loop guard may have side effects?

- my answer:

*Hoare logic for while-programs with imperative expressions: this **must** be well-known!*

- search through the literature, asking THOSE-WHO-MUST-KNOW:

:-)

- one way to proceed:

D.I.Y.

... and present it to WG1.3 to find out who and where did this earlier...

The standard case

Built-in data type:

- signature: $\Sigma_{\mathbf{D}} = \langle \langle \Omega_n \rangle_{n \in N}, \langle \Pi_n \rangle_{n \in N} \rangle$
- semantic structure \mathbf{D} with:
 - carrier D
 - operations $f_{\mathbf{D}}: D^n \rightarrow D$ for $f \in \Omega_n, n \in N$
 - predicates $p_{\mathbf{D}}: D^n \rightarrow \mathbf{B}$ for $p \in \Pi_n, n \in N$

where $\mathbf{B} = \{\mathbf{ff}, \mathbf{tt}\}$

*Single sorted...
only to keep the notation simple...*

While-programs

$x \in \mathbf{Var} ::= \dots$

$e \in \mathbf{Exp} ::= x \mid f(e_1, \dots, e_n) \quad (\text{for each } f \in \Omega_n, n \in N)$

$b \in \mathbf{BExp} ::= \mathbf{true} \mid \mathbf{false} \mid \neg b' \mid b_1 \wedge b_2 \mid p(e_1, \dots, e_n) \quad (\text{for each } p \in \Pi_n, n \in N)$

$S \in \mathbf{Stmt} ::= x := e \mid \mathbf{skip} \mid S_1; S_2 \mid \mathbf{if } b \mathbf{ then } S_1 \mathbf{ else } S_2 \mid \mathbf{while } b \mathbf{ do } S'$

Semantics

$\mathcal{E}: \mathbf{Exp} \rightarrow \mathbf{State} \rightarrow D$

$\mathcal{B}: \mathbf{BExp} \rightarrow \mathbf{State} \rightarrow \mathbf{B}$

$\mathcal{S}: \mathbf{Stmt} \rightarrow \mathbf{State} \rightarrow \mathbf{State}$

Standard semantic clauses omitted

where $\mathbf{State} = \mathbf{Var} \rightarrow D$.

Judgements

Whenever program $S \in \mathbf{Stmt}$ starts in a state satisfying precondition $\varphi \in \mathcal{L}$ and terminates successfully, then the final state satisfies postcondition $\psi \in \mathcal{L}$

$$\{\varphi\} S \{\psi\}$$

Semantic satisfaction

$$\models \{\varphi\} S \{\psi\}$$

iff

for $s \in \mathbf{State}$, if $\llbracket \varphi \rrbracket s = \mathbf{tt}$ and $\mathcal{S}[[S]] s = s'$ then $\llbracket \psi \rrbracket s' = \mathbf{tt}$

where $\llbracket - \rrbracket : \mathcal{L} \rightarrow \mathbf{State} \rightarrow \mathbf{B}$ gives the semantics of formulae in \mathcal{L}

Proof system

$$\frac{}{\{\varphi[x \mapsto e]\} x := e \{\varphi\}}$$

$$\frac{}{\{\varphi\} \text{skip} \{\varphi\}}$$

$$\frac{\{\varphi\} S_1 \{\theta\} \quad \{\theta\} S_2 \{\psi\}}{\{\varphi\} S_1; S_2 \{\psi\}}$$

$$\frac{\varphi' \Rightarrow \varphi \quad \{\varphi\} S \{\psi\} \quad \psi \Rightarrow \psi'}{\{\varphi'\} S \{\psi'\}}$$

$$\frac{\{\varphi \wedge b\} S_1 \{\psi\} \quad \{\varphi \wedge \neg b\} S_2 \{\psi\}}{\{\varphi\} \text{if } b \text{ then } S_1 \text{ else } S_2 \{\psi\}}$$

$$\frac{\{\varphi \wedge b\} S \{\varphi\}}{\{\varphi\} \text{while } b \text{ do } S \{\varphi \wedge \neg b\}}$$

Soundness

if $Th(\mathcal{L}) \vdash \{\varphi\} S \{\psi\}$ then $\models \{\varphi\} S \{\psi\}$

where $Th(\mathcal{L})$ is the \mathcal{L} -theory of \mathbf{D}

Completeness

If \mathcal{L} is expressive in \mathbf{D} for Stmt then:

if $\models \{\varphi\} S \{\psi\}$ then $Th(\mathcal{L}) \vdash \{\varphi\} S \{\psi\}$

While-programs with imperative expressions

$x \in \mathbf{Var} ::= \dots$

$E \in \mathbf{IExp} ::= x \mid f(E_1, \dots, E_n) \quad (\text{for each } f \in \Omega_n, n \in N)$
 $\mid E' \text{ after } S$

$B \in \mathbf{IBExp} ::= \text{true} \mid \text{false} \mid \neg B' \mid B_1 \wedge B_2 \mid p(E_1, \dots, E_n) \quad (\text{for each } p \in \Pi_n, n \in N)$
 $\mid B' \text{ after } S$

$S \in \mathbf{Stmt} ::= x := E \mid \text{skip} \mid S_1; S_2 \mid \text{if } B \text{ then } S_1 \text{ else } S_2 \mid \text{while } B \text{ do } S'$

Semantics

$\mathcal{E}_I: \mathbf{Exp} \rightarrow \mathbf{State} \rightarrow D \times \mathbf{State}$

$\mathcal{B}_I: \mathbf{BExp} \rightarrow \mathbf{State} \rightarrow \mathbf{B} \times \mathbf{State}$

$\mathcal{S}: \mathbf{Stmt} \rightarrow \mathbf{State} \rightarrow \mathbf{State}$

Expected semantic clauses omitted

Judgements

$$\{\varphi\} S \{\psi\}$$

Whenever computation $S \in \mathbf{Stmt}$ starts in a state satisfying φ and terminates, the final state satisfies $\psi \in \mathcal{L}$

$$\{\varphi\} E \{\lambda v:\mathbf{D} \cdot \psi\}$$

Whenever computation of $E \in \mathbf{IExp}$ starts in a state satisfying φ and terminates, the final state satisfies $\psi[v \mapsto d]$, where $d \in D$ is the value of E

$$\{\varphi\} B \{\lambda v:\mathbf{B} \cdot \psi\}$$

Whenever computation of $B \in \mathbf{IBExp}$ starts in a state satisfying φ and terminates, the final state satisfies $\psi[v \mapsto b]$, where $b \in \mathbf{B}$ is the value of B

Semantic satisfaction

$$\models \{\varphi\} S \{\psi\}$$

for $s \in \mathbf{State}$, if $\llbracket \varphi \rrbracket s = \mathbf{tt}$ and $\mathcal{S}[\![S]\!] s = s'$ then $\llbracket \psi \rrbracket s' = \mathbf{tt}$

$$\models \{\varphi\} E \{\lambda v:\mathbf{D} \cdot \psi\}$$

for $s \in \mathbf{State}$, if $\llbracket \varphi \rrbracket s = \mathbf{tt}$ and $\mathcal{E}_I[\![E]\!] s = \langle d, s' \rangle$ then $\llbracket \psi \rrbracket (s'[v \mapsto d]) = \mathbf{tt}$

$$\models \{\varphi\} B \{\lambda v:\mathbf{B} \cdot \psi\}$$

for $s \in \mathbf{State}$, if $\llbracket \varphi \rrbracket s = \mathbf{tt}$ and $\mathcal{B}_I[\![B]\!] s = \langle b, s' \rangle$ then $\llbracket \psi \rrbracket (s'[v \mapsto b]) = \mathbf{tt}$

Proof system

$$\{\varphi\} S \{\psi\}$$

$$\{\varphi\} E \{\lambda v:\mathbf{D} \cdot \psi\}$$

$$\{\varphi\} B \{\lambda v:\mathbf{B} \cdot \psi\}$$

$$\{\varphi\} S \{\psi\}$$
$$\frac{\{\varphi\} E \{\lambda v:\mathbf{D} \cdot \psi\}}{\{\varphi\} x := E \{\psi[v \mapsto x]\}}$$
$$\frac{}{\{\varphi\} \text{skip} \{\varphi\}}$$
$$\frac{\{\varphi\} S_1 \{\theta\} \quad \{\theta\} S_2 \{\psi\}}{\{\varphi\} S_1; S_2 \{\psi\}}$$
$$\frac{\varphi' \Rightarrow \varphi \quad \{\varphi\} S \{\psi\} \quad \psi \Rightarrow \psi'}{\{\varphi'\} S \{\psi'\}}$$
$$\frac{\{\varphi\} B \{\lambda v:\mathbf{B} \cdot \theta\} \quad \{\theta[v \mapsto \text{true}]\} S_1 \{\psi\} \quad \{\theta[v \mapsto \text{false}]\} S_2 \{\psi\}}{\{\varphi\} \text{if } B \text{ then } S_1 \text{ else } S_2 \{\psi\}}$$
$$\frac{\{\varphi\} B \{\lambda v:\mathbf{B} \cdot \psi\} \quad \{\psi[v \mapsto \text{true}]\} S \{\varphi\}}{\{\varphi\} \text{while } B \text{ do } S \{\psi[v \mapsto \text{false}]\}}$$

$$\{\varphi\} E \{\lambda v:\mathbf{D} \cdot \psi\}$$

$$\frac{\varphi' \Rightarrow \varphi \quad \{\varphi\} E \{\lambda v:\mathbf{D} \cdot \psi\} \quad \psi \Rightarrow \psi'}{\{\varphi'\} E \{\lambda v:\mathbf{D} \cdot \psi'\}}$$

$$\frac{\{\varphi\} S \{\theta\} \quad \{\theta\} E \{\lambda v:\mathbf{D} \cdot \psi\}}{\{\varphi\} E \text{ after } S \{\lambda v:\mathbf{D} \cdot \psi\}}$$

$$\frac{}{\{\psi[v \mapsto x]\} x \{\lambda v:\mathbf{D} \cdot \psi\}}$$

$$\frac{}{\{\psi[v \mapsto f()]\} f() \{\lambda v:\mathbf{D} \cdot \psi\}}$$

$$\frac{\begin{array}{c} \{\varphi\} E_1 \{\lambda v:\mathbf{D} \cdot \theta_1\} \\ \{\theta_1[v \mapsto v_1]\} E_2 \{\lambda v:\mathbf{D} \cdot \theta_2\} \quad \dots \quad \{\theta_{n-1}[v \mapsto v_{n-1}]\} E_n \{\lambda v:\mathbf{D} \cdot \theta_n\} \\ \theta_n[v \mapsto v_n] \Rightarrow \psi[v \mapsto f(v_1, \dots, v_n)] \end{array}}{\{\varphi\} f(E_1, \dots, E_n) \{\lambda v:\mathbf{D} \cdot \psi\}}$$

$$\{\varphi\} B \{\lambda v:\mathbf{B} \cdot \psi\}$$

$$\frac{\varphi' \Rightarrow \varphi \quad \{\varphi\} B \{\lambda v:\mathbf{B} \cdot \psi\} \quad \psi \Rightarrow \psi'}{\{\varphi'\} B \{\lambda v:\mathbf{B} \cdot \psi'\}}$$

$$\frac{\{\varphi\} S \{\theta\} \quad \{\theta\} B \{\lambda v:\mathbf{B} \cdot \psi\}}{\{\varphi\} B \text{ after } S \{\lambda v:\mathbf{B} \cdot \psi\}}$$

$$\frac{\{\varphi\} B \{\lambda v:\mathbf{B} \cdot \psi\}}{\{\varphi\} \neg B \{\lambda v:\mathbf{B} \cdot \psi[v \mapsto \neg v]\}}$$

$$\frac{}{\{\psi[v \mapsto p()]\} p() \{\lambda v:\mathbf{B} \cdot \psi\}}$$

...

$$\frac{\begin{array}{c} \{\varphi\} E_1 \{\lambda v:\mathbf{D} \cdot \theta_1\} \\ \{\theta_1[v \mapsto v_1]\} E_2 \{\lambda v:\mathbf{D} \cdot \theta_2\} \quad \dots \quad \{\theta_{n-1}[v \mapsto v_{n-1}]\} E_n \{\lambda v:\mathbf{D} \cdot \theta_n\} \\ \theta_n[v \mapsto v_n] \Rightarrow \psi[v \mapsto p(v_1, \dots, v_n)] \end{array}}{\{\varphi\} p(E_1, \dots, E_n) \{\lambda v:\mathbf{B} \cdot \psi\}}$$

Soundness

	if	$Th(\mathcal{L}) \vdash \{\varphi\} S \{\psi\}$	then	$\models \{\varphi\} S \{\psi\}$
if		$Th(\mathcal{L}) \vdash \{\varphi\} E \{\lambda v:\mathbf{D} \cdot \psi\}$	then	$\models \{\varphi\} E \{\lambda v:\mathbf{D} \cdot \psi\}$
if		$Th(\mathcal{L}) \vdash \{\varphi\} B \{\lambda v:\mathbf{B} \cdot \psi\}$	then	$\models \{\varphi\} B \{\lambda v:\mathbf{B} \cdot \psi\}$

Completeness

If \mathcal{L} is expressive in \mathbf{D} for Stmt then:

	if	$\models \{\varphi\} S \{\psi\}$	then	$Th(\mathcal{L}) \vdash \{\varphi\} S \{\psi\}$
if		$\models \{\varphi\} E \{\lambda v:\mathbf{D} \cdot \psi\}$	then	$Th(\mathcal{L}) \vdash \{\varphi\} E \{\lambda v:\mathbf{D} \cdot \psi\}$
if		$\models \{\varphi\} B \{\lambda v:\mathbf{B} \cdot \psi\}$	then	$Th(\mathcal{L}) \vdash \{\varphi\} B \{\lambda v:\mathbf{B} \cdot \psi\}$

Further comments

- other imperative constructs (in particular: recursion)
- backward vs. forward reasoning style
- wp-reasoning, binary conditions, dynamic/algorithmic logic, ...
- exact assumption about the underlying logic \mathcal{L}
- exact assumptions on the built-in data type, and on the use of new variables
- an institution-independent version :-)

is this of any interest?