

Preliminaries

On-the-fly Strategy Synthesis for Event-Clock Linear Temporal Logic on Timed Games

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Gilles Geeraerts, Jean-François Raskin, Julien Reichert,
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Realizability problem in a real-time setting

Realizability problem in a real-time setting

Environment

Realizability problem in a real-time setting

Environment

? System ?

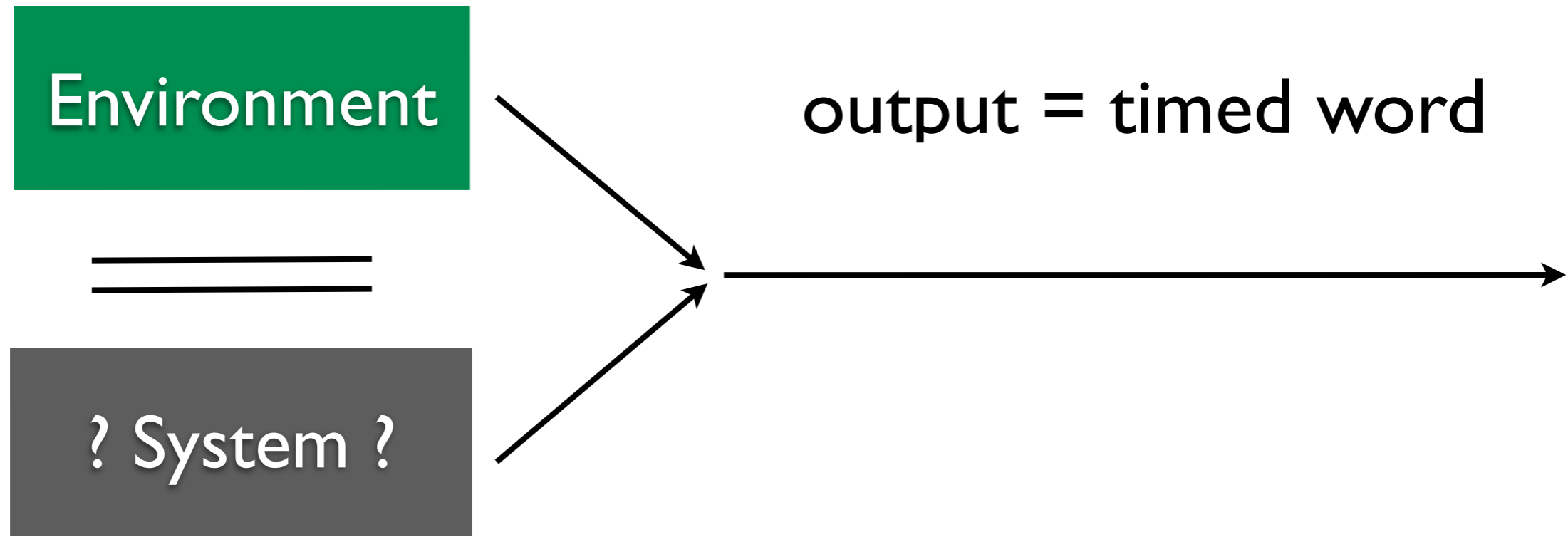
Realizability problem in a real-time setting

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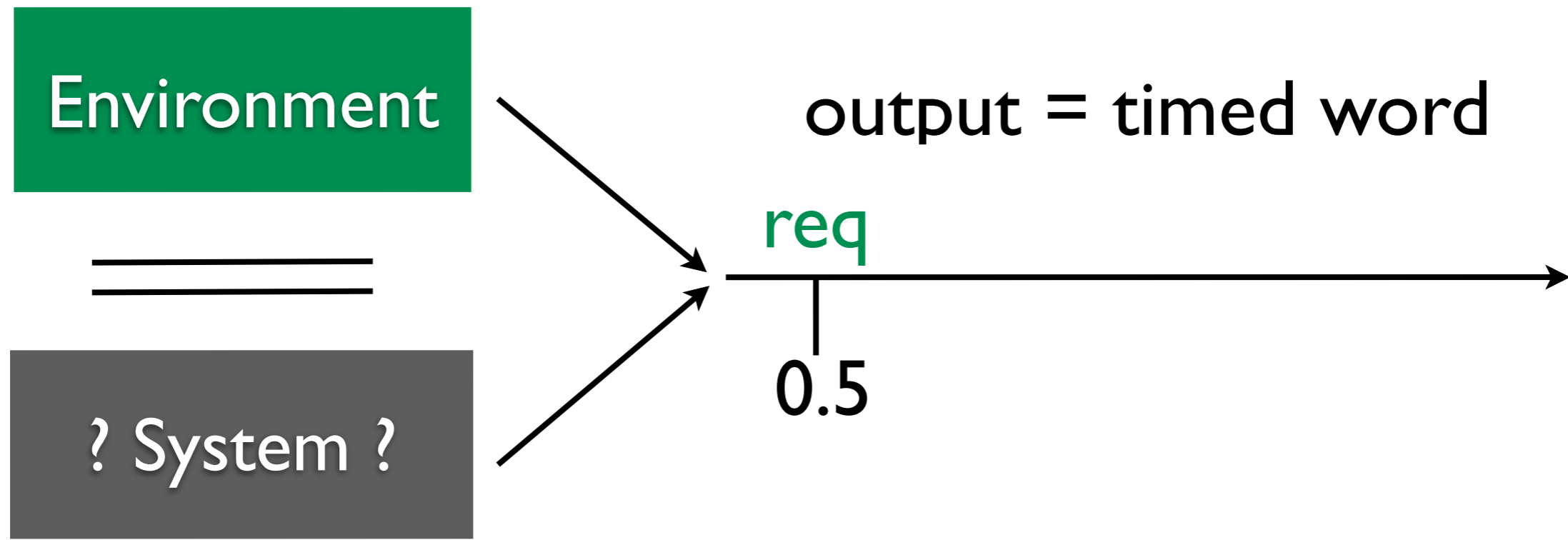


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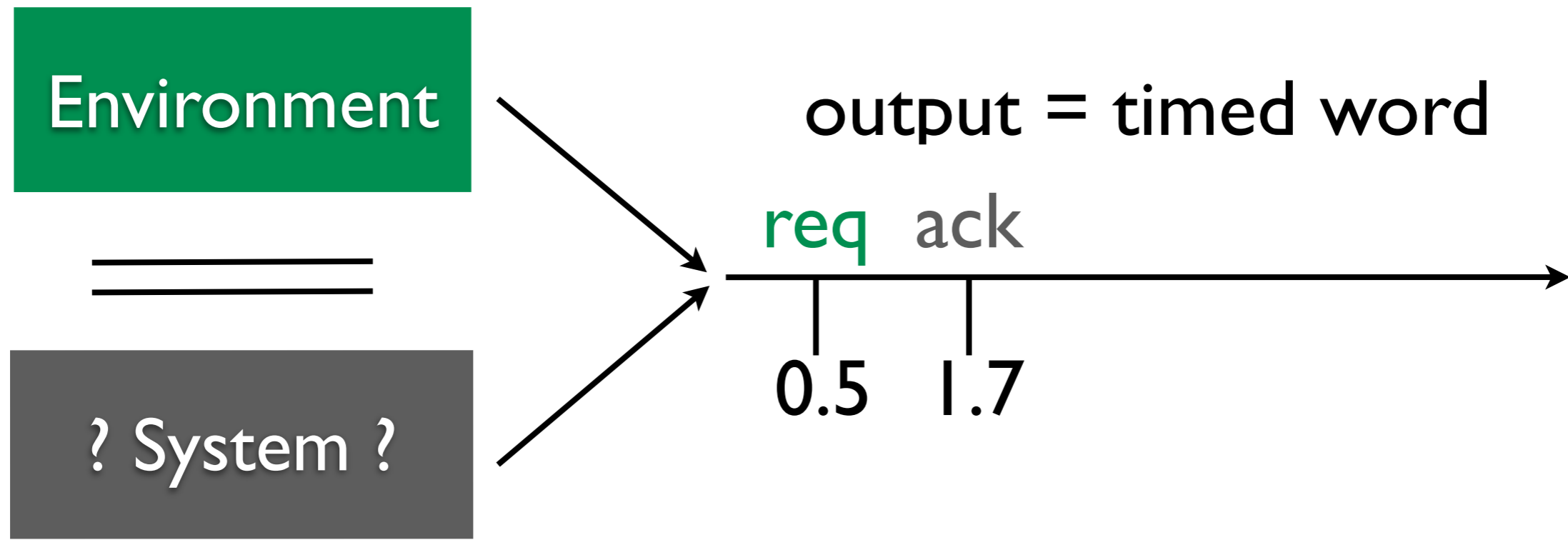
Realizability problem in a real-time setting



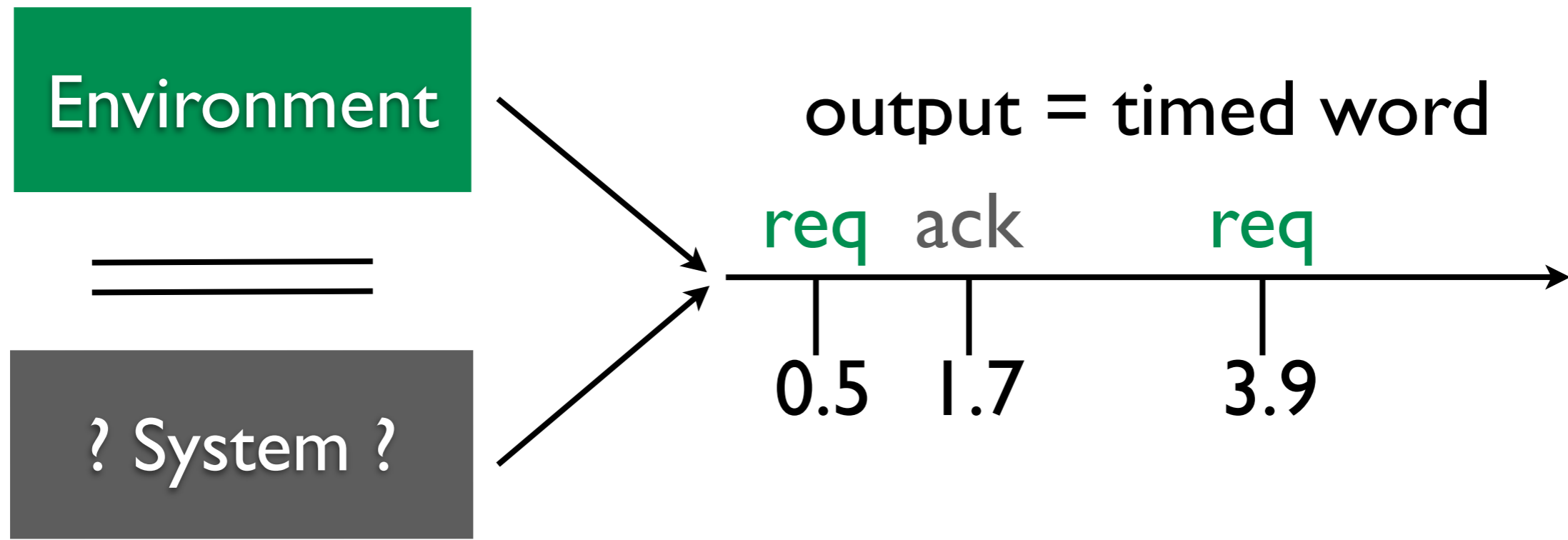
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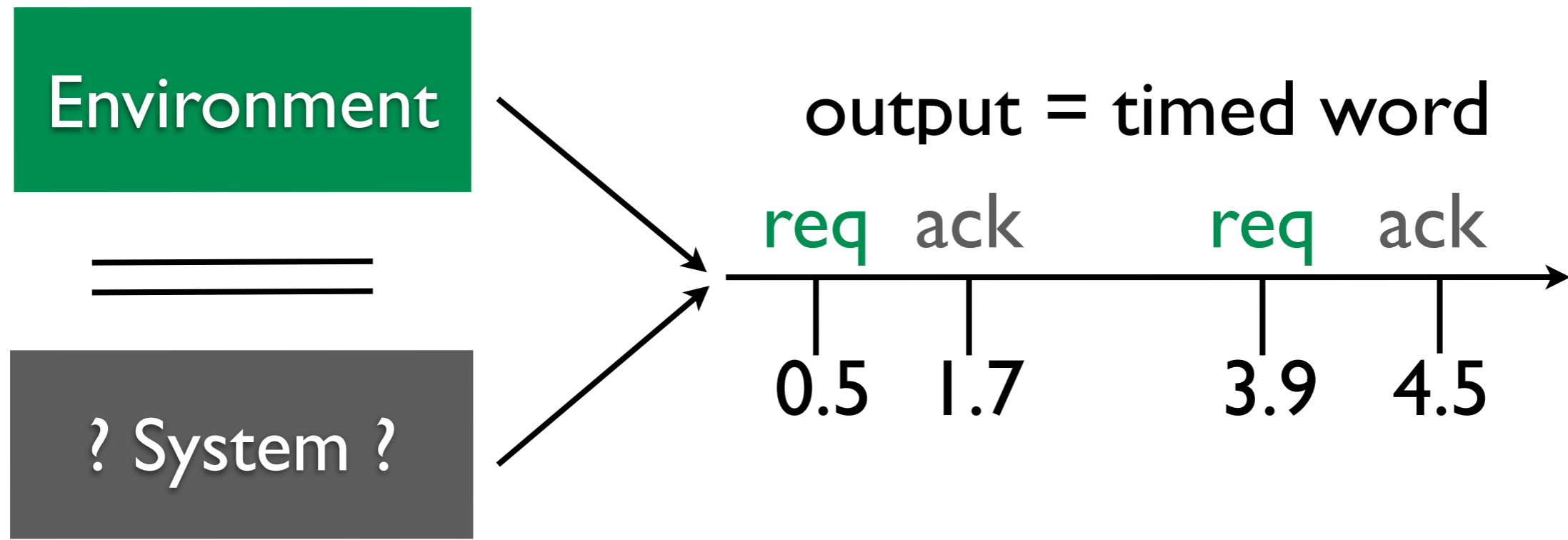
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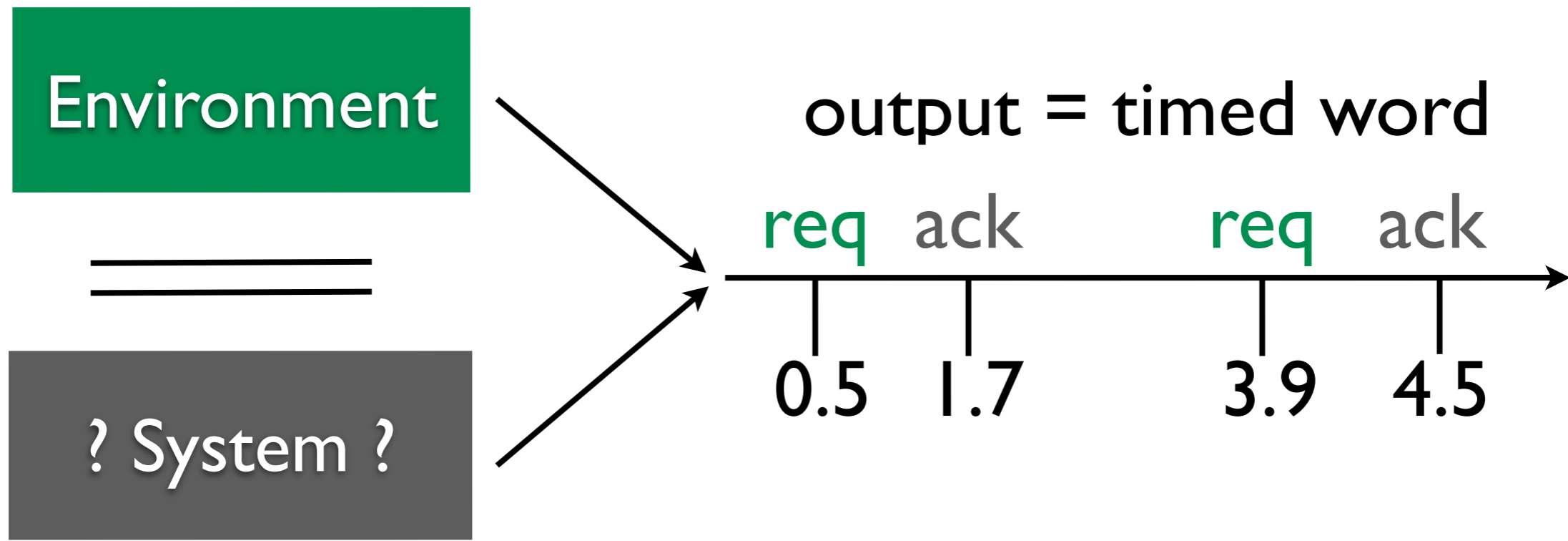
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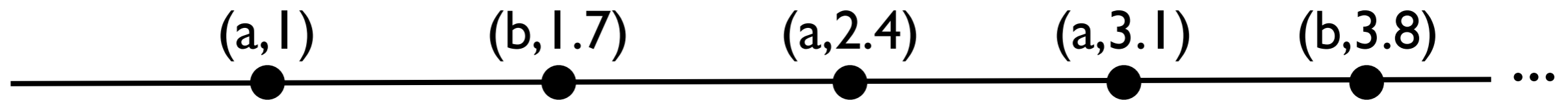


Problem

Given a spec Φ , does there exist a way for the System to choose its signals along time so that, **no matter how** the environment chooses its signals, the resulting execution satisfies the formula Φ ?

Timed words

Timed word on $\Sigma=\{a,b\}$:



= infinite sequence of elements in $\Sigma \times \mathbb{R}^{\geq 0}$

$(\sigma_0, t_0) (\sigma_1, t_1) (\sigma_2, t_2) \dots (\sigma_n, t_n) \dots$

such that $\sigma_i \in \Sigma$ and $t_i \leq t_{i+1}$, for all $i \in \mathbb{N}$.

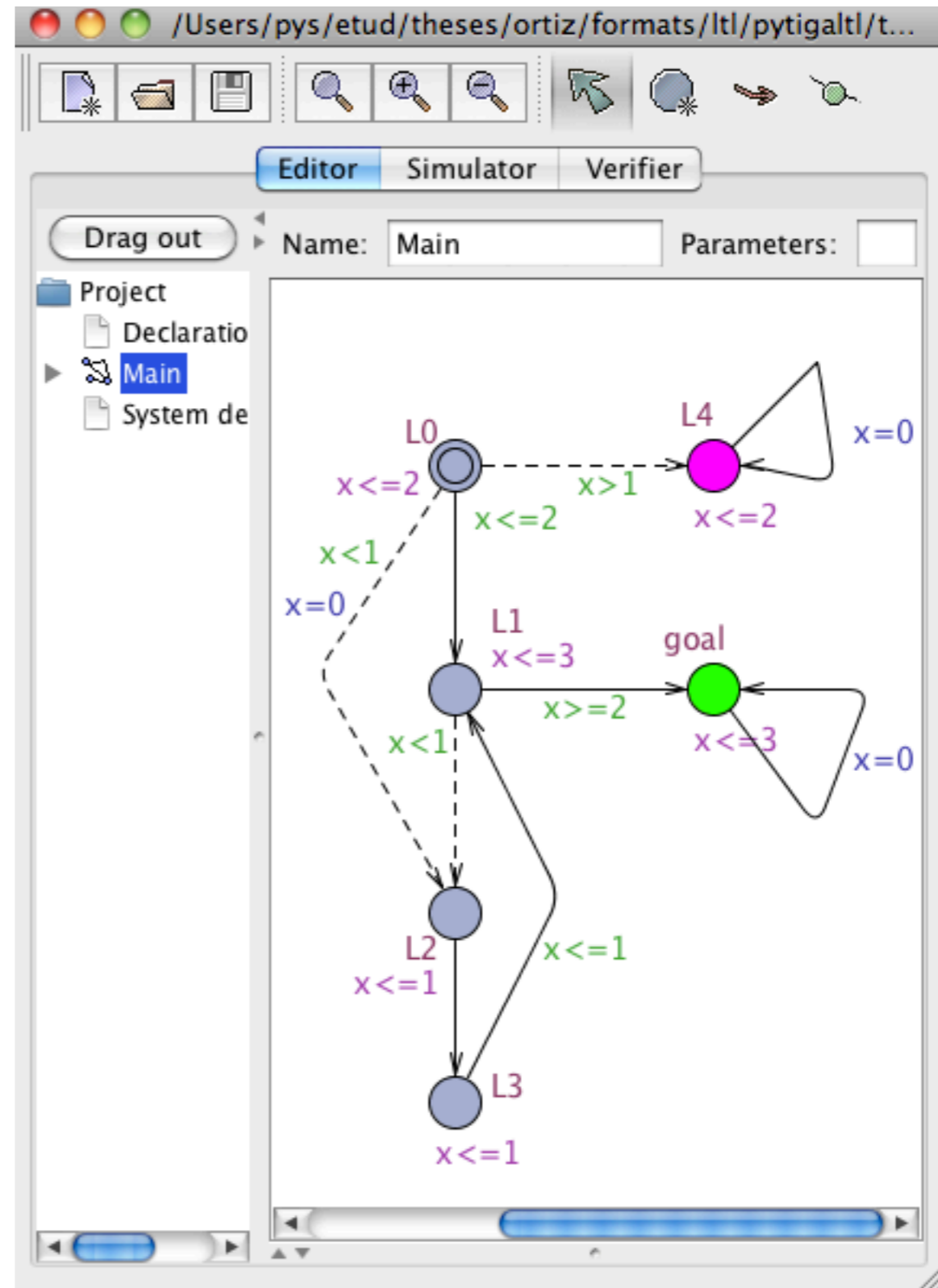
Timed Games

± Timed Automaton

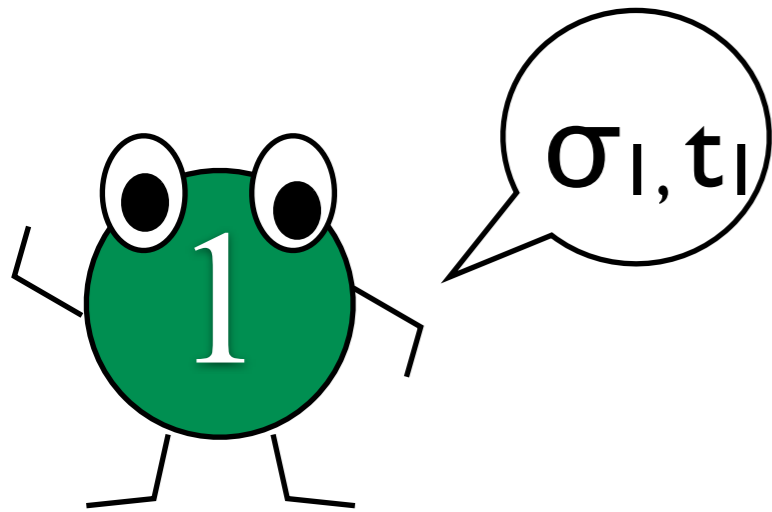
2 players: Sys and Env →

Own transitions

Both players can agree to wait (as long as the location invariant stays true)



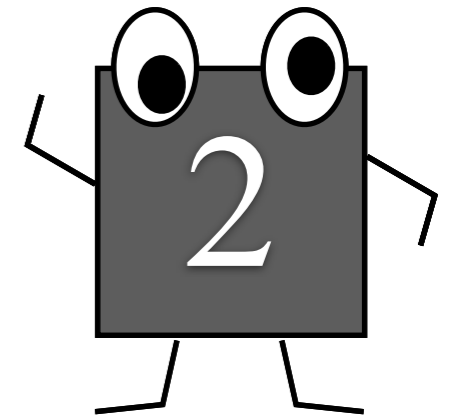
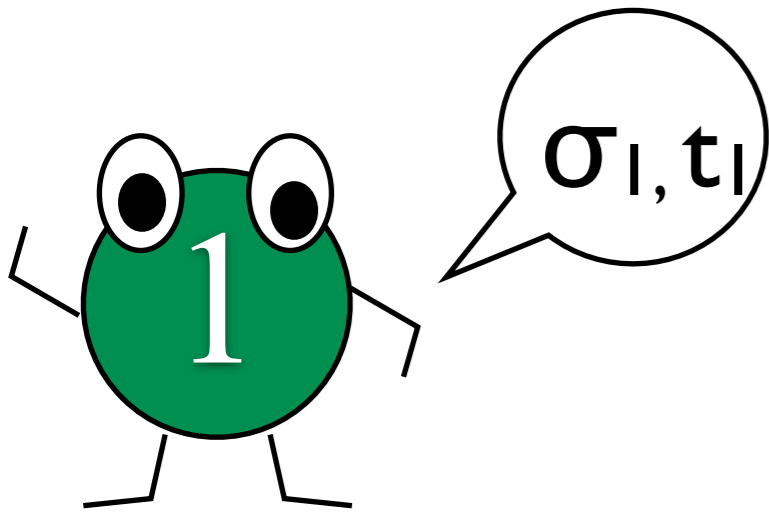
One round of the game



Player 1 chooses an action and a delay t_1

$(\sigma^1, \tau^1), \dots, (\sigma^n, \tau^n),$

One round of the game

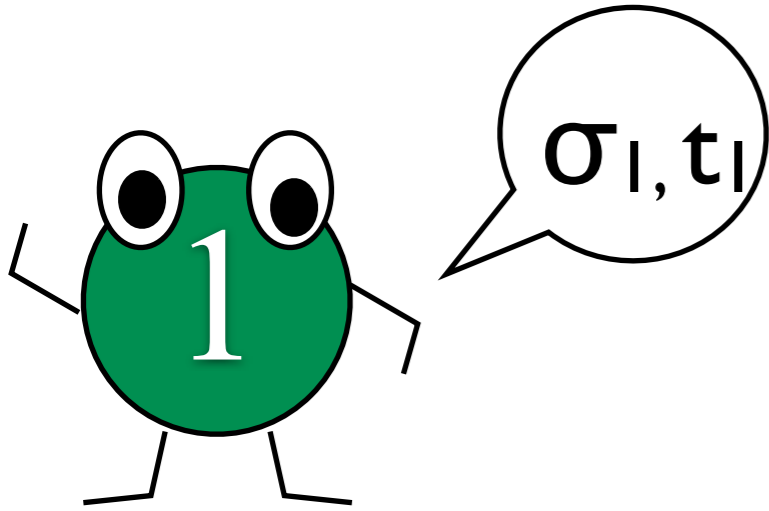


Player 1 chooses an action and a delay t_1

Player 2 may let Player 1 play

$(\sigma^1, \tau^1), \dots, (\sigma^n, \tau^n),$

One round of the game



Player 1 chooses an action and a delay t_1

Player 2 may let Player 1 play

$(\sigma^1, \tau^1), \dots, (\sigma^n, \tau^n), (\sigma_1, \tau^n + t_1)$

One round of the game



Player 1 chooses an action and a delay t_1

or chooses an action and a delay t_2 ,
 $t_2 \leq t_1$

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One round of the game



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Timed strategies

- Player 1's **strategies**: $\lambda_1: (\Sigma \times \mathbb{R}^{\geq 0})^* \rightarrow (\Sigma_1 \times \mathbb{R}^{\geq 0})$

$$\text{ex: } \lambda_1((a,0.6),(b,0.9))=(a,0.5)$$

then **either** Player 2 let Player 1 play, and we obtain:

$$(a,0.6),(b,0.9)(a,1.4)$$

or it overtakes Player 1, for example by playing (b,0.3), and we get

$$(a,0.6),(b,0.9)(b,1.2)$$

➤➤ λ_1 is winning in $\langle \Sigma_1, \Sigma_2, \mathbf{Win} \rangle$ if $\text{Outcome}(\lambda_1) \subseteq \mathbf{Win}$

Event-Clock Logic (ECL)

$\varphi \in \text{ECL} ::= a \mid \neg\varphi \mid \varphi \vee \varphi \mid \varphi \mathcal{S} \varphi \mid \varphi \mathcal{U} \varphi \mid \triangleleft_I \varphi \mid \triangleright_I \varphi$

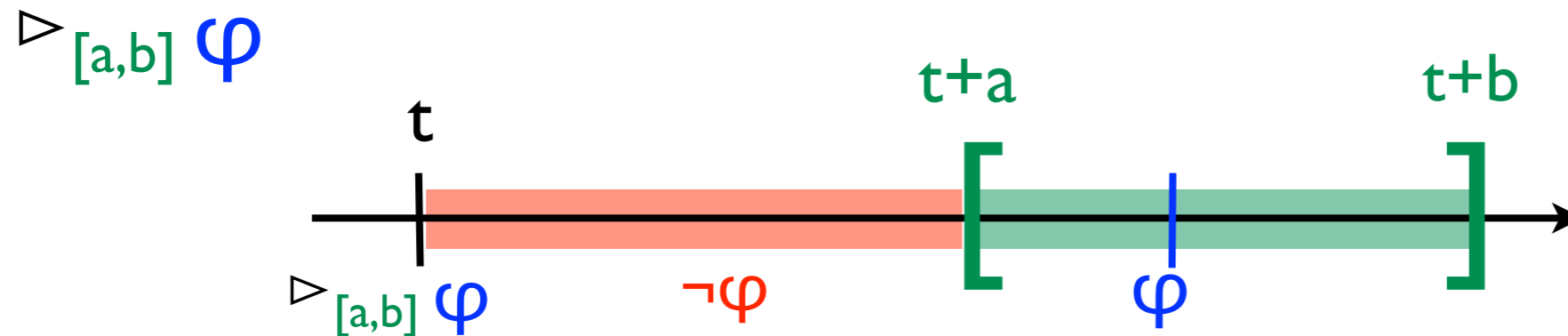
with I an interval of $\mathbb{R}^{\geq 0}$ with integer bounds

$\triangleright_{[a,b]} \varphi$

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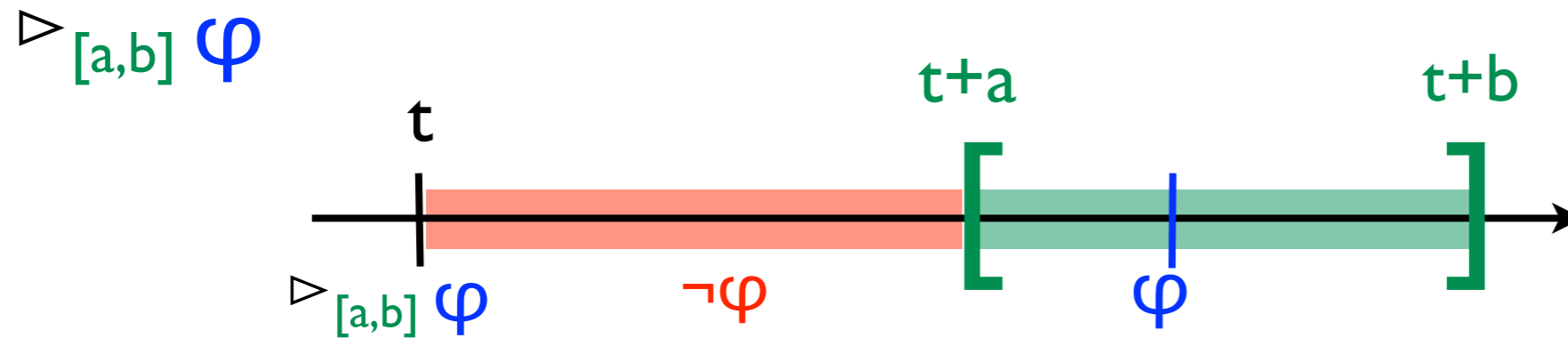
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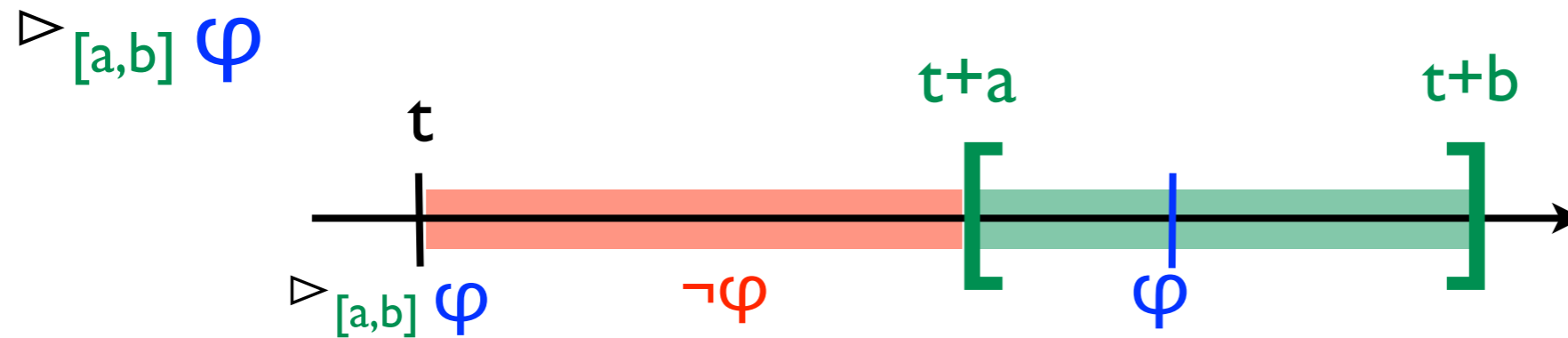


Remark: it is different from:

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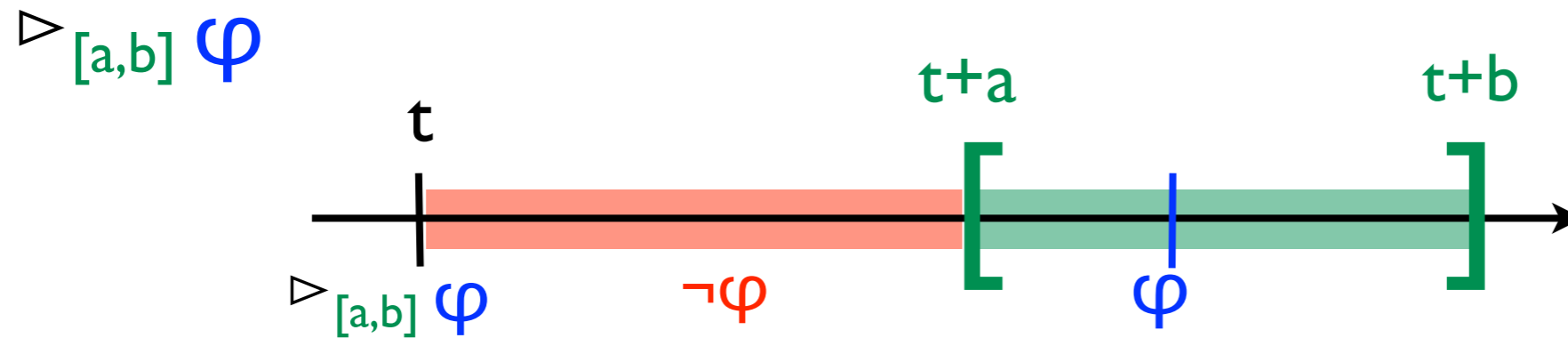
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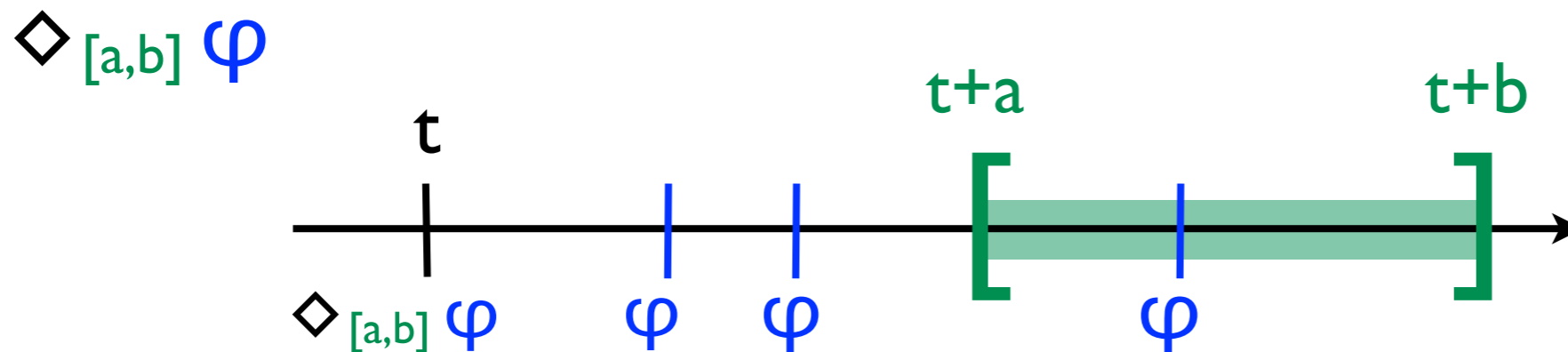
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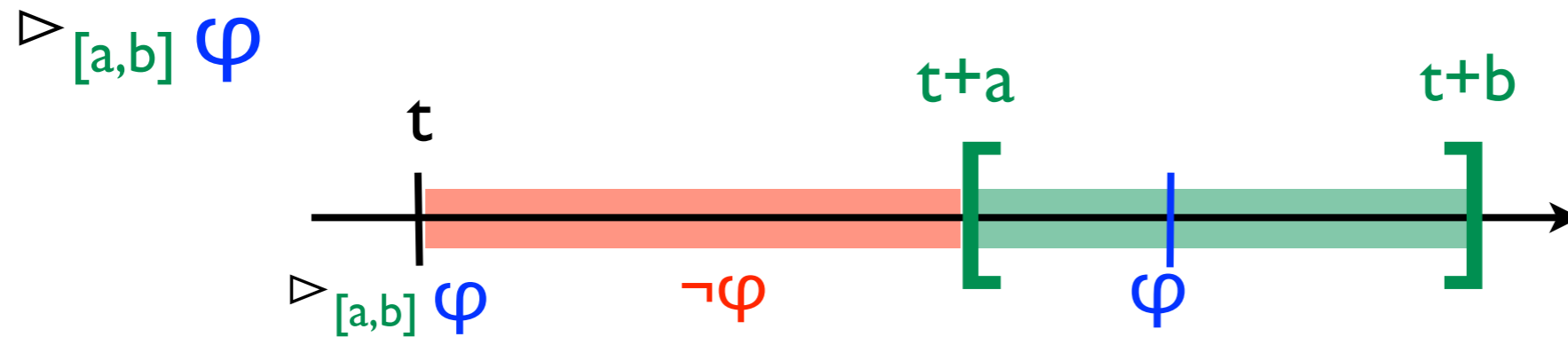
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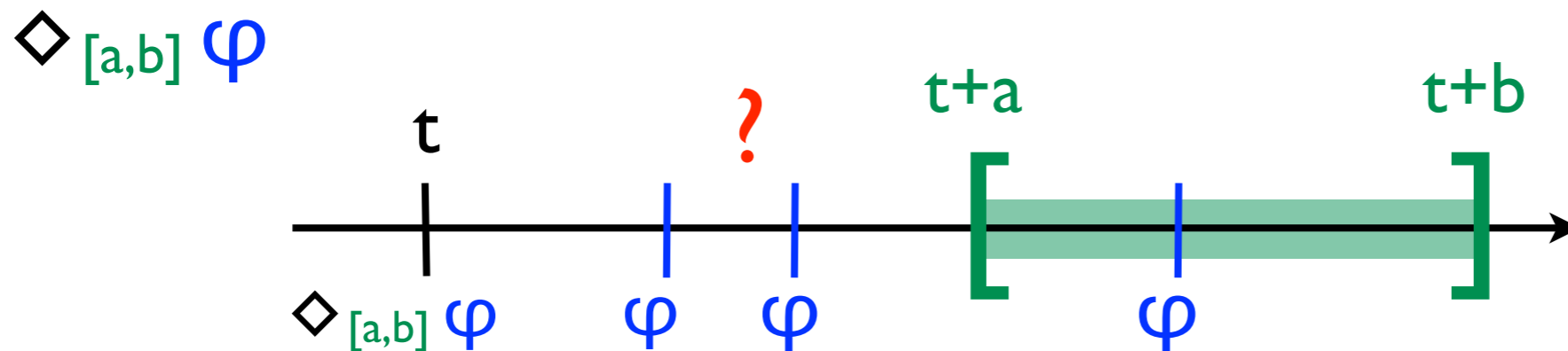
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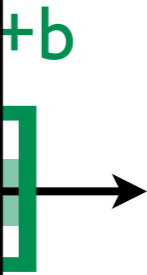
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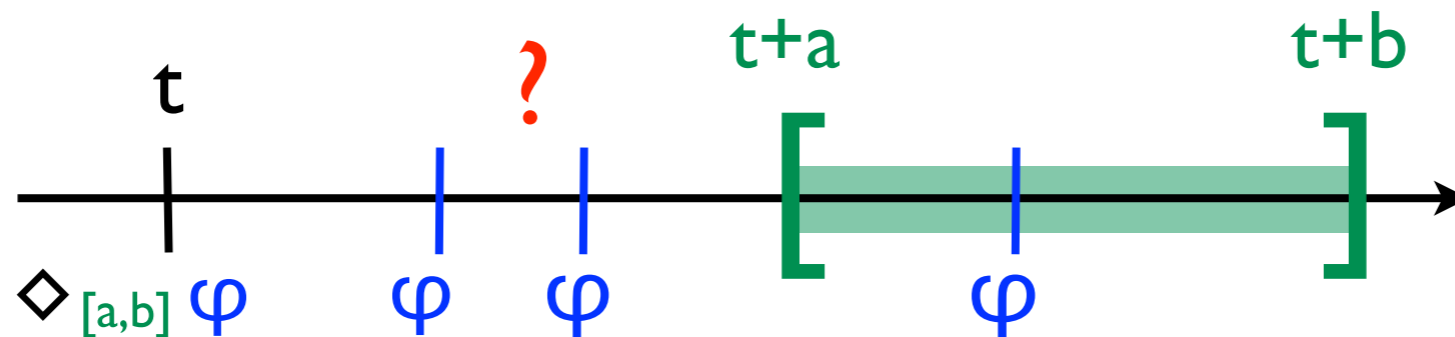
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We consider timed games of the form $\langle \Sigma_1, \Sigma_2, \llbracket \varphi \rrbracket \rangle$ where φ is an ECL formula



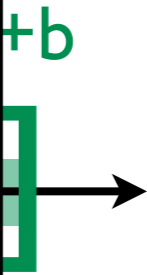
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Event-Clock Logic (ECL)

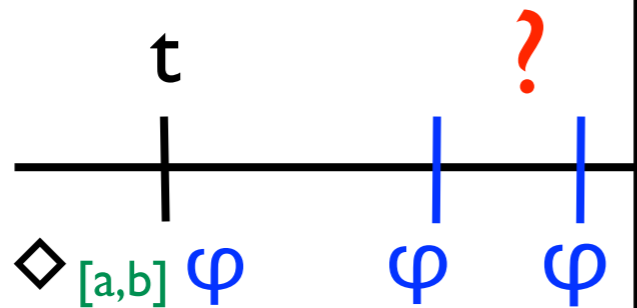
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We consider timed games of the form $\langle \Sigma_1, \Sigma_2, [\varphi] \rangle$ where φ is an ECL formula



This problem is called ECL «realizability»

$$\diamond_{[a,b]} \varphi$$



Why ECL?

- Satisfiability of MTL **undecidable** on infinite words.
⇒ Realizability is thus **undecidable** too !
- ECL is an interesting subcase of MITL (equivalent to $\text{MITL}_{0,\infty}$).

Results

Undecidability of ECL realizability

Theorem: ECL realizability is undecidable

- Idea of the proof: encode computations of lossy three counters machines into timed words
- Build a game s.t. Player I has a winning strategy iff the machine admits an infinite bounded run
- One has to use the interaction of the Players to check that the encoding is correct.

LTL \triangleleft realizability is decidable

$\varphi \in \text{ECL} ::= a \mid \neg\varphi \mid \varphi \vee \varphi \mid \varphi \mathcal{S} \varphi \mid \varphi \mathcal{U} \varphi \mid \triangleleft_I \varphi \mid \triangleright_I \varphi$

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The real-time modality can «speak»
about past events only

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- **Theorem:** The realizability problem for LTL \triangleleft is 2EXPTIME-complete

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- **Theorem:** The realizability problem for LTL \triangleleft is 2EXPTIME-complete
- **Idea:** from ψ , build a deterministic timed automaton with parity condition

LTL \triangleleft realizability is decidable

Determinization of Büchi automata
is already hard in practice !

$\varphi \mid \triangleleft_I \varphi \mid \triangleright_I \varphi$

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LTL_◁ realizability is decidable

Determinization of Büchi automata
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$\varphi \mid \triangleleft_I \varphi \mid \triangleright_I \varphi$
 $\psi \mid \triangleleft_I a$

Can we find «Safraless» procedures
that avoid Safra's determinization ?

- **Theorem**
LTL_◁ is 2EX

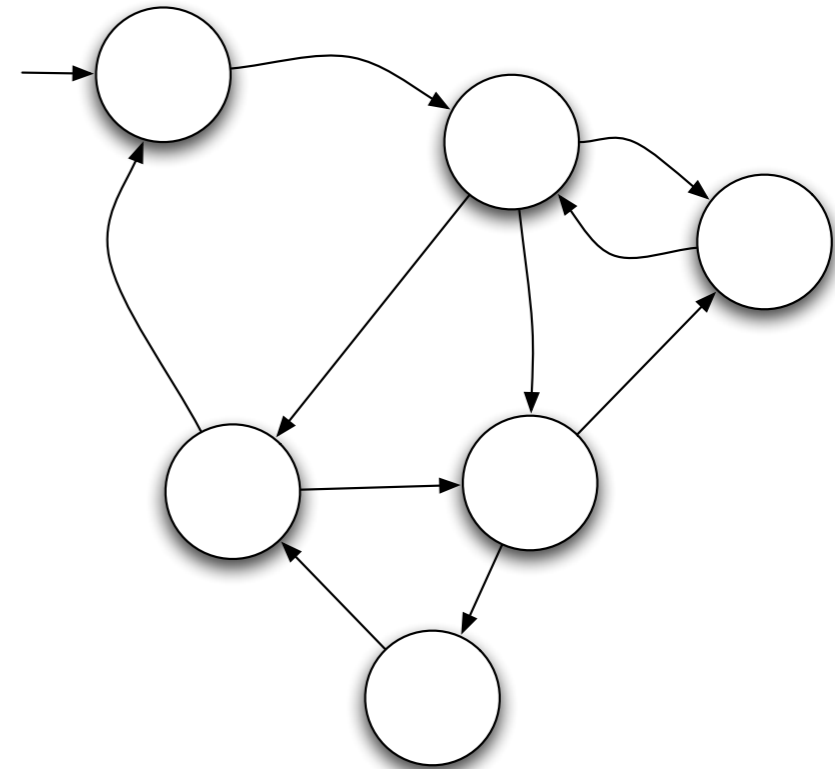
- **Idea:** from ψ , build a **deterministic** timed automaton with parity condition

Safraless procedures

- Safraless realizability/synthesis (untimed setting):
 - ★ Rank construction [KupfermanVardi05]:
LTL \rightarrow UcoBW \rightarrow ABT \rightarrow NBT \rightarrow Büchi game
 - ★ K-co-Büchi condition:
[ScheweFinkbeiner07] application to distributed synthesis,
[FiliotJinRaskin09] application to LTL synthesis.
LTL \rightarrow UcoBW \rightarrow UKcoBW \rightarrow Safety game

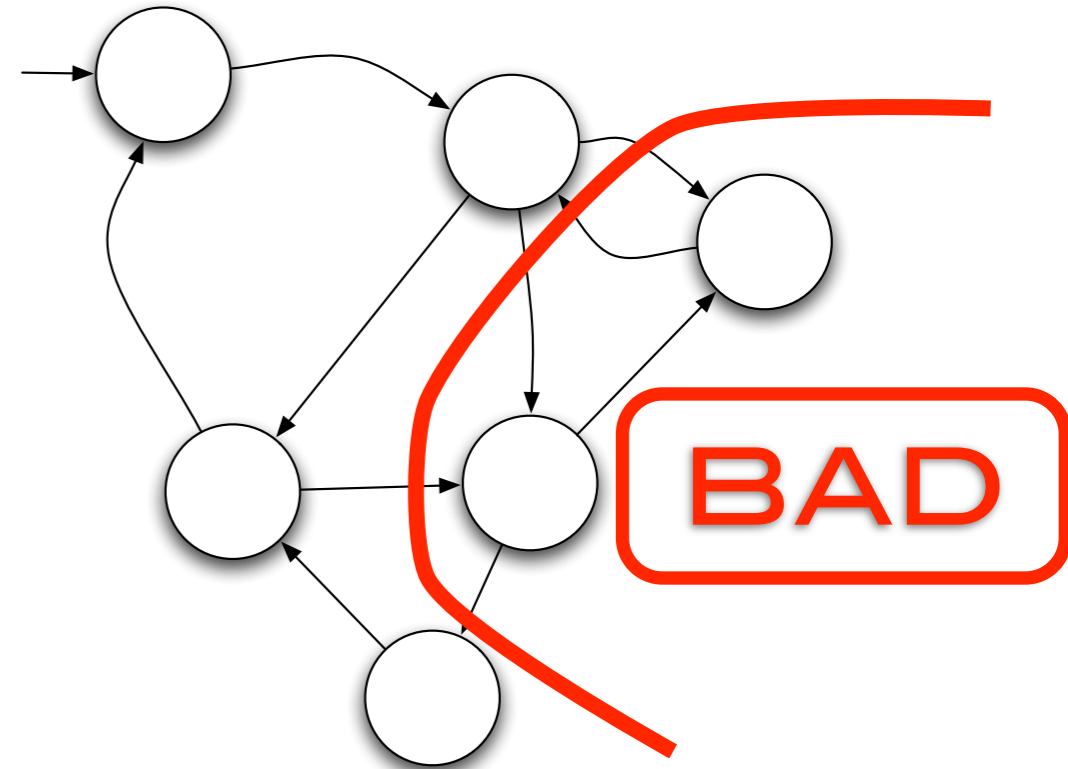
Idea of procedure

- **Reduce** the realizability problem to a **safety (timed) game**
- Game played on a **graph**
- Goal: **avoid** bad states
- Not a Büchi condition: **avoid Safra !**
- Allows **incremental procedure**
- Tools and algorithms exist to solve safety (timed) games
 - e.g.: **UppAal TiGa**



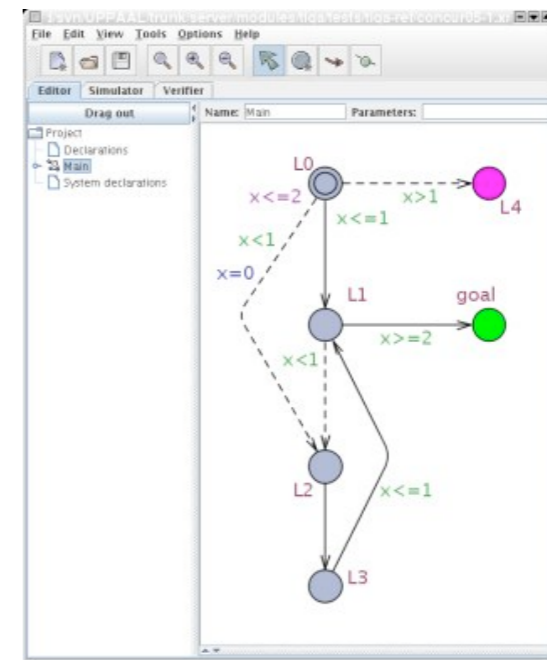
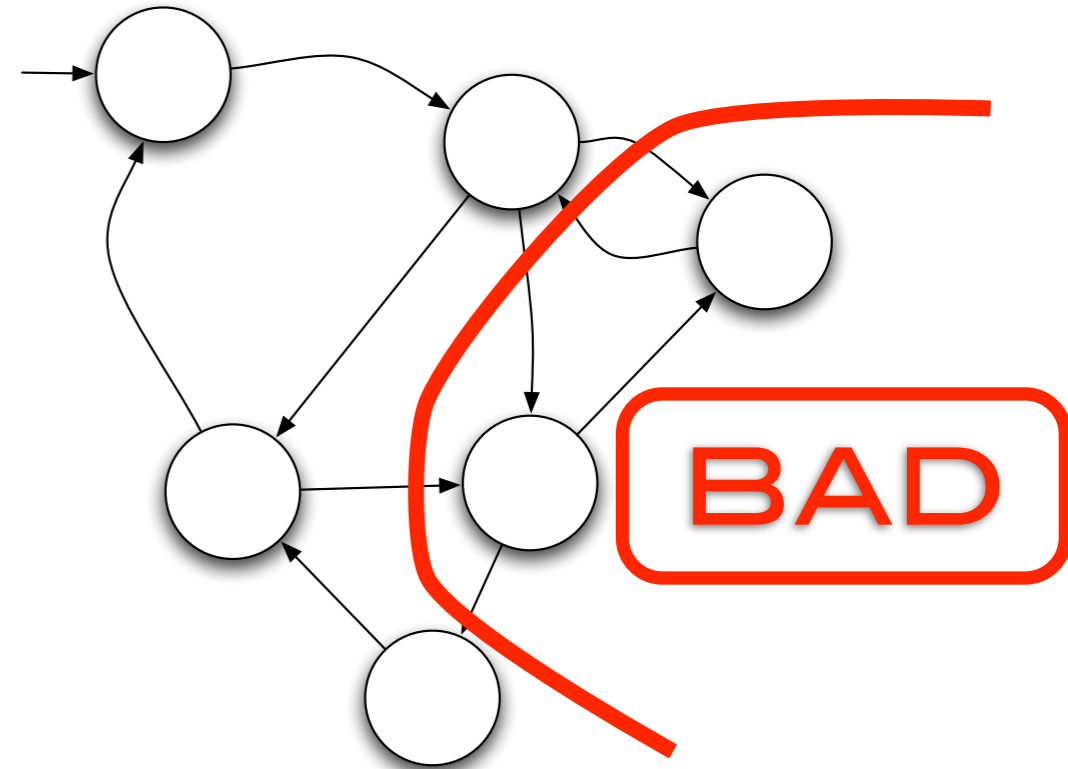
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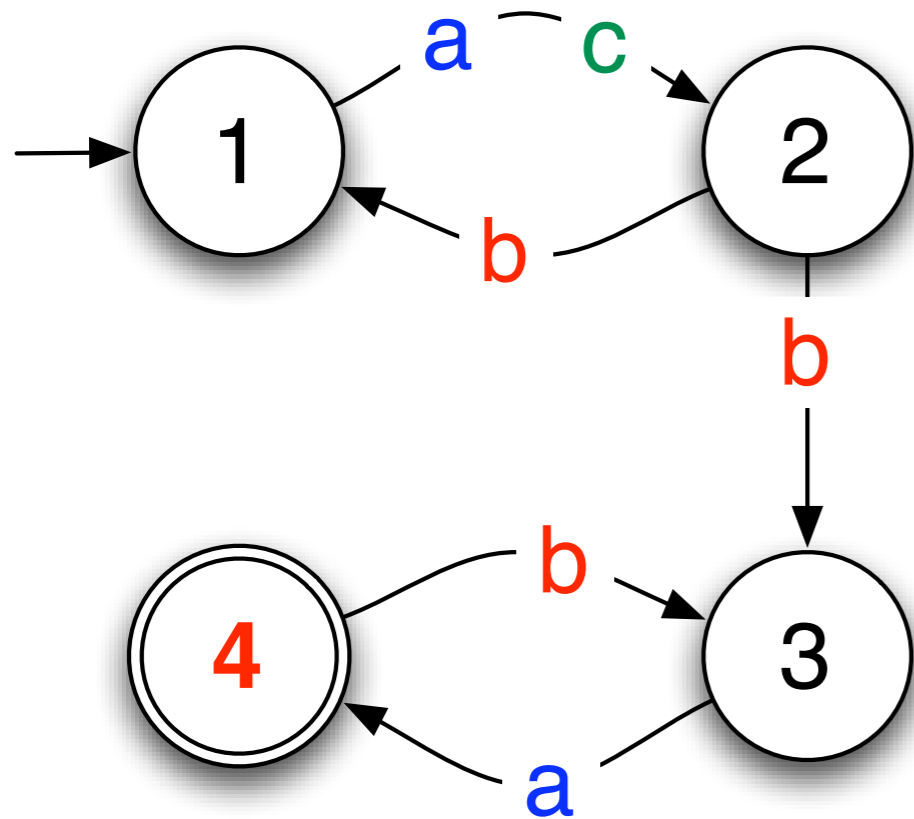


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Universal coBüchi **Word** Automata



Σ^ω

a

b

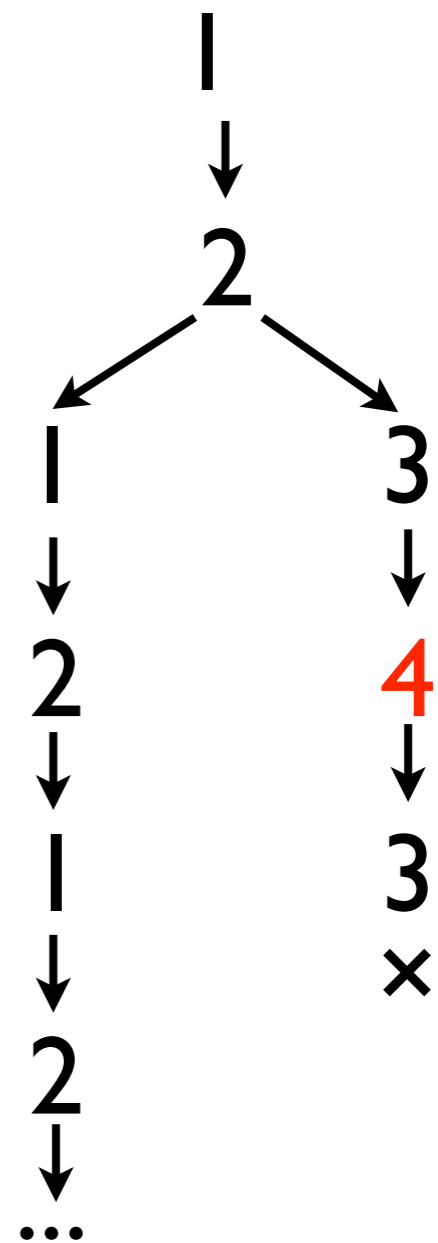
a

b

c

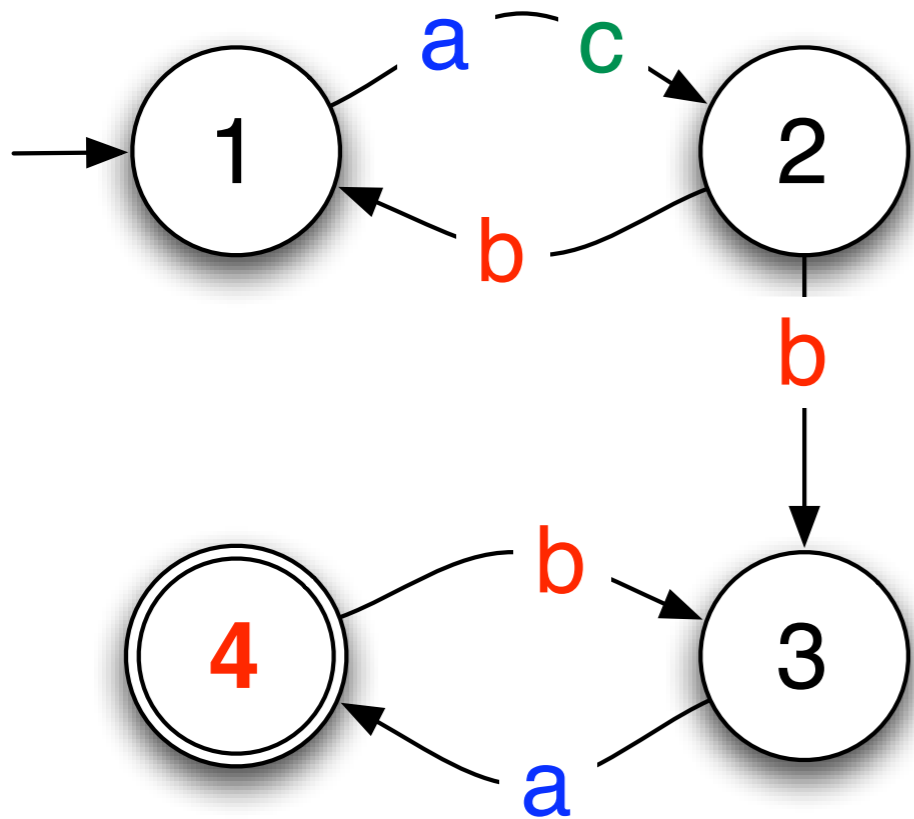
...

Run



$w \in \mathbf{LU}_{\mathbf{coB}}(A)$
 iff
all runs of A on w visit
finitely many times α .

Universal KcoBüchi **Word** Automata



Σ^ω

a

b

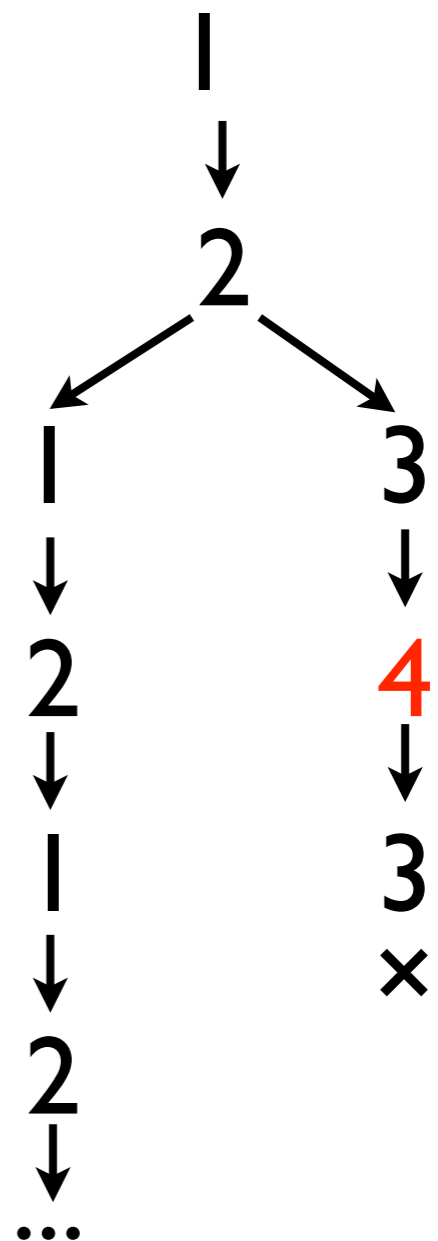
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...

Run

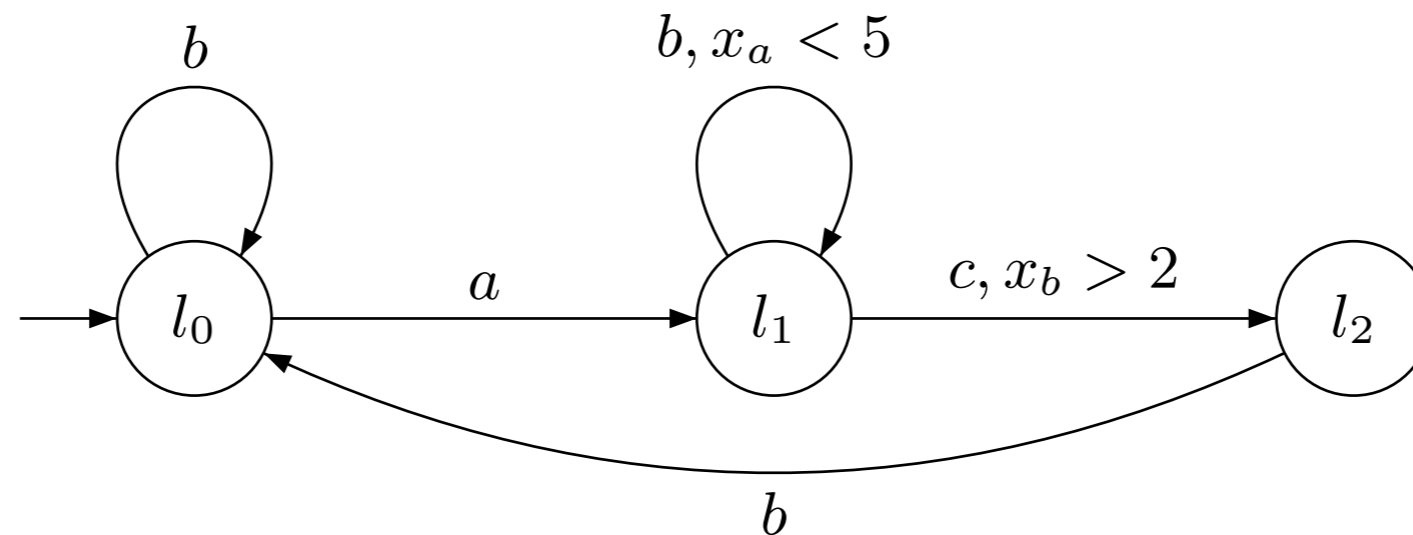


$w \in \text{LUKcoB}(A)$

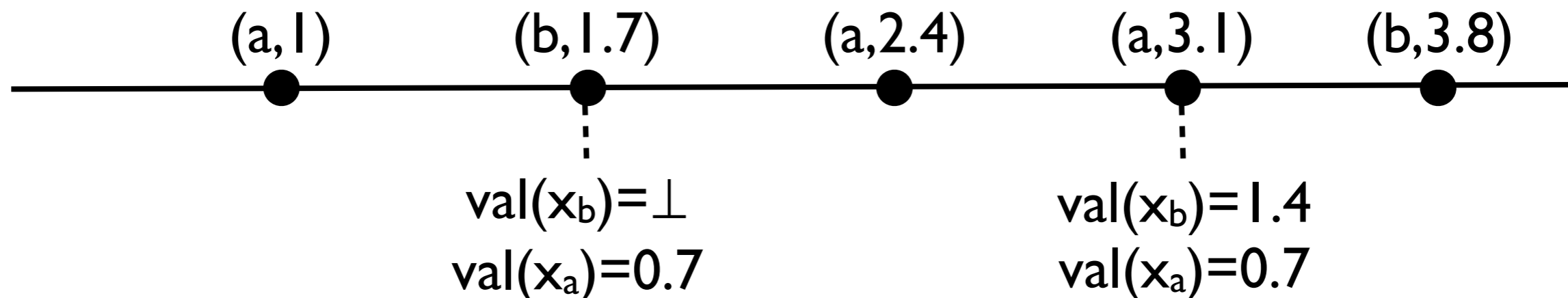
iff

all runs of A on w visit
at most K times α .

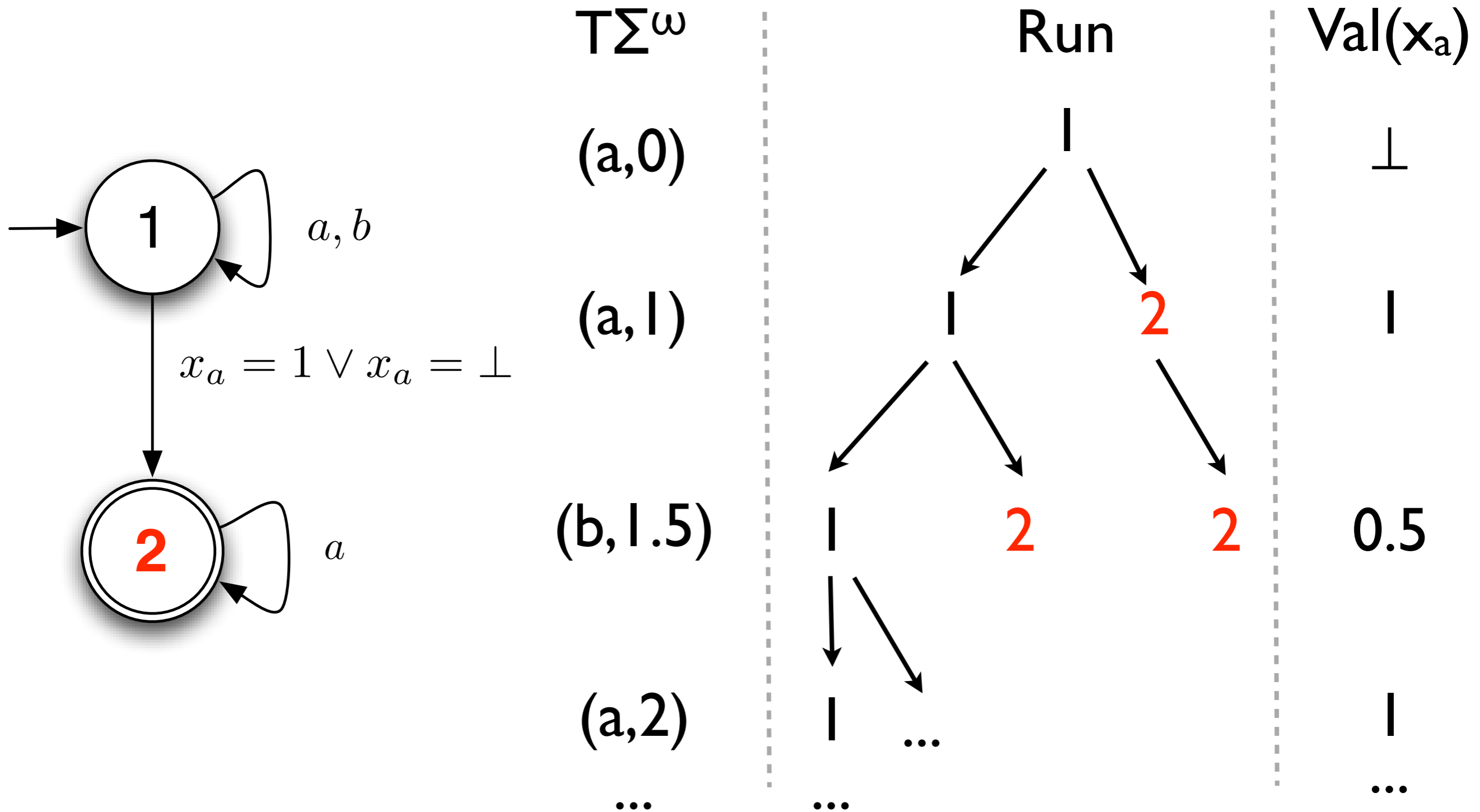
Event-recording automata



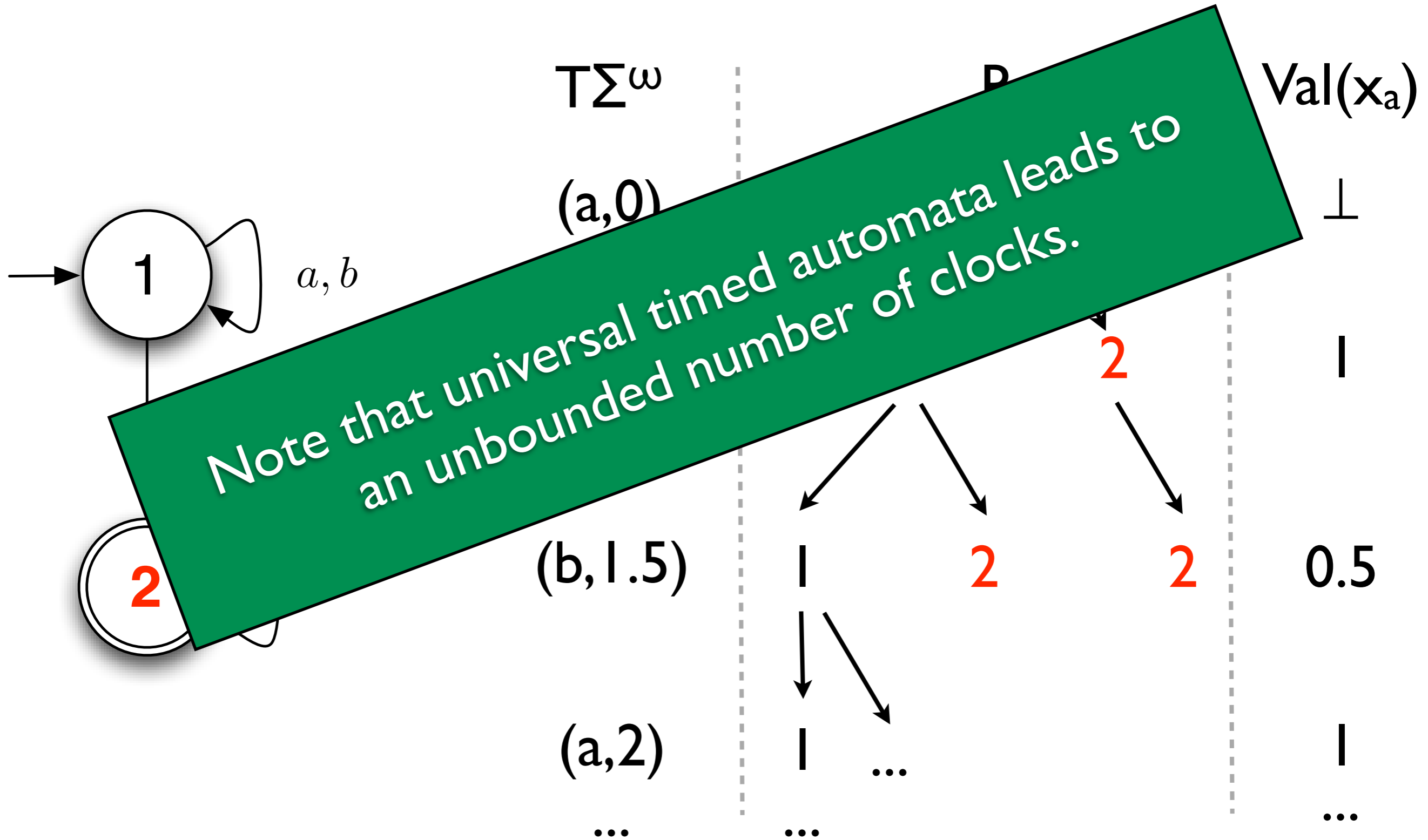
Clocks are **not** reset and are associated to events: $\{ x_\sigma \mid \sigma \in \Sigma \}$
 Each clock monitors the last occurrence of the associated letter
 Values of event-clocks are **input determined**:



Universal ERA with coBüchi a. c.



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Back to LTL_{\triangleleft} realizability

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Theorem: From φ in LTL_{\triangleleft} , one can build a
Universal co-Büchi ERA A_{φ}
such that $L_{UcoB}(A_{\varphi}) = \llbracket \varphi \rrbracket$

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$\langle \Sigma_1, \Sigma_2, \llbracket \varphi \rrbracket \rangle$ becomes $\langle \Sigma_1, \Sigma_2, L_{UcoB}(A_{\varphi}) \rangle$

Back to LTL_{\triangleleft} realizability

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We are now playing the game on A_{φ}

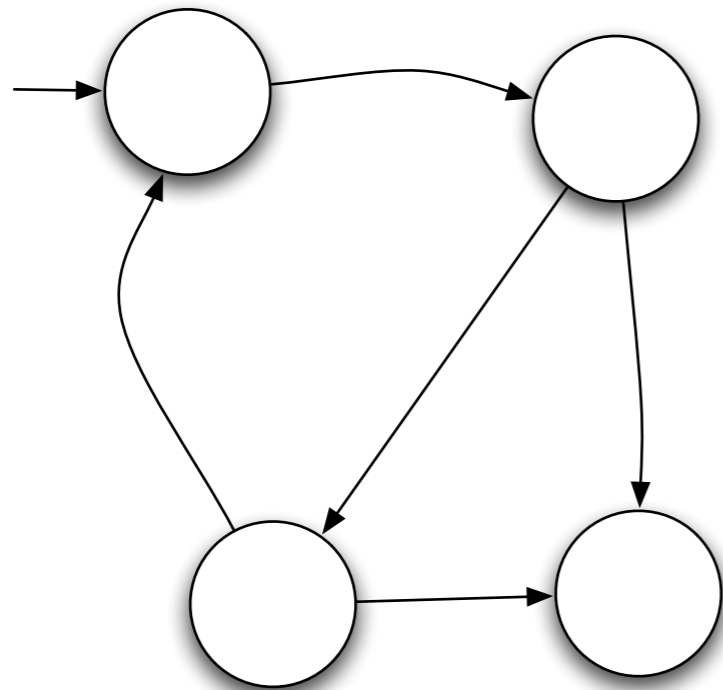
Goal of Player I: ensure that every run on the outcome visits accepting states **finitely often**

From UCoB to UKCoB

Theorem: Winning strategies of Player I on the UCoB automaton can be represented by a **finite machine** (with **m** states)

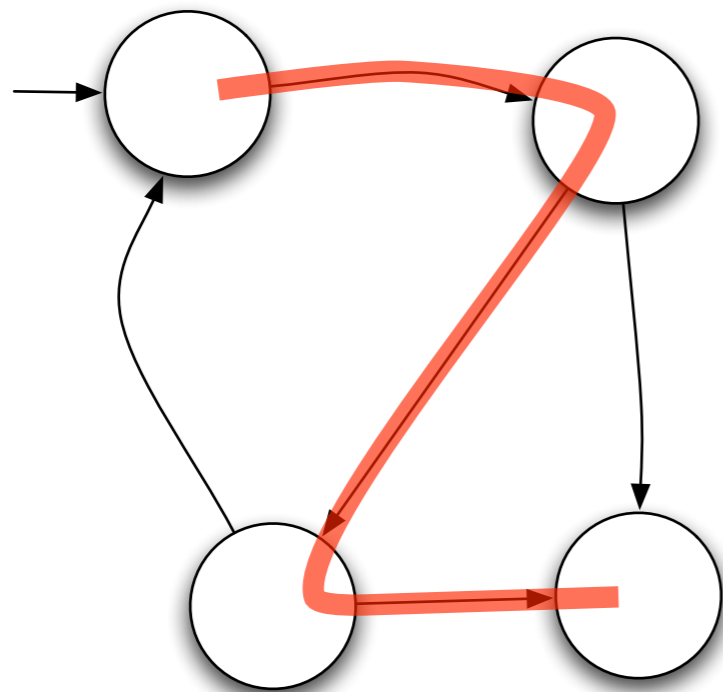
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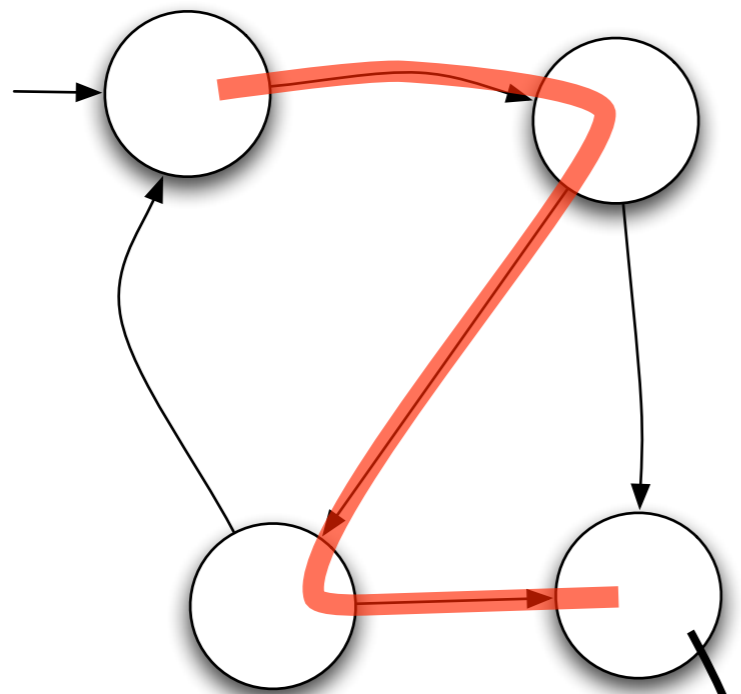
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$(\sigma_1, t_1) (\sigma_2, t_2) (\sigma_3, t_3) \dots$

From UCoB to UKCoB

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Each state
tells PI what to play

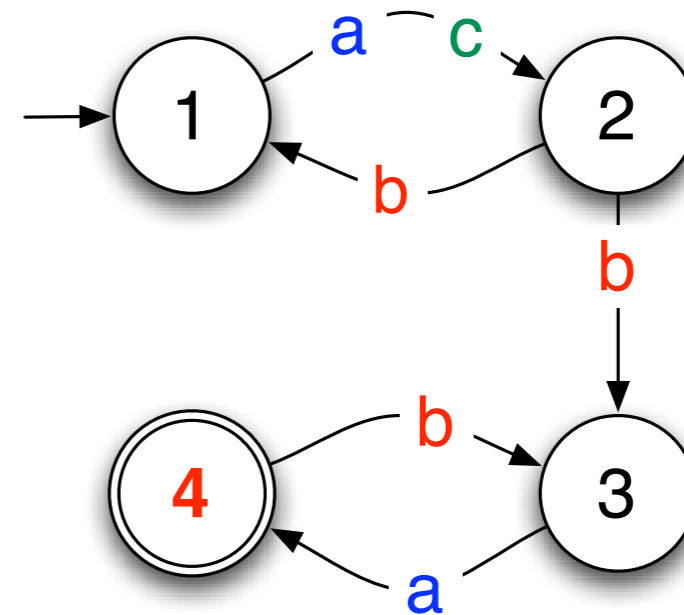
$(\sigma_1, t_1) (\sigma_2, t_2) (\sigma_3, t_3) \dots$

From UCoB to UKCoB

Strategy

UCoB

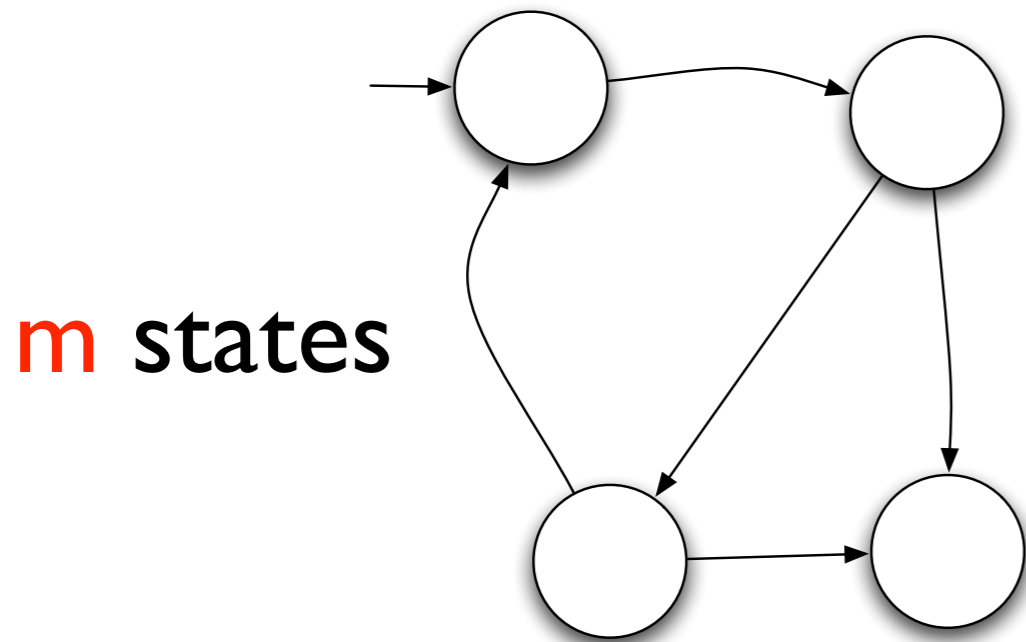
m states



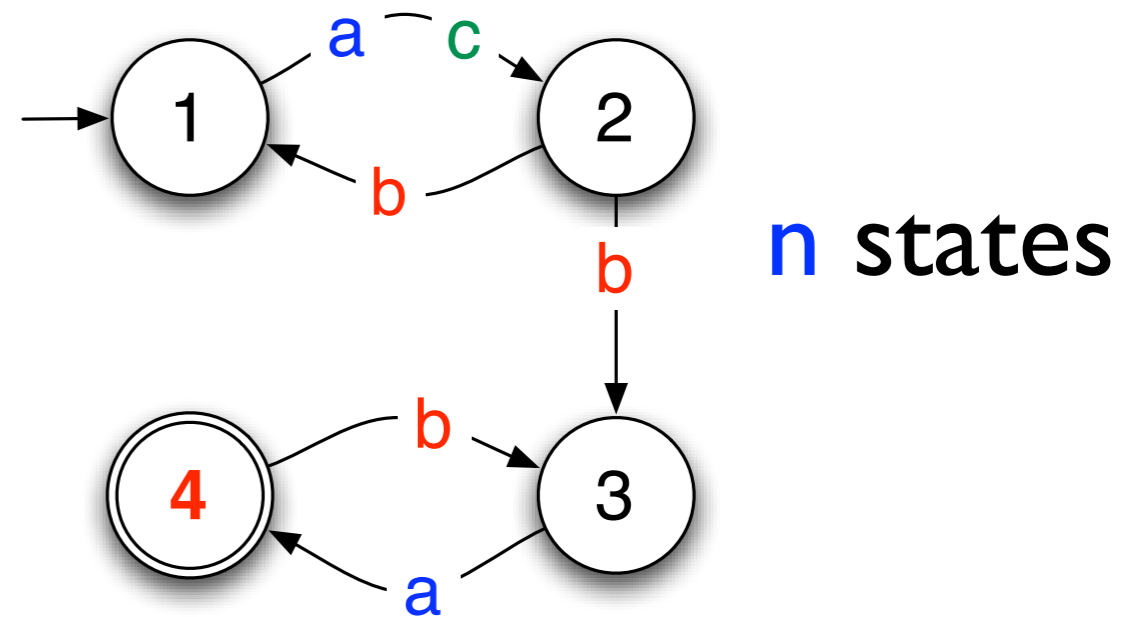
n states

From UCoB to UKCoB

Strategy

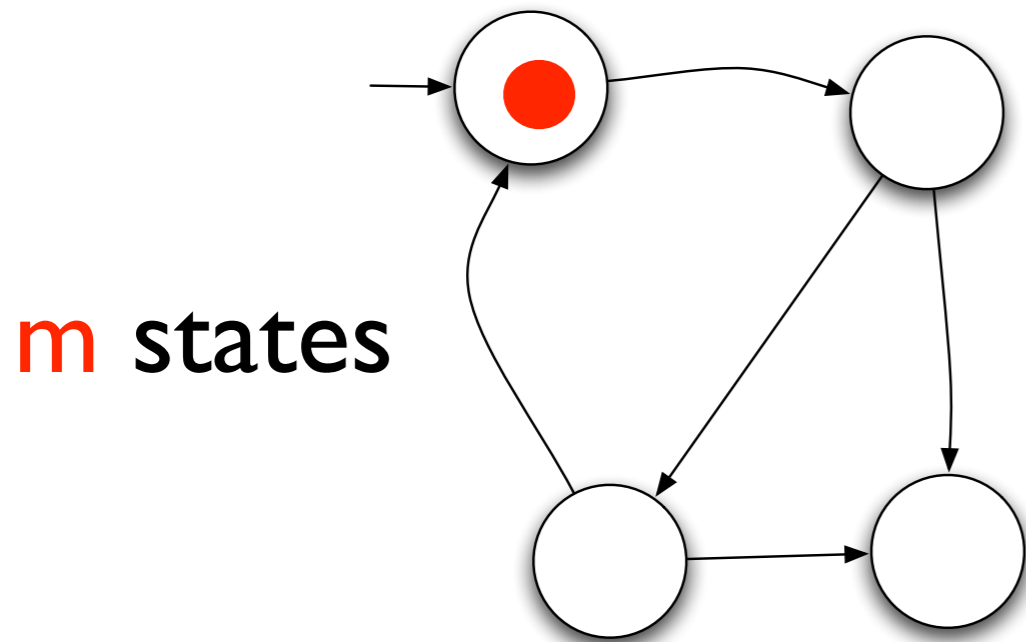


UCoB

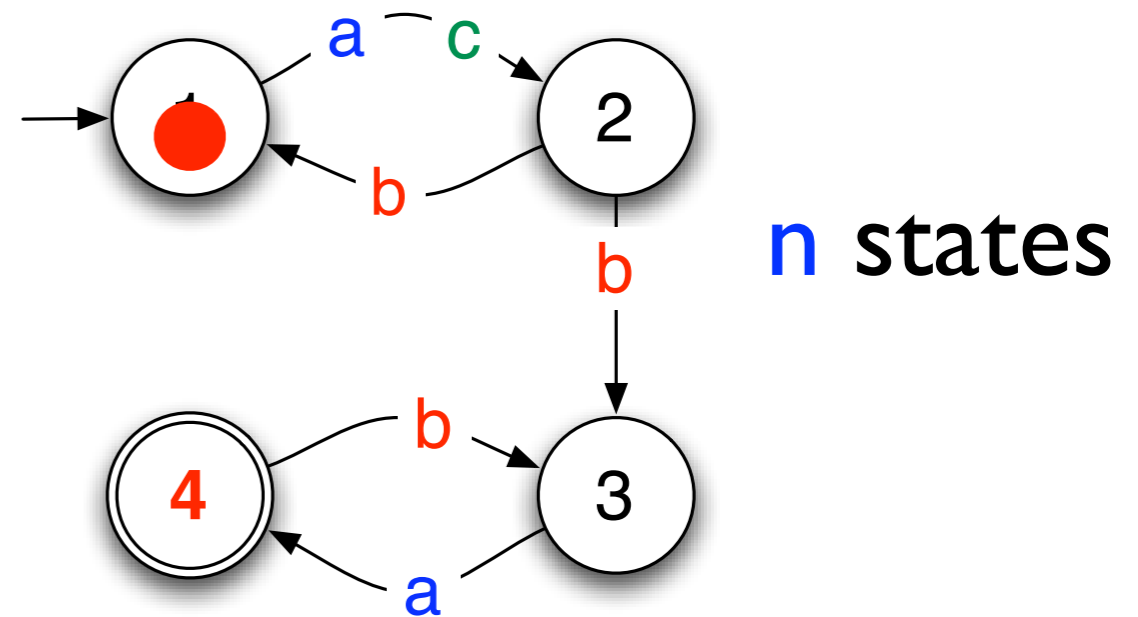


From UCoB to UKCoB

Strategy

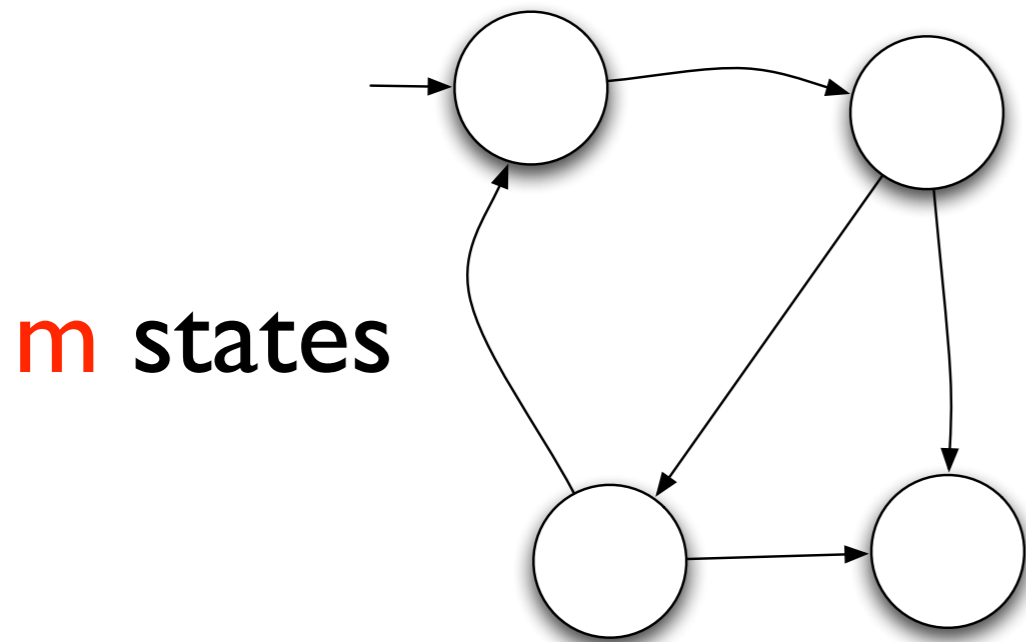


UCoB

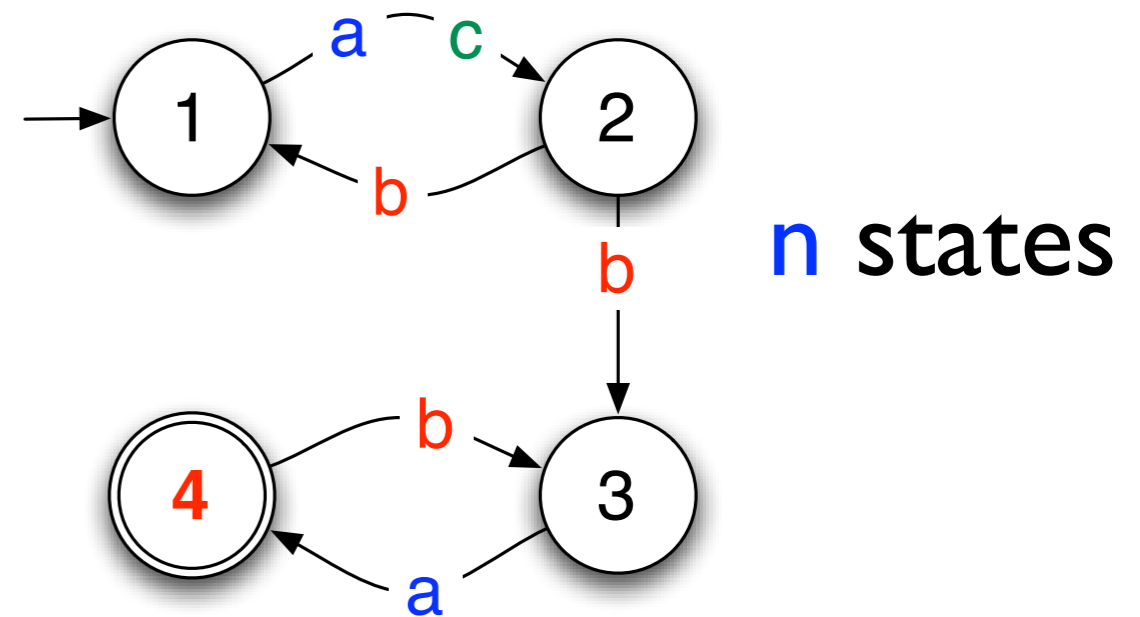


From UCoB to UKCoB

Strategy

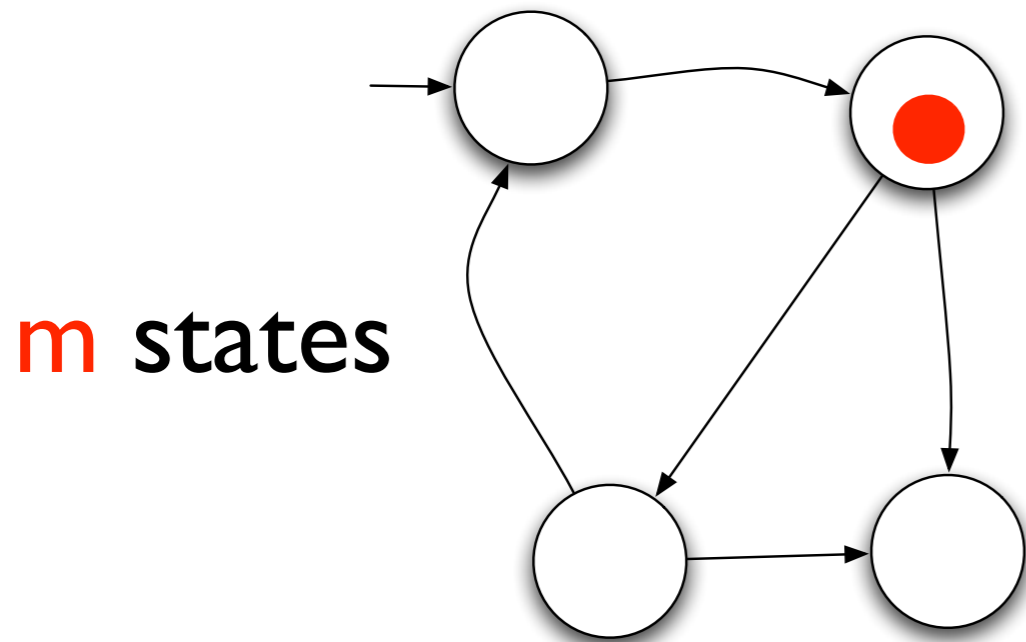


UCoB

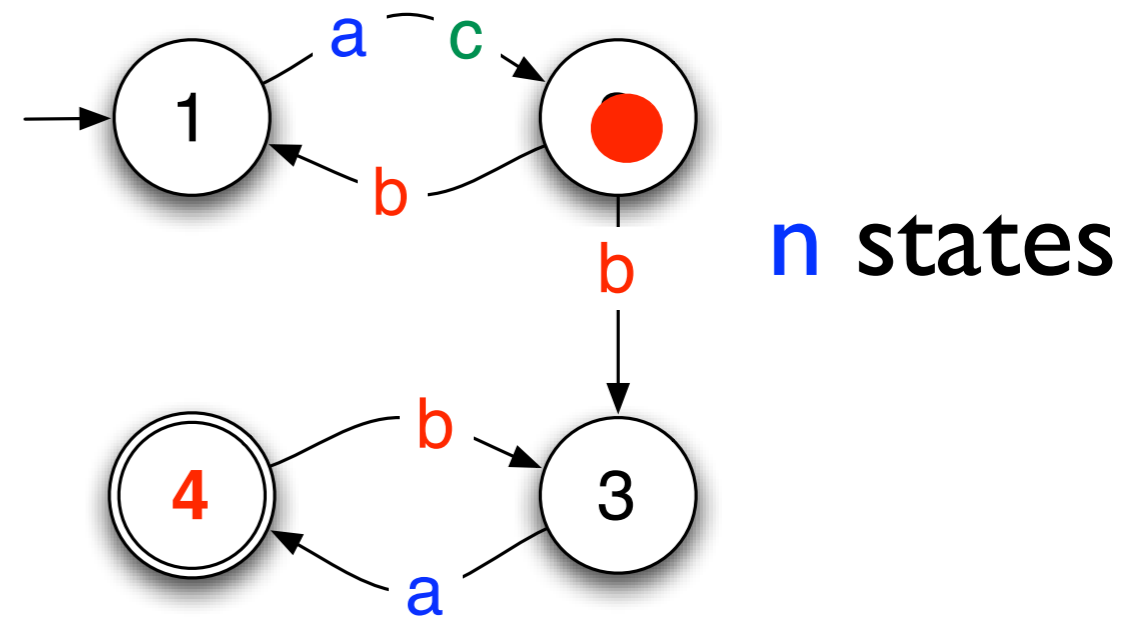


From UCoB to UKCoB

Strategy

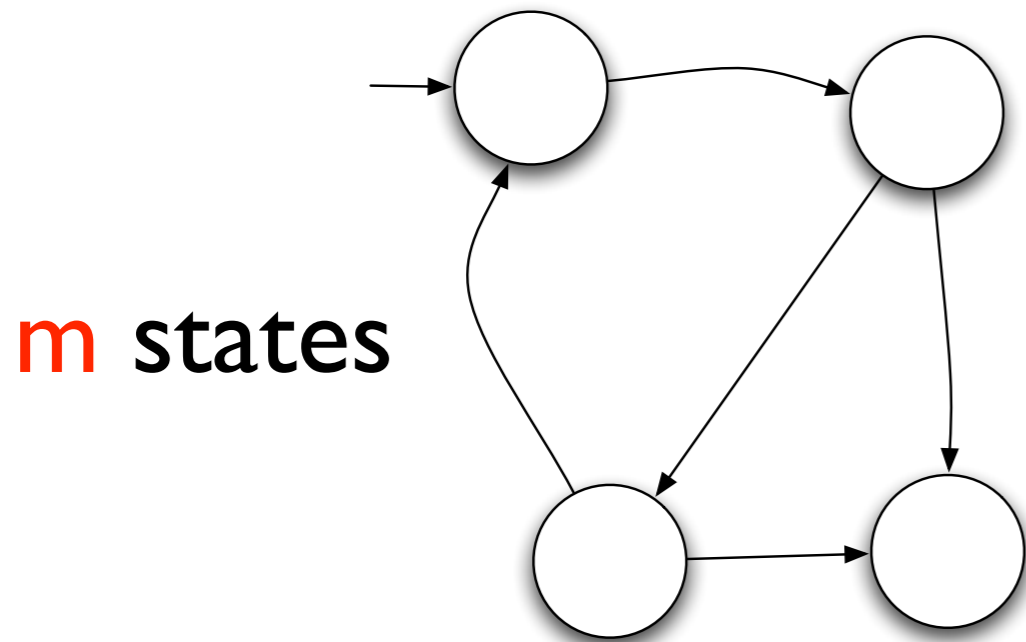


UCoB

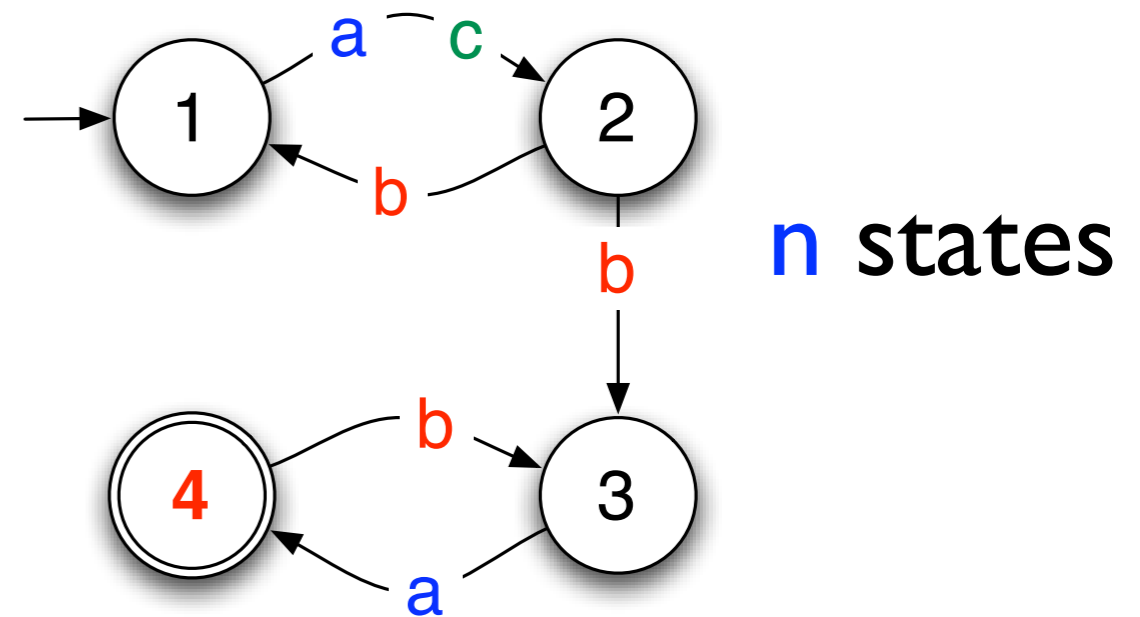


From UCoB to UKCoB

Strategy

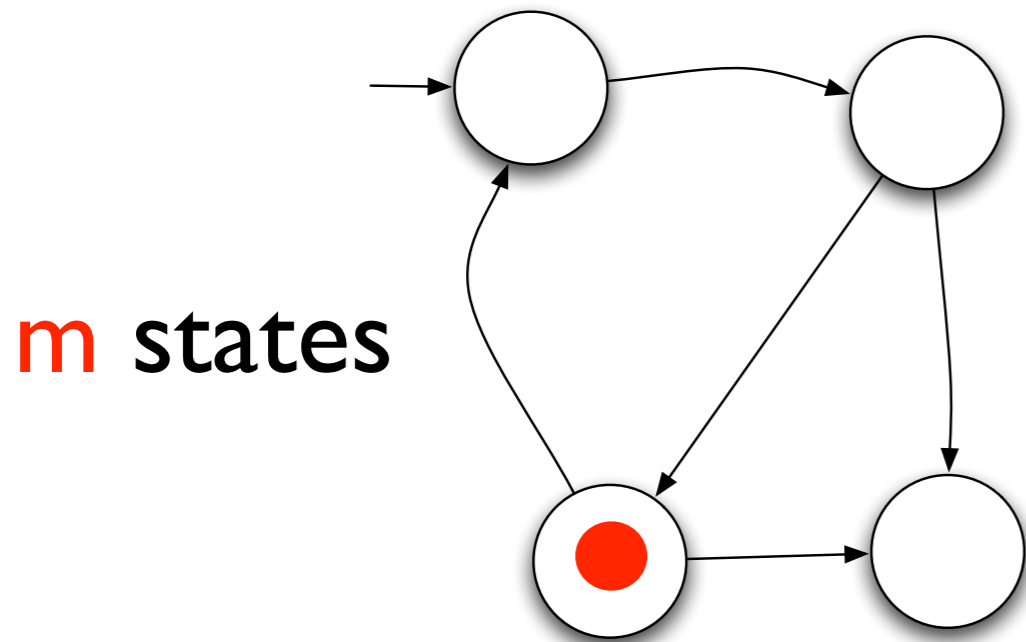


UCoB

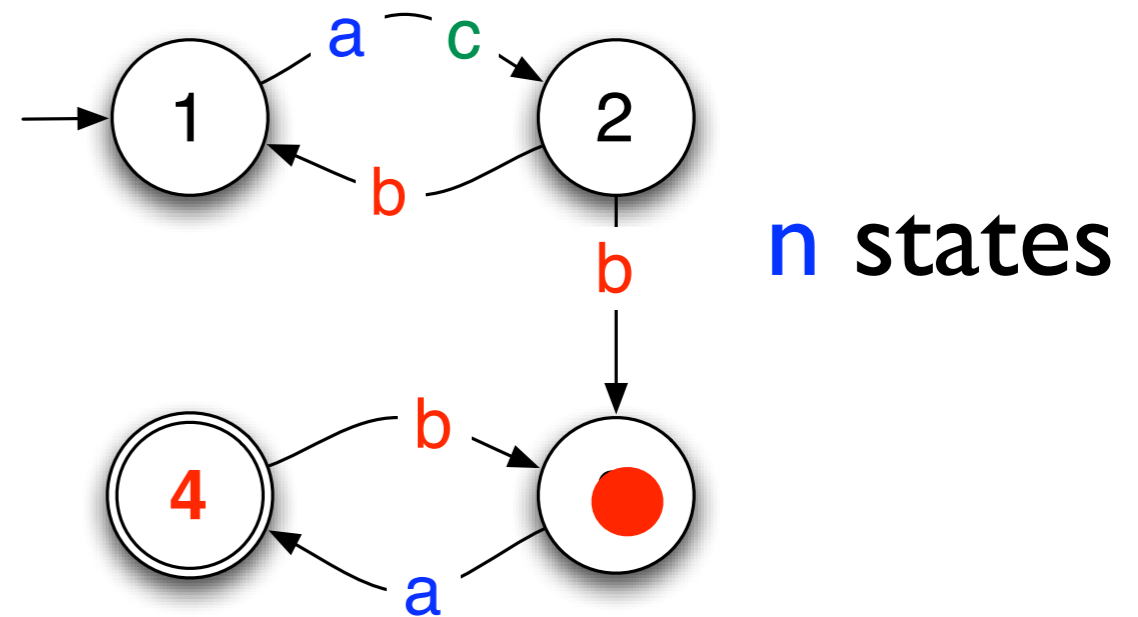


From UCoB to UKCoB

Strategy

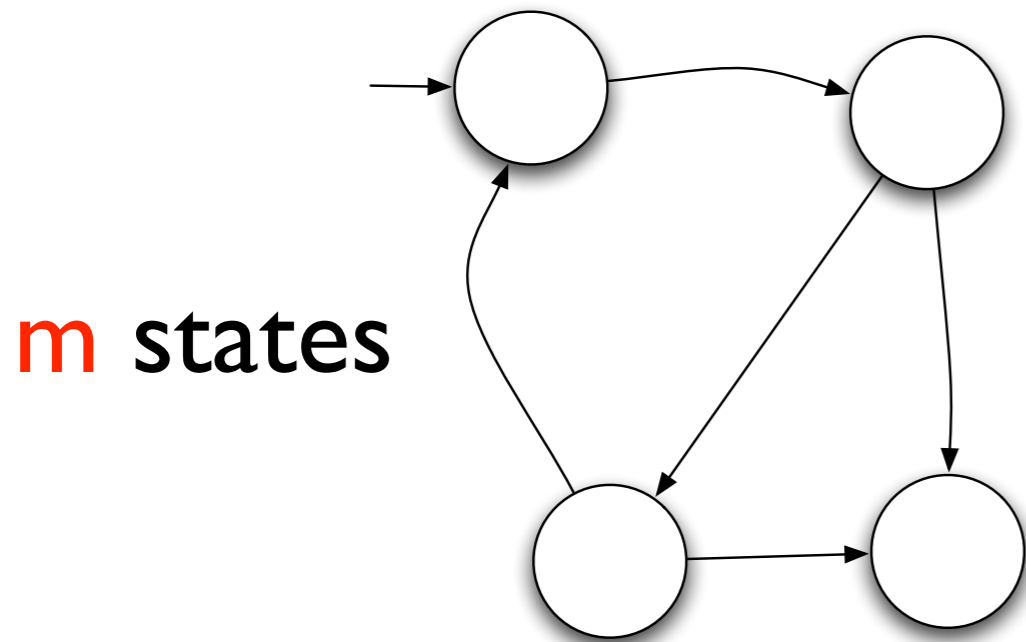


UCoB

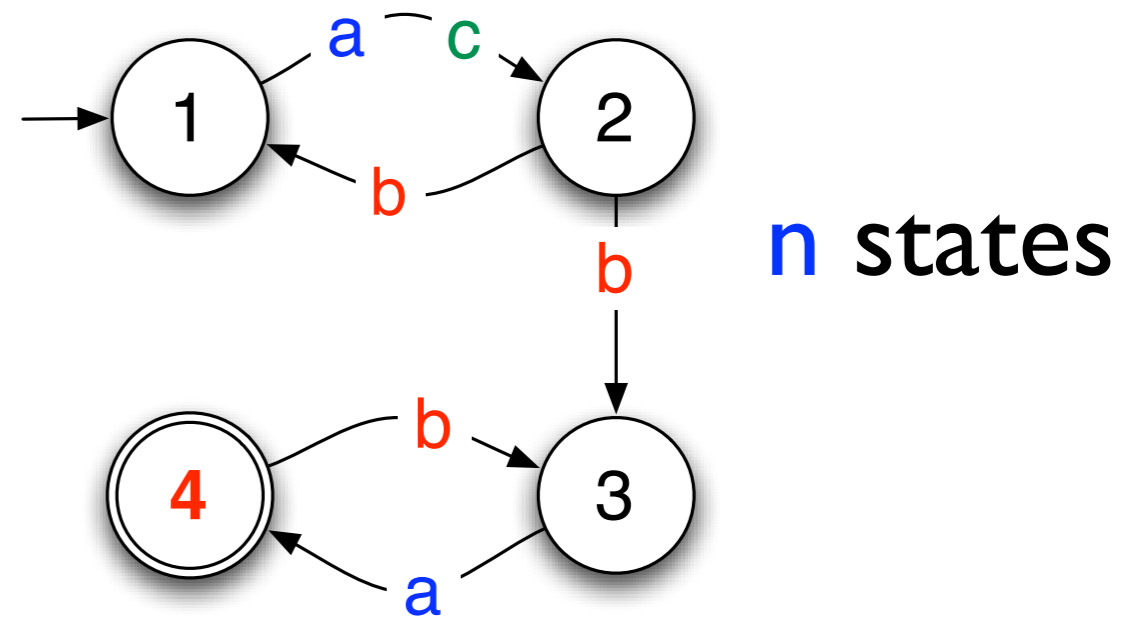


From UCoB to UKCoB

Strategy

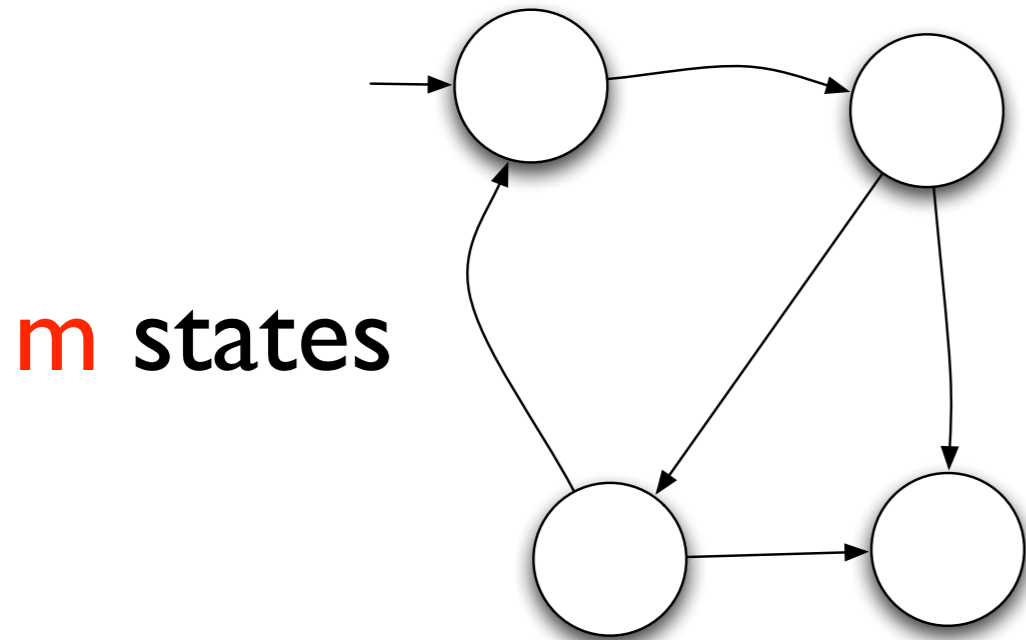


UCoB

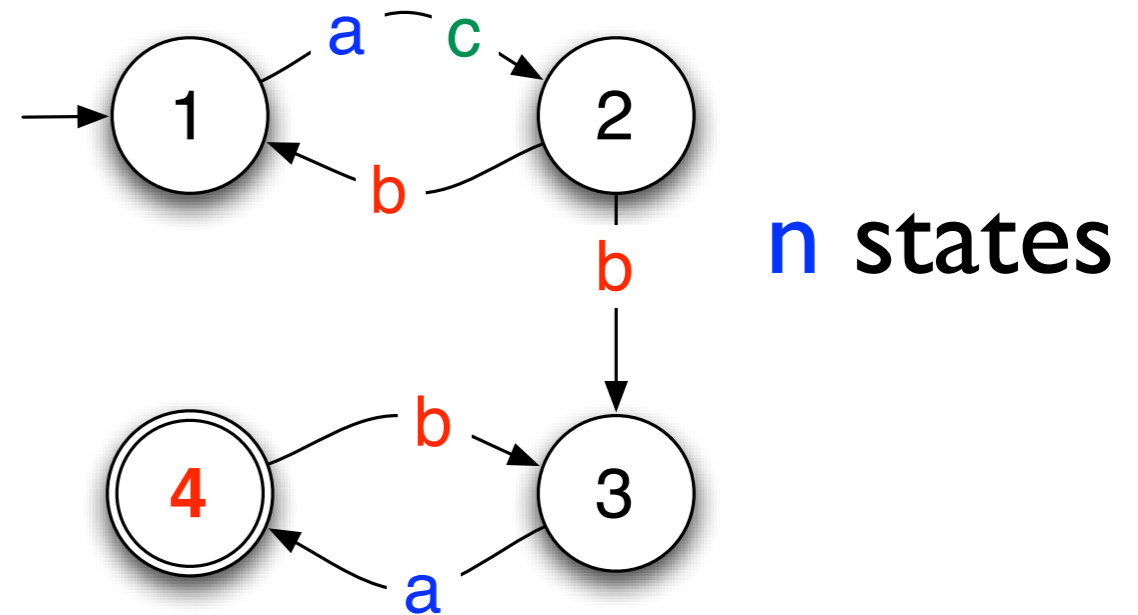


From UCoB to UKCoB

Strategy



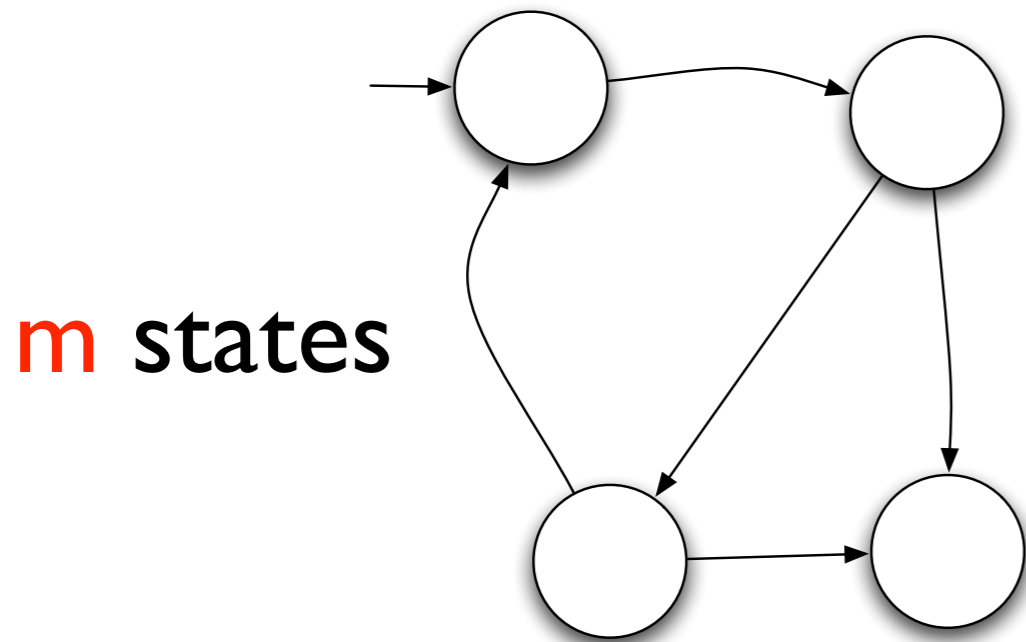
UCoB



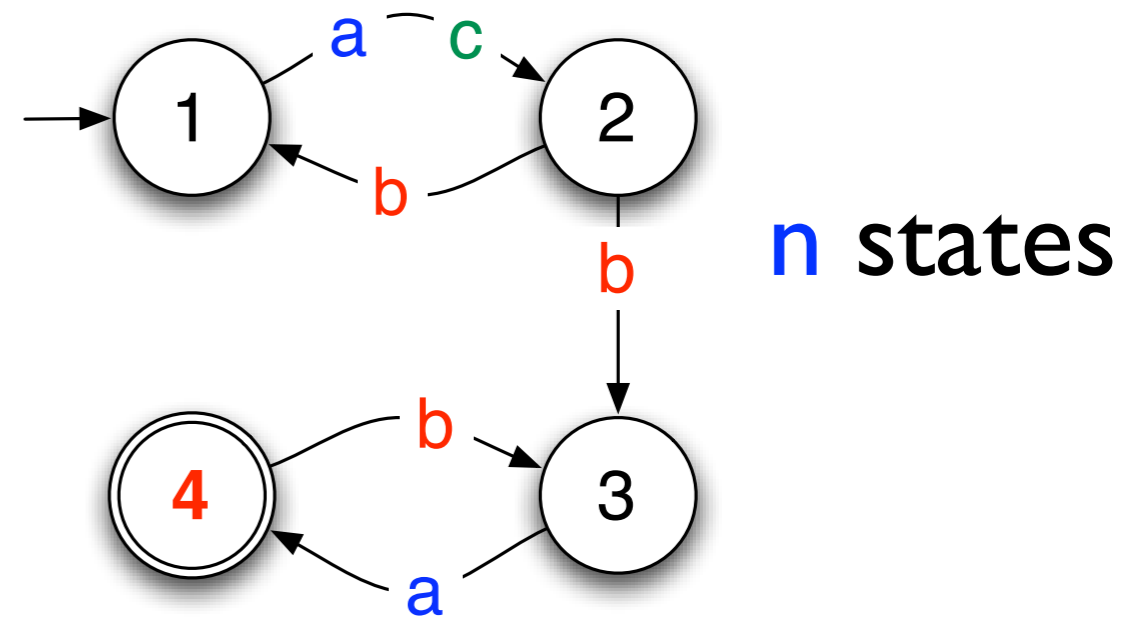
Assume the strategy lets us visit an accepting state
more than $n \times m$ times

From UCoB to UKCoB

Strategy



UCoB

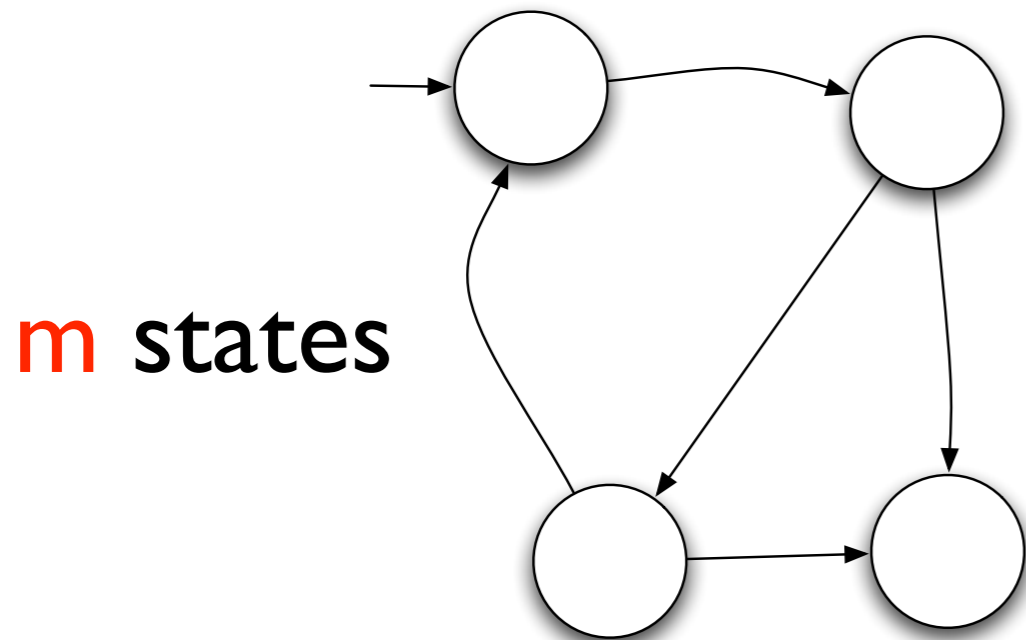


Assume the strategy lets us visit an accepting state
more than $n \times m$ times

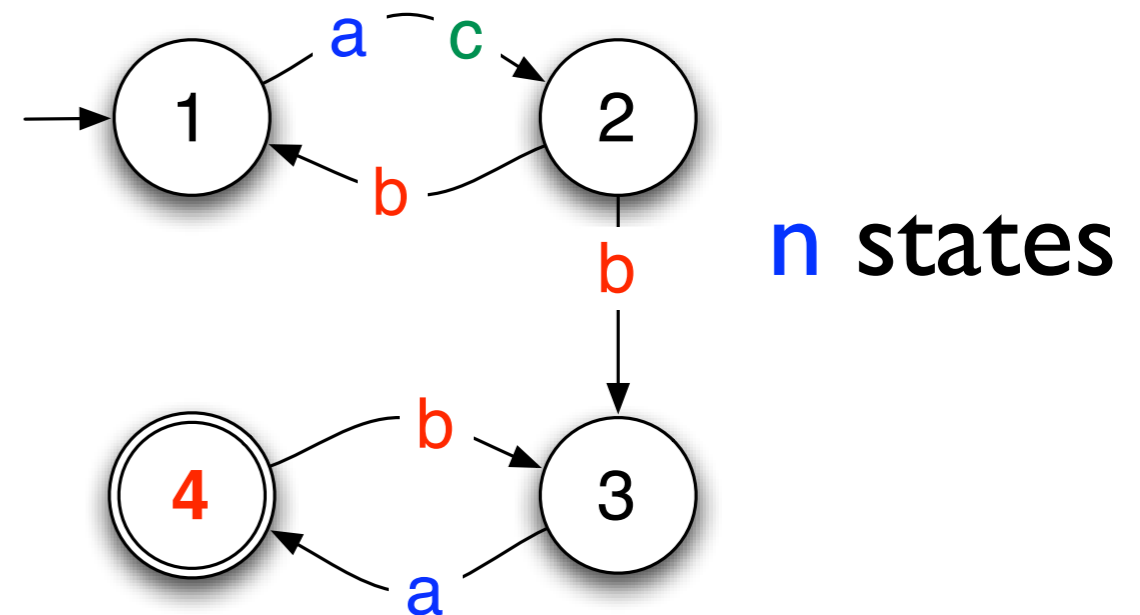
👉 cycle in the product of the strategy and the UCoB

From UCoB to UKCoB

Strategy



UCoB

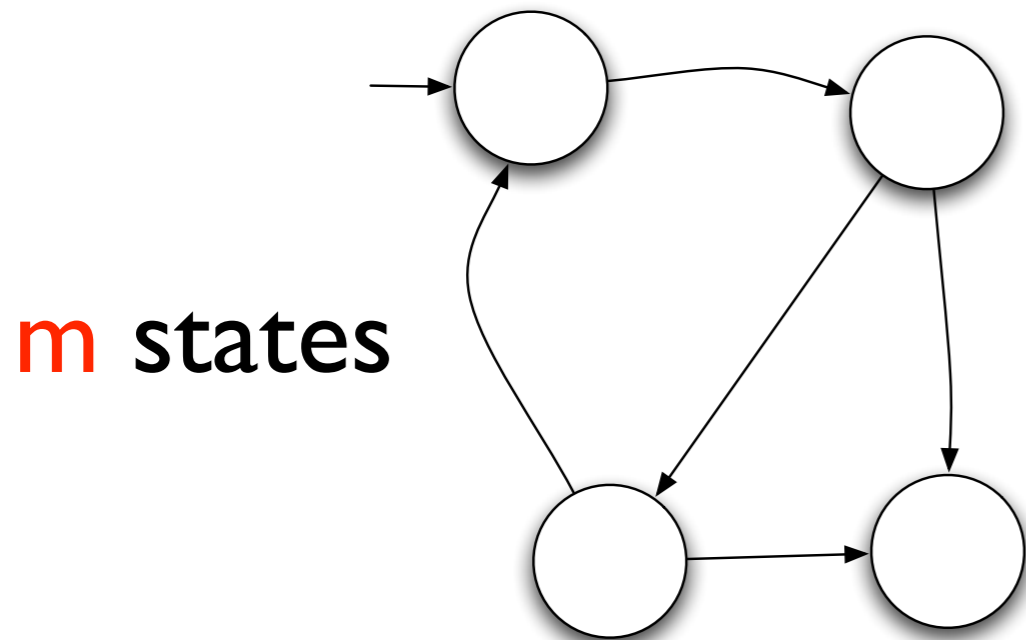


Assume the strategy lets us visit an accepting state
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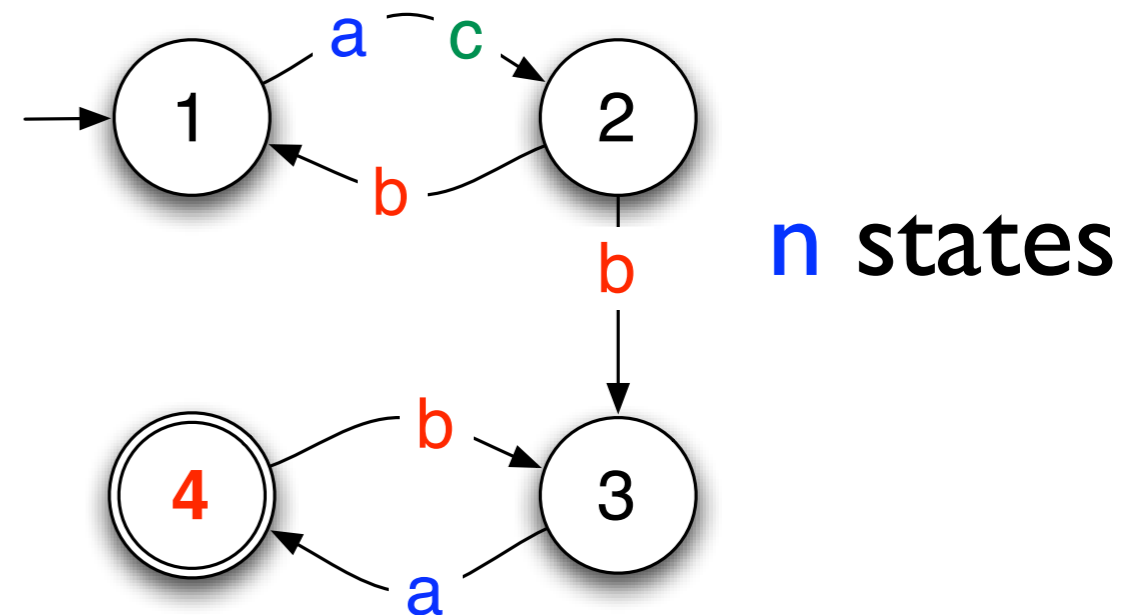
- 👉 **cycle** in the product of the strategy and the UCoB
- 👉 accepting states are visited **infinitely** often

From UCoB to UKCoB

Strategy



UCoB



Assume the strategy lets us visit an accepting state
more than $n \times m$ times

👉 **cycle** in the product of the strategy and the UCoB

👉 accepting states are visited **infinitely** often

👉 the strategy is **not winning**

From UCoB to UKCoB

Theorem: Player I has a winning strategy in
 $\langle \Sigma_1, \Sigma_2, L_{\text{UCoB}}(A_\varphi) \rangle$

iff

she has a winning strategy in
 $\langle \Sigma_1, \Sigma_2, L_{\text{UKCoB}}(A_\varphi) \rangle$ for $K=n \times m$

We can thus **solve the game** by playing with
the (**weaker**) **K-Co-Büchi** acceptance condition

K-Co-Büchi = avoid visiting accepting states too often
= **safety condition** !

Incremental procedure

Theorem: **If** Player I has a winning strategy in
 $\langle \Sigma_1, \Sigma_2, L_{UK \text{coB}}(A_\varphi) \rangle$

then

she has a winning strategy in
 $\langle \Sigma_1, \Sigma_2, L_{UK' \text{coB}}(A_\varphi) \rangle$ for $K' \geq K$

Incremental procedure

Theorem: If Player I has a winning strategy in
 $\langle \Sigma_1, \Sigma_2, \text{LU}_K \text{coB}(A_\varphi) \rangle$

then

she has a winning strategy in
 $\langle \Sigma_1, \Sigma_2, \text{LU}_{K'} \text{coB}(A_\varphi) \rangle$ for $K' \geq K$

```
i := 0
```

```
While (true)
```

```
  If P1 wins on  $\text{LU}_i \text{coB}(A_\varphi)$  return «win»
```

```
  Else if P2 wins on  $\text{LU}_i \text{coB}(A_{\neg\varphi})$  return «lose»
```

```
  Else i := i + 1
```

Incremental procedure

Theorem: If Player 1 has a winning strategy in

Each step can be computed by **solving** a
safety game

she has a winning strategy in
 $\langle \Sigma_1, \Sigma_2, \text{LU}_{K'}^{\text{coB}}(A_\varphi) \rangle$ for $K' \geq K$

```
i := 0
While (true)
  If P1 wins on  $\text{LU}_{\mathbf{i}}^{\text{coB}}(A_\varphi)$  return «win»
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```


Incremental procedure

Theorem: If Player 1 has a winning strategy in

Each step can be computed by **solving** a safety game

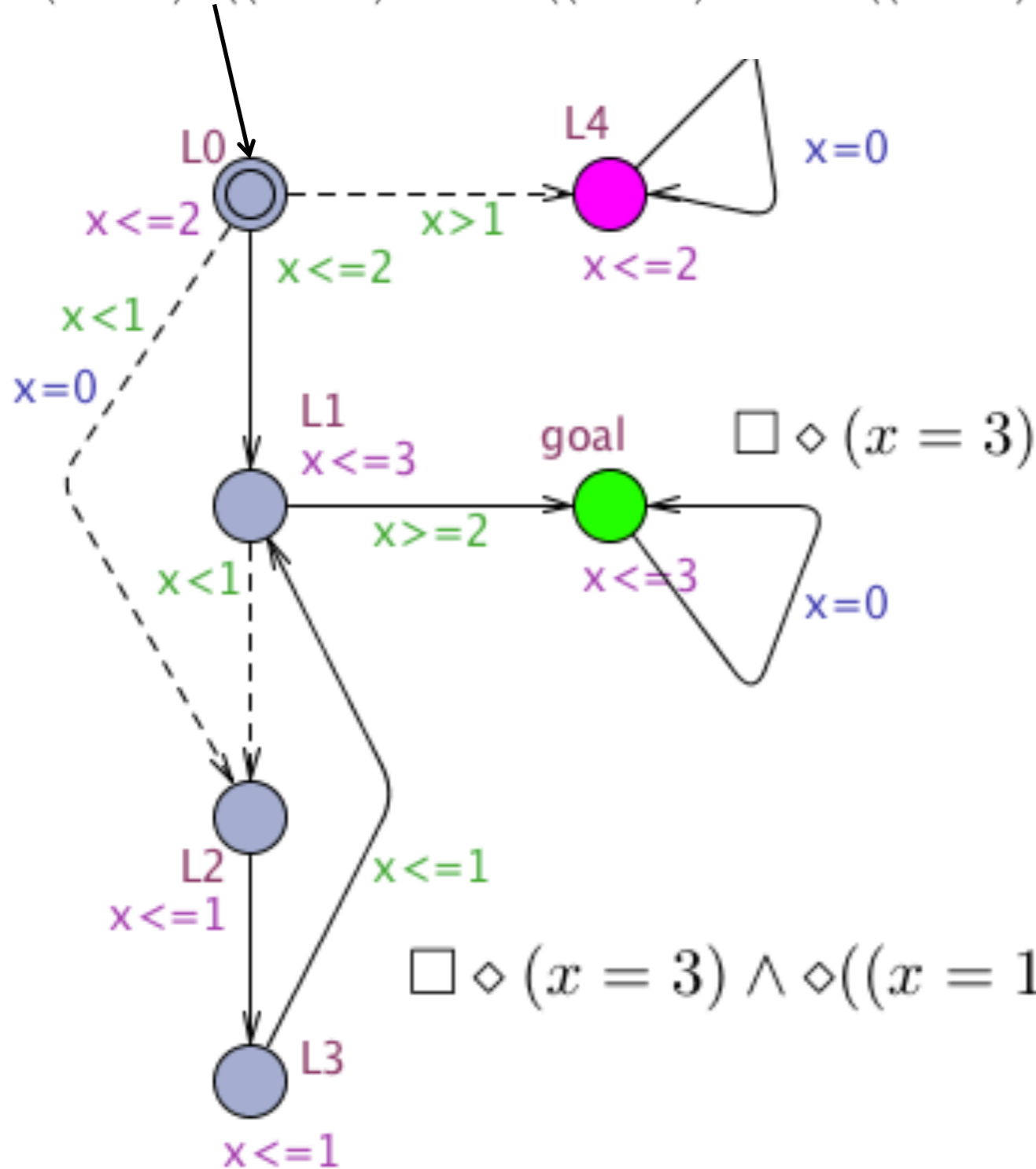
she has a winning strategy in $\langle \Sigma_i \rangle$

In practice this algorithm **might terminate** with **small** values of ***i***

```
i := 0
While (true)
  If P1 wins on  $\text{LU}_{\mathbf{i}}\text{coB}(A_{\varphi})$  return «win»
  Else if P2 wins on  $\text{LU}_{\mathbf{i}}\text{coB}(A_{\neg\varphi})$  return «lose»
  Else i := i + 1
```

Initial example

$$\Box \diamond (x = 3) \wedge ((x < 1) \wedge t02 \wedge \diamond ((x = 1) \wedge t23 \wedge \diamond ((x = 1) \wedge t31)) \vee (t01 \wedge (x = 1)) \wedge \diamond ((x = 1) \mathcal{U} (t1g \wedge (x = 2))))$$



Example

$$\Sigma_1 = \{grant\},$$

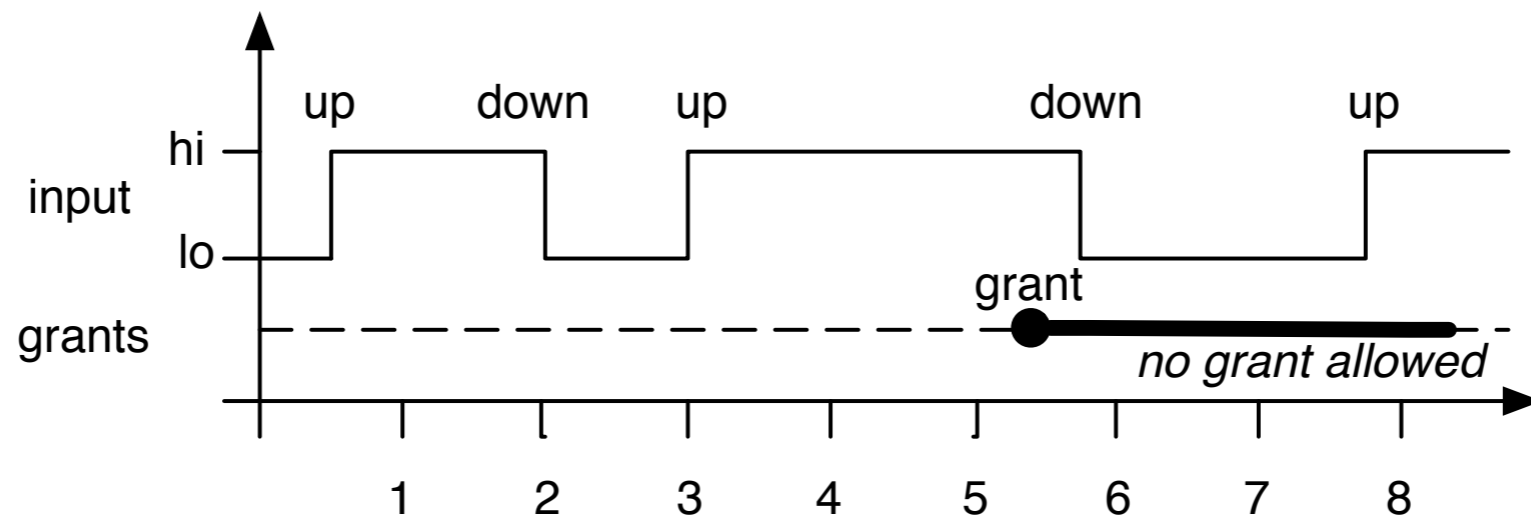
$$\Sigma_2 = \{up, down\}$$

$$\text{Hyp} \equiv \square \left(up \rightarrow (\neg down \mathcal{U} (down \wedge \triangleleft_{\geq 1} up)) \right) \wedge$$

$$\square \left(down \rightarrow (\neg up \mathcal{U} (up \wedge \triangleleft_{\geq 1} down)) \right)$$

$$\text{Req}_1 \equiv \square \left((down \wedge \triangleleft_{> 2} up) \rightarrow (\neg up \mathcal{U} grant) \right)$$

$$\text{Req}_2 \equiv \square (grant \rightarrow \neg \triangleleft_{< 3} grant)$$



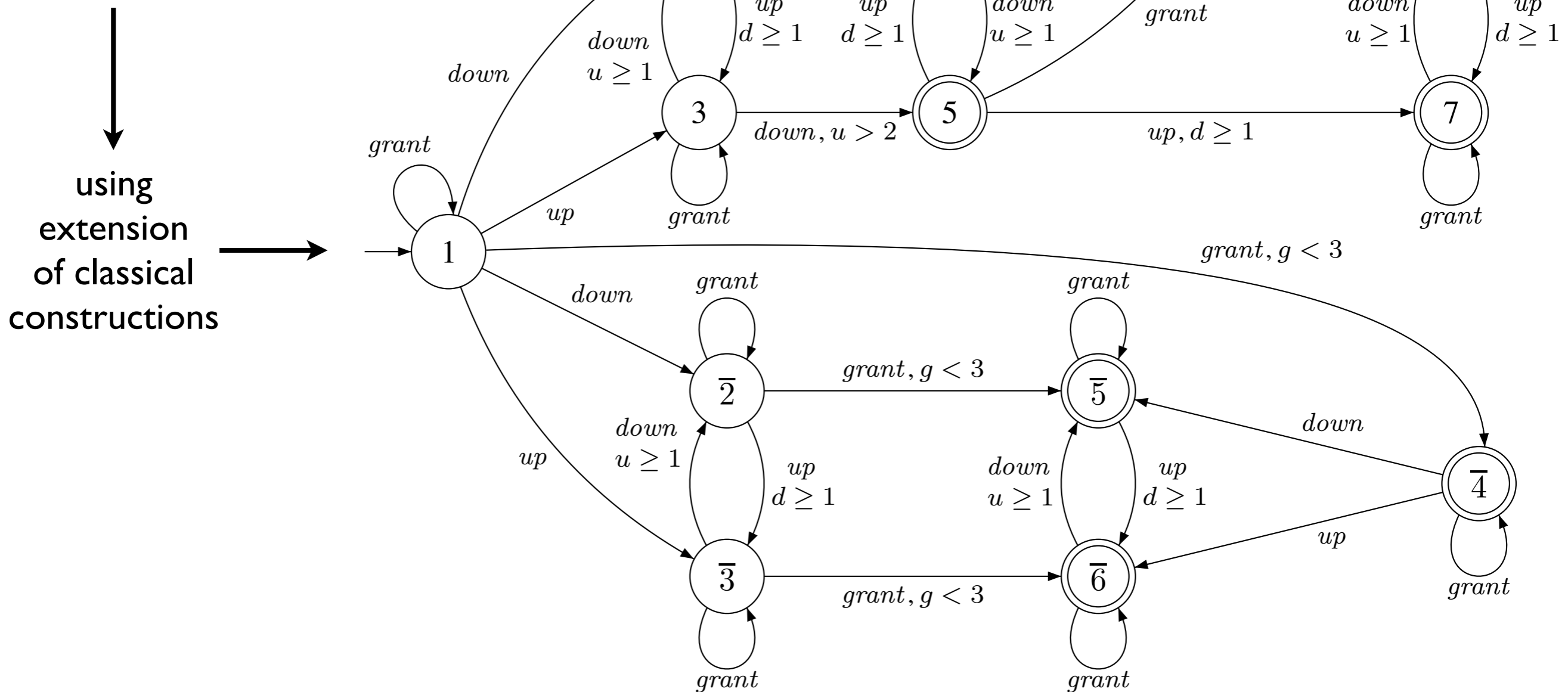
Example

$$\text{Hyp} \equiv \square \left(\text{up} \rightarrow (\neg \text{down} \mathcal{U} (\text{down} \wedge \triangleleft_{\geq 1} \text{up})) \right) \wedge$$

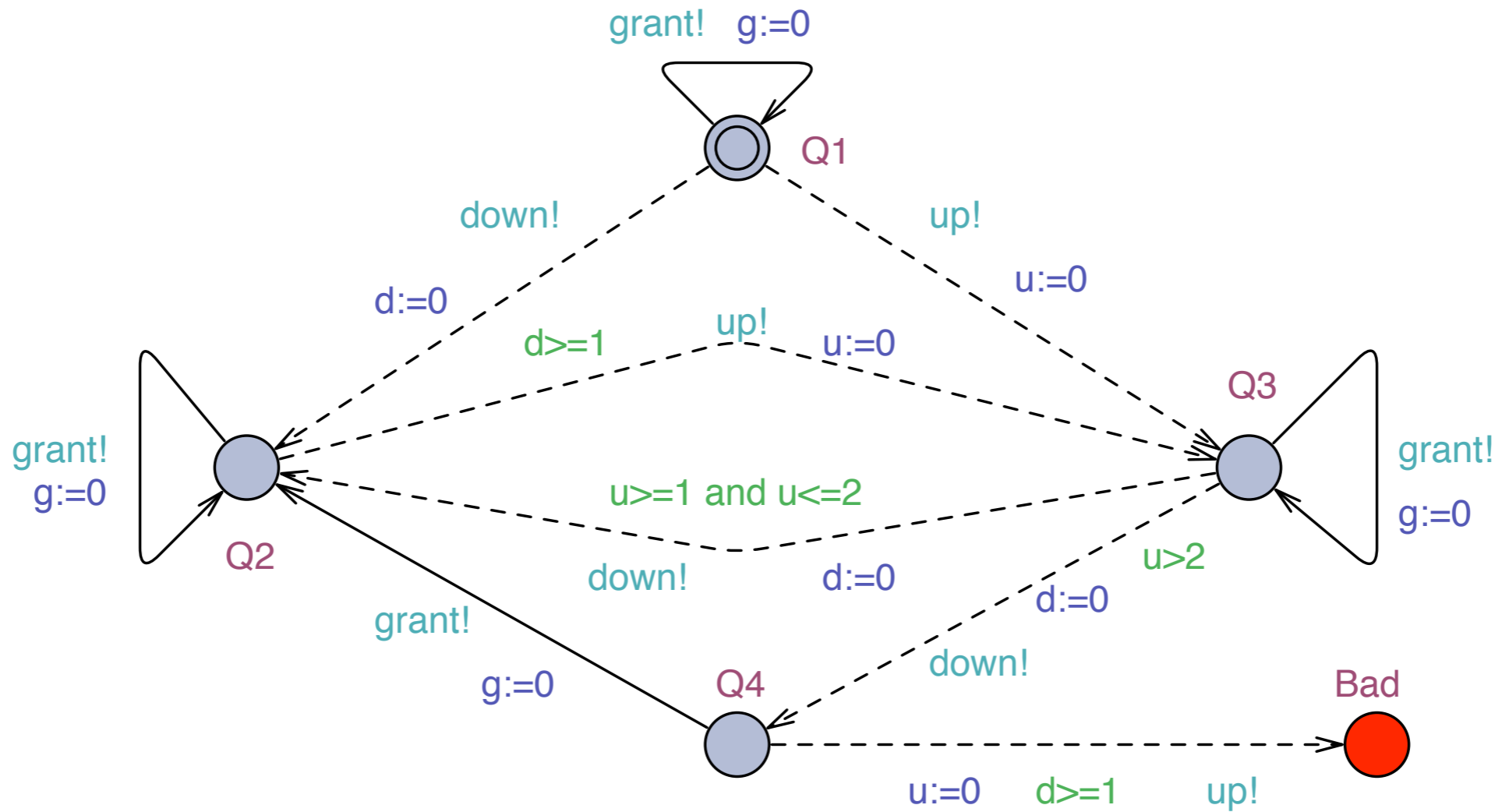
$$\square \left(\text{down} \rightarrow (\neg \text{up} \mathcal{U} (\text{up} \wedge \triangleleft_{\geq 1} \text{down})) \right)$$

$$\text{Req}_1 \equiv \square \left((\text{down} \wedge \triangleleft_{> 2} \text{up}) \rightarrow (\neg \text{up} \mathcal{U} \text{grant}) \right)$$

$$\text{Req}_2 \equiv \square (\text{grant} \rightarrow \neg \triangleleft_{< 3} \text{grant})$$

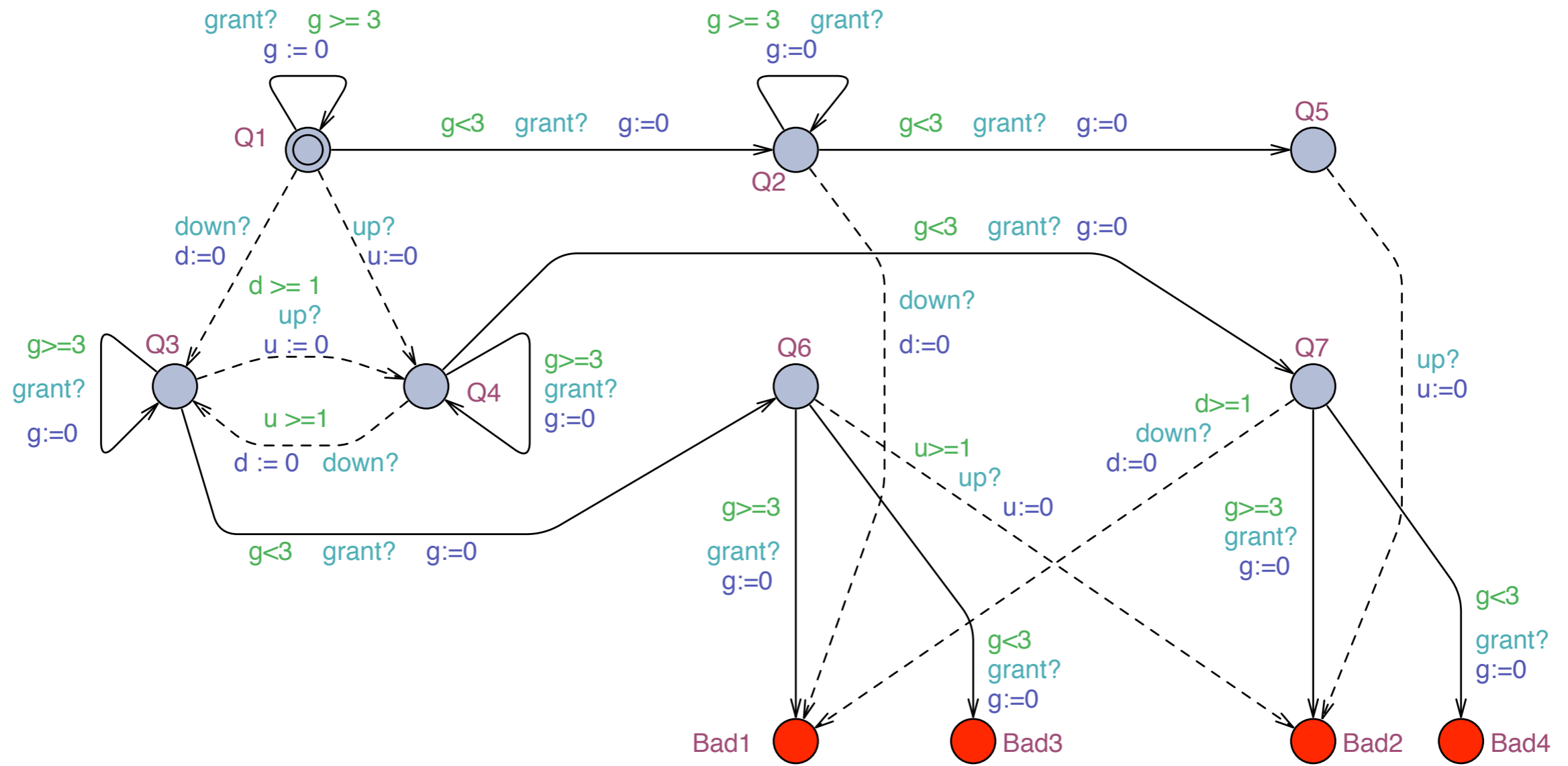


Illustration



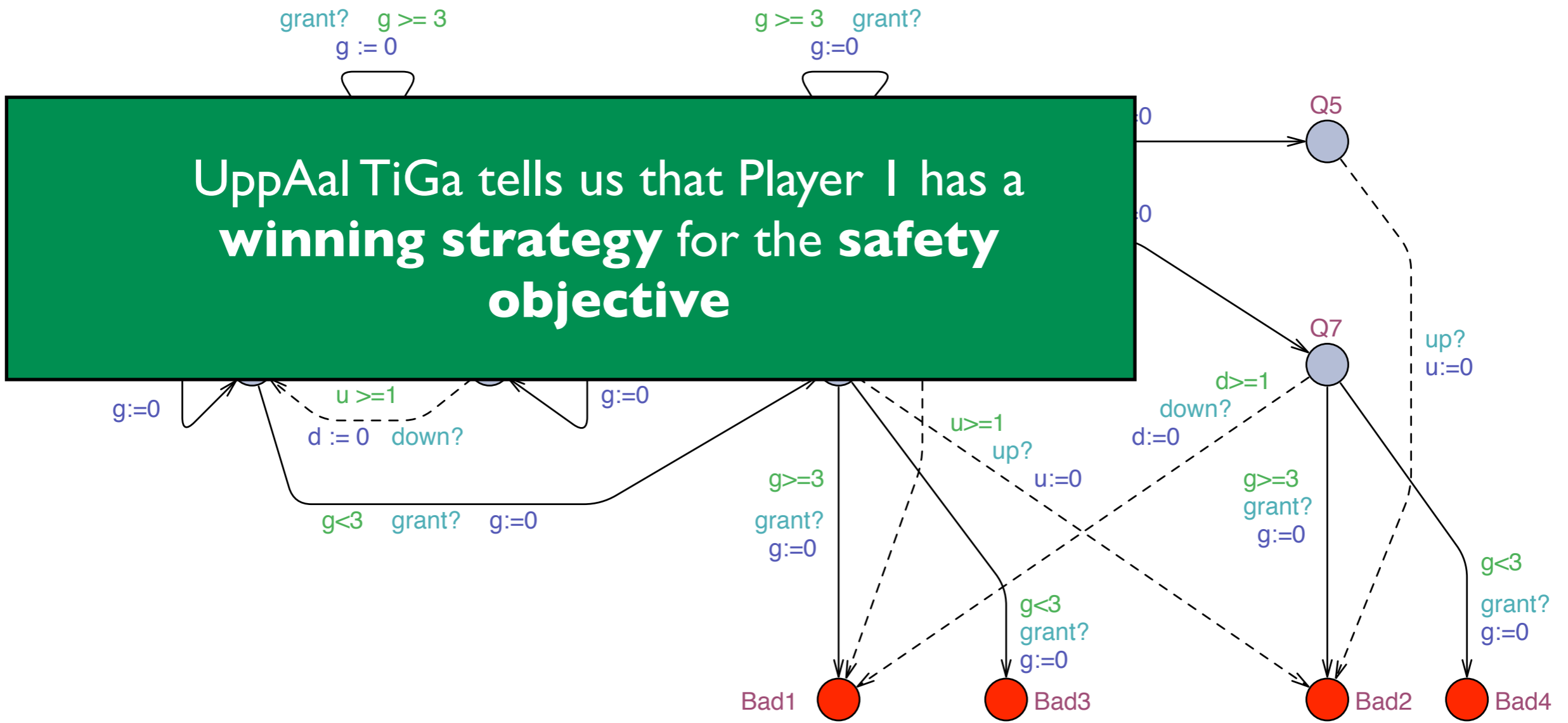
For $K=1$

Illustration



For $K=1$

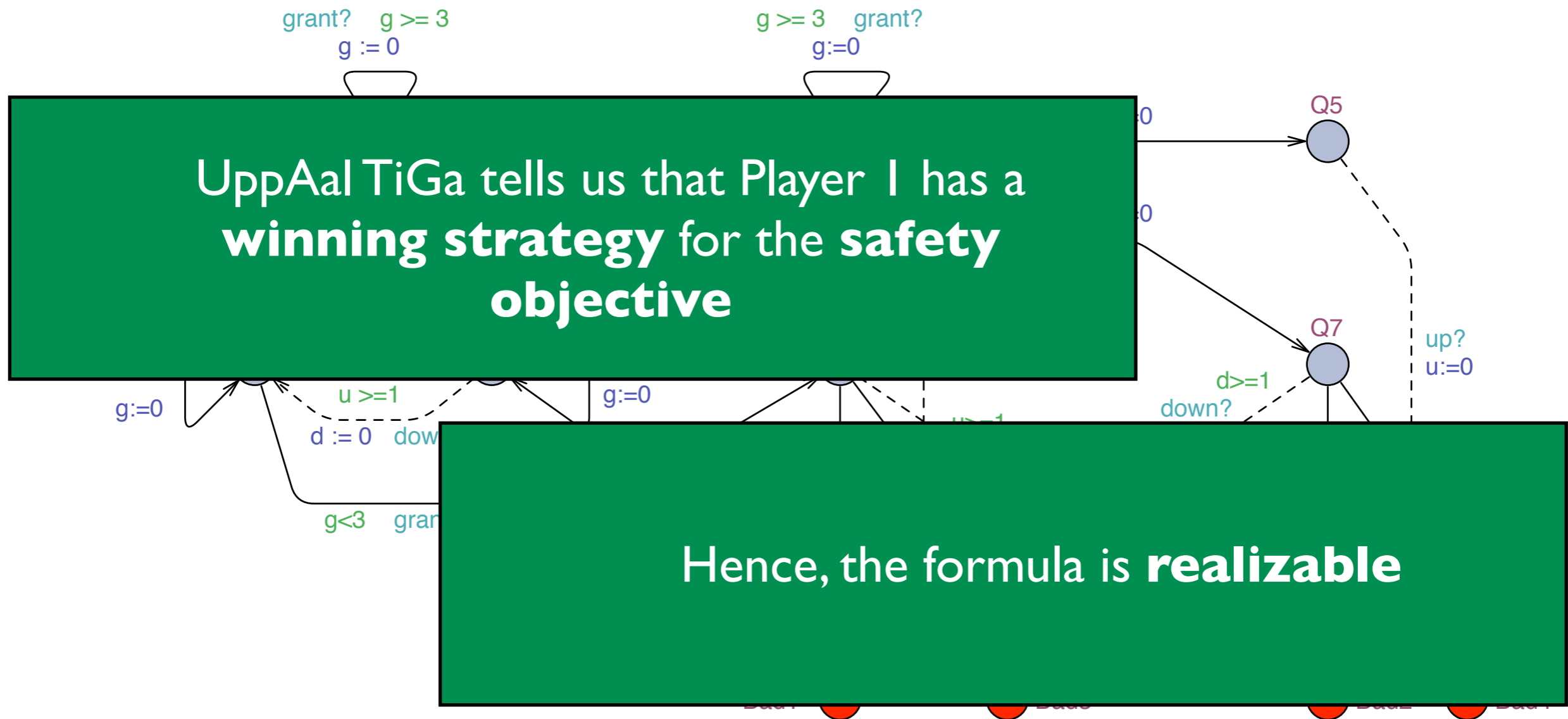
Illustration



UppAal TiGa tells us that Player I has a **winning strategy** for the **safety objective**

For $K=1$

Illustration



For $K=1$

Questions ?

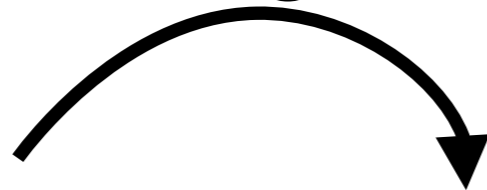


Counter machine - run

q_1		
1	5	4

Counter machine - run

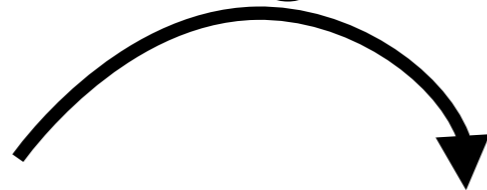
c_2++ ; goto q_3



q_1		
1	5	4

Counter machine - run

c_2++ ; goto q_3



q_1		
1	5	4

q_3		
1	6	4

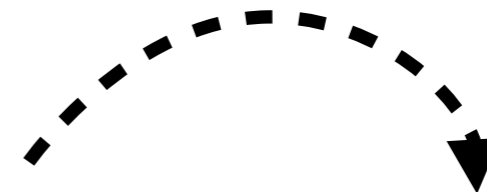
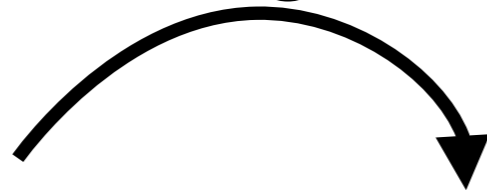
Counter machine - run

c_2++ ; goto q_3

loss

q_1		
1	5	4

q_3		
1	6	4



Counter machine - run

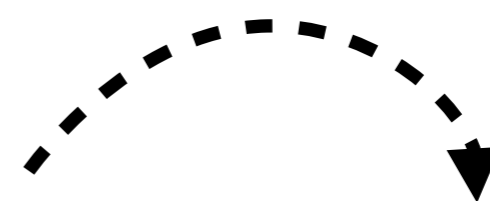
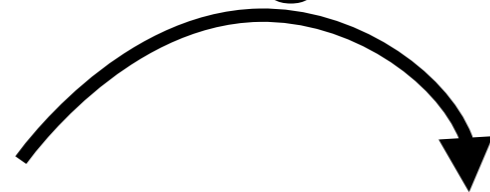
c_2++ ; goto q_3

loss

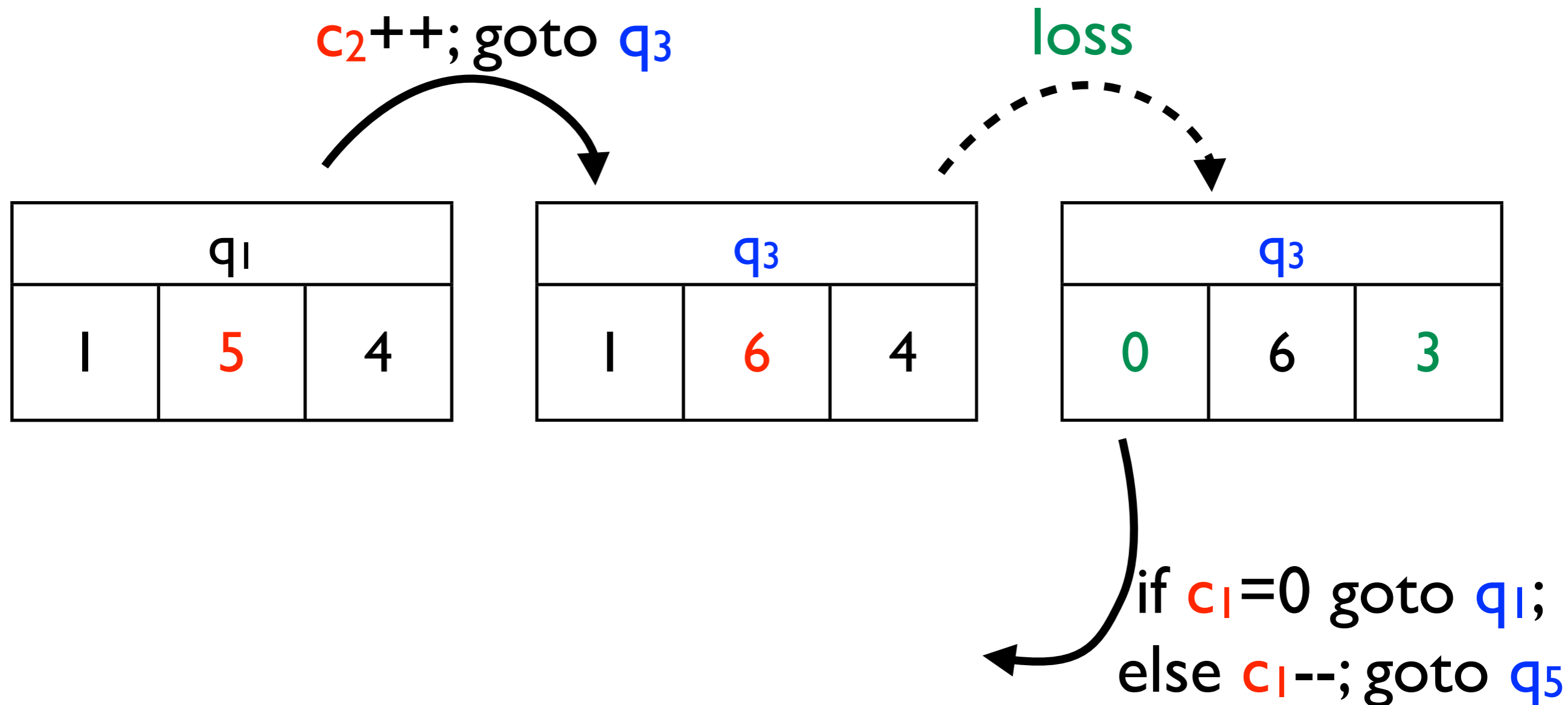
q_1		
1	5	4

q_3		
1	6	4

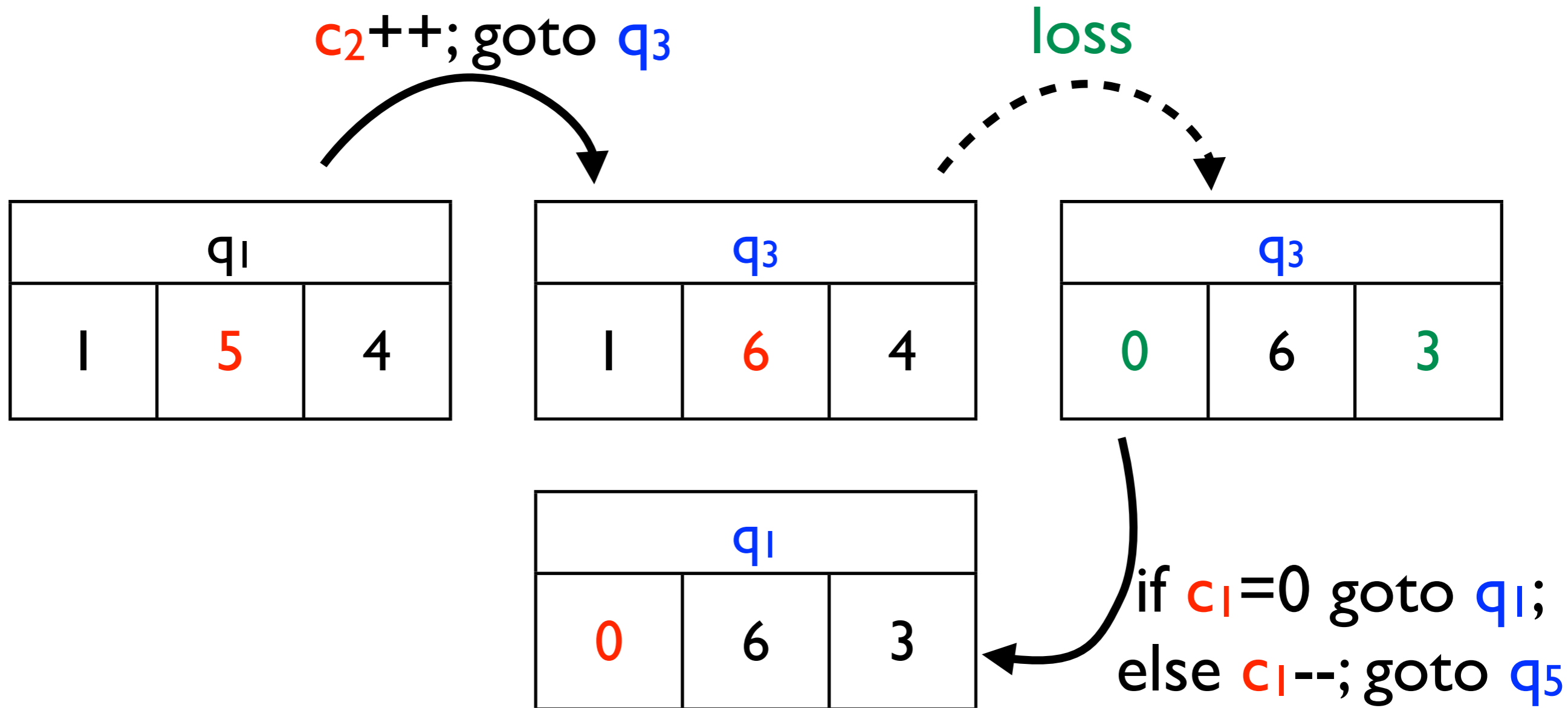
q_3		
0	6	3



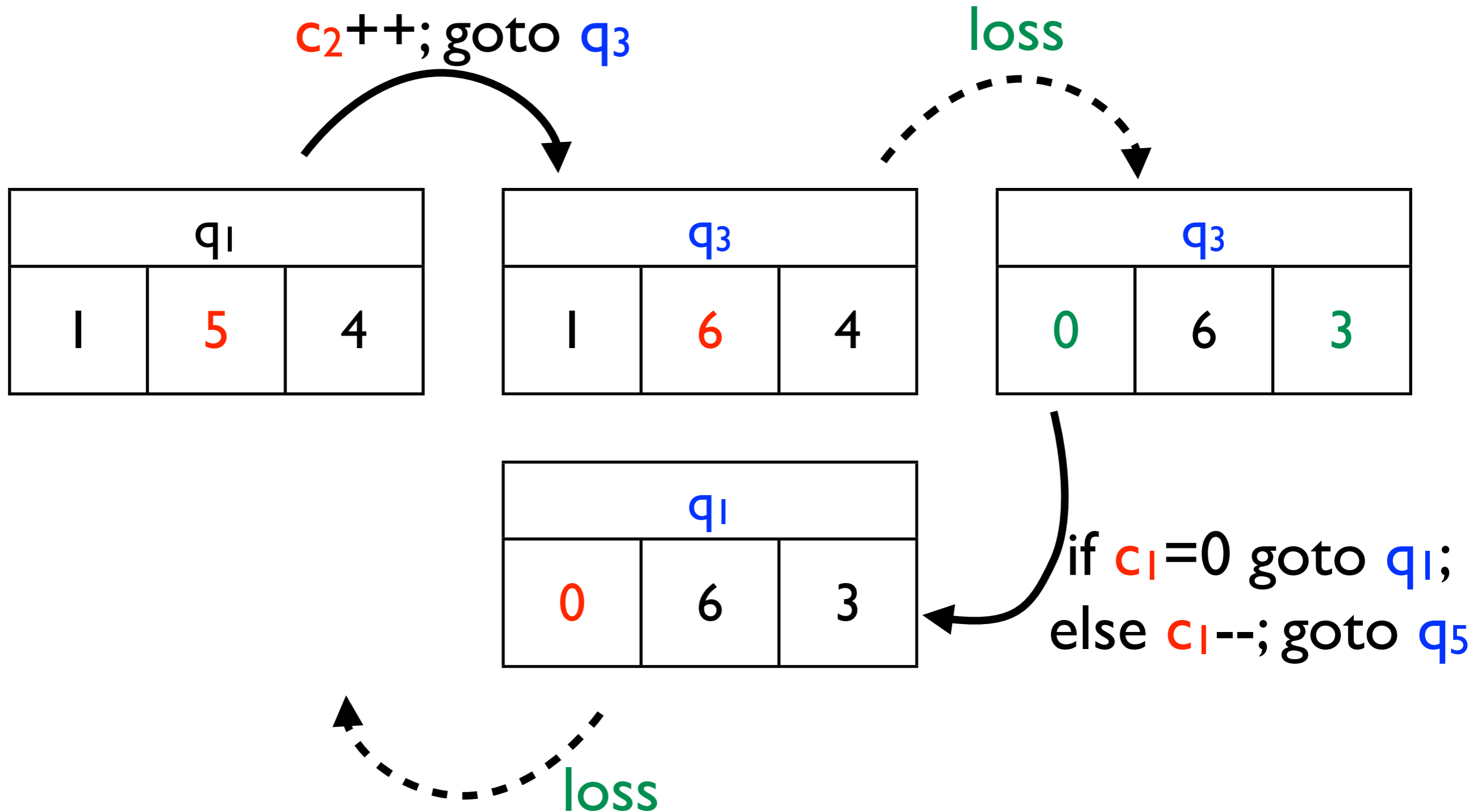
Counter machine - run



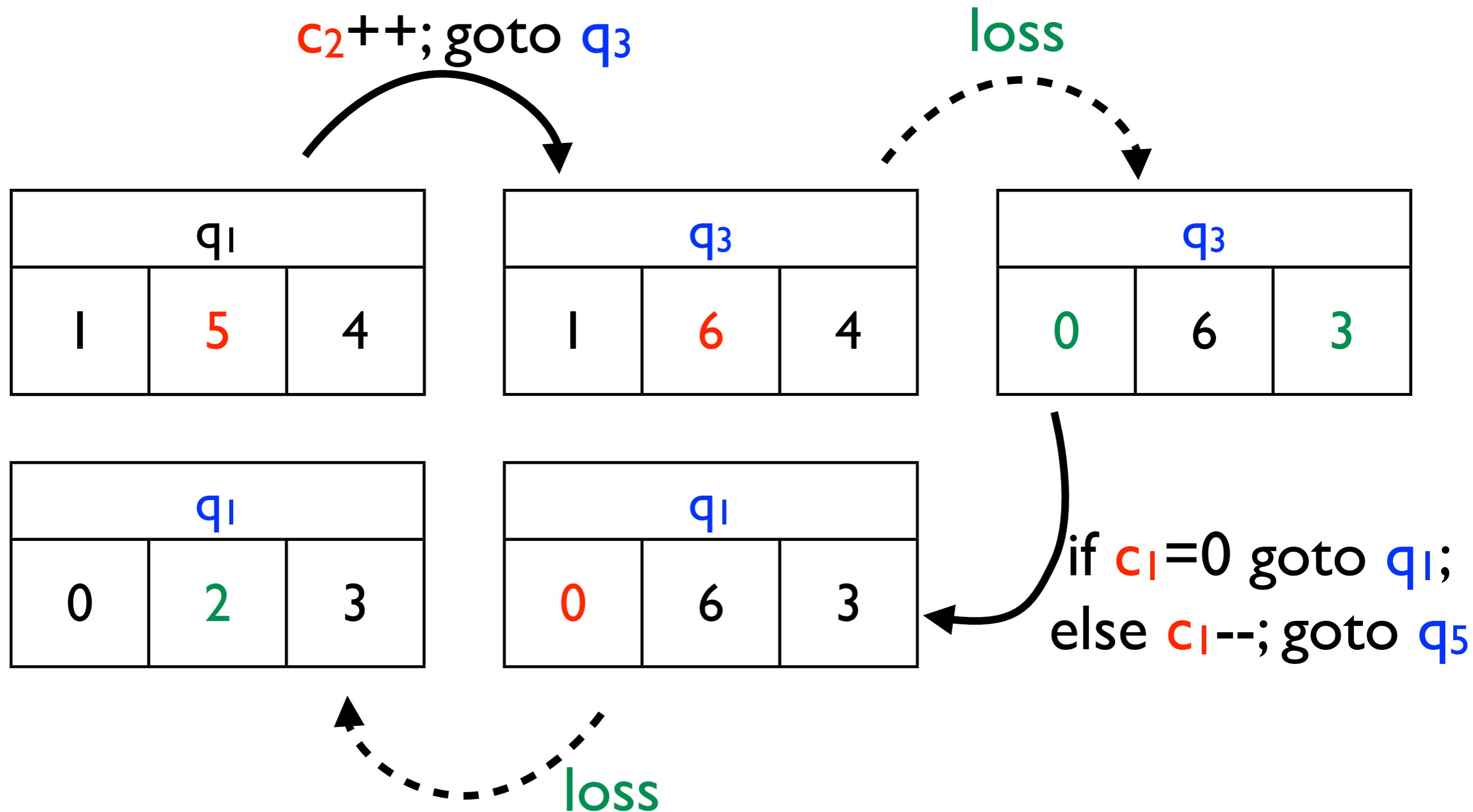
Counter machine - run



Counter machine - run



Counter machine - run



Encoding runs

9		
1	3	0



Encoding runs

9		
1	3	0

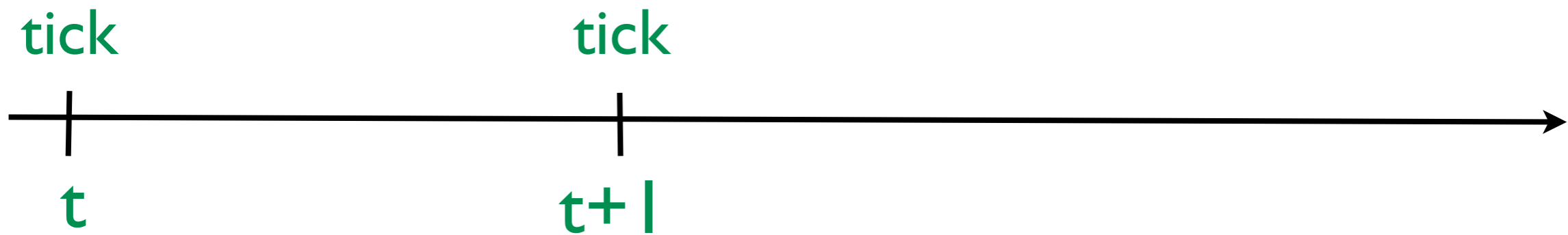
tick



t

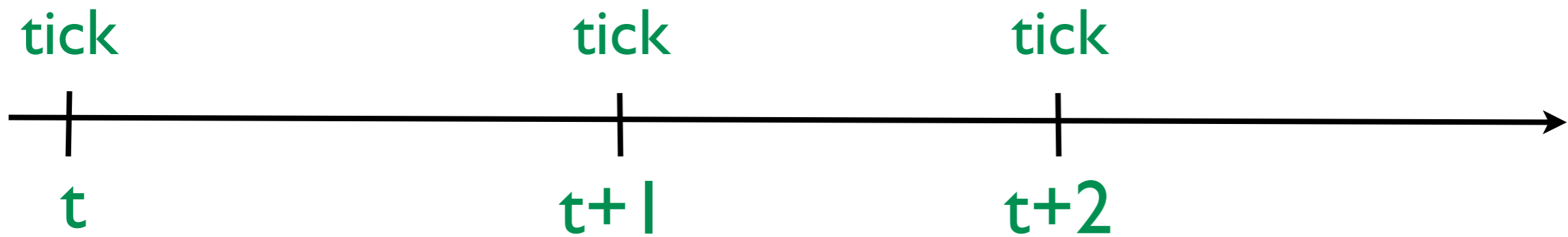
Encoding runs

9		
1	3	0



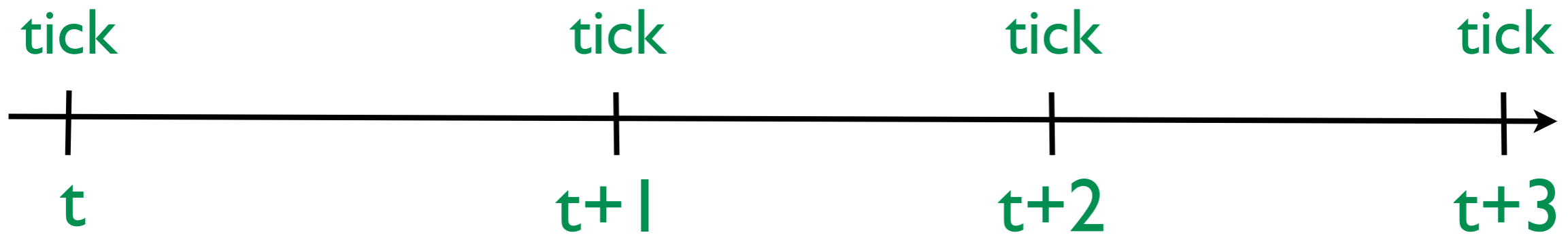
Encoding runs

9		
1	3	0



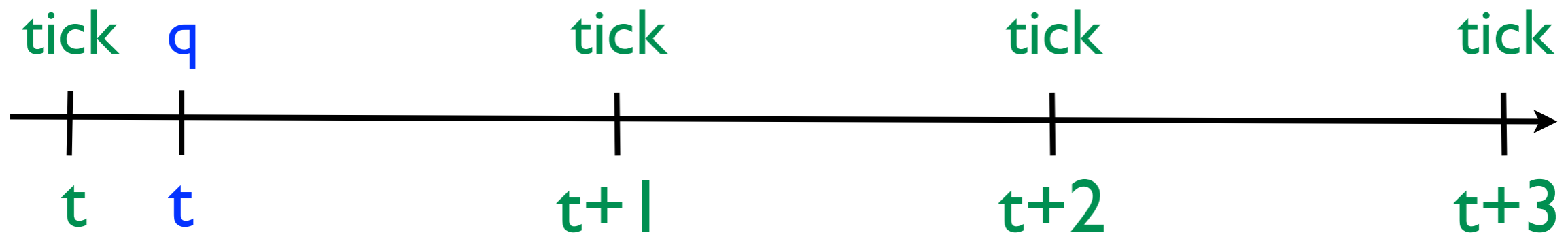
Encoding runs

9		
1	3	0



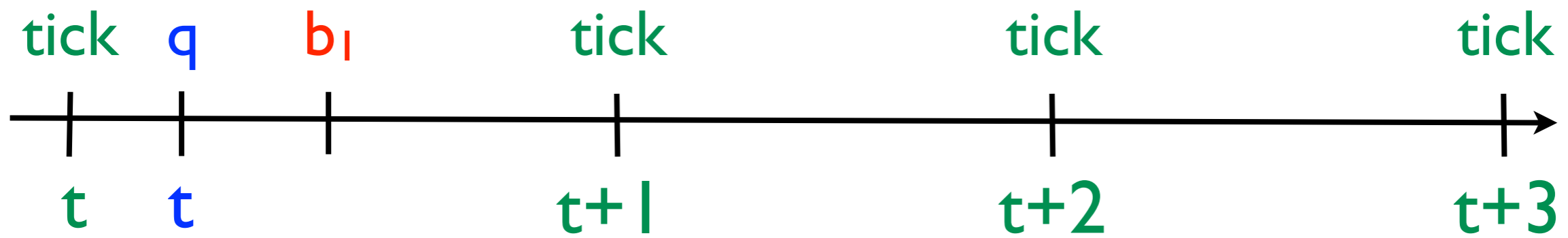
Encoding runs

q		
1	3	0



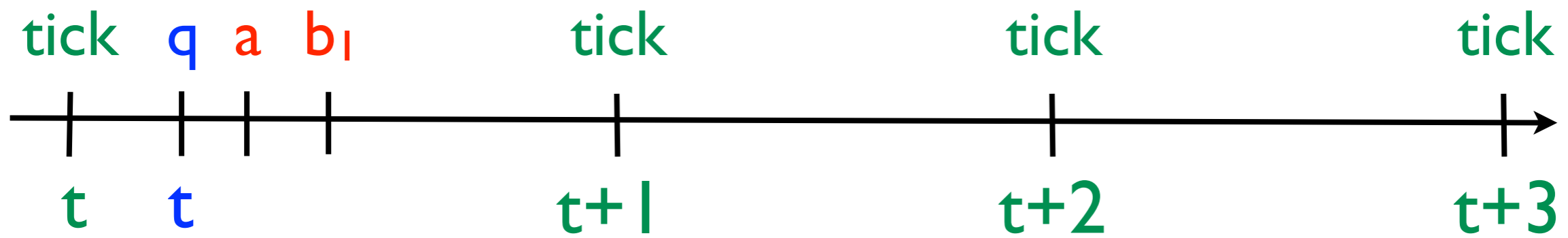
Encoding runs

q		
1	3	0



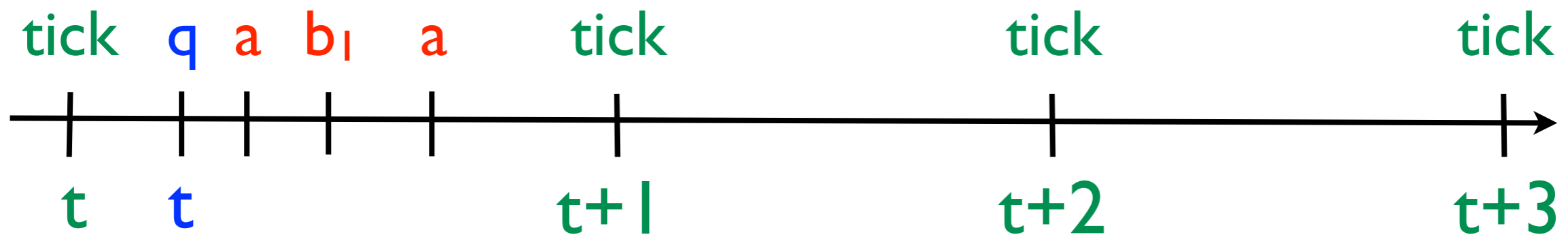
Encoding runs

q		
1	3	0



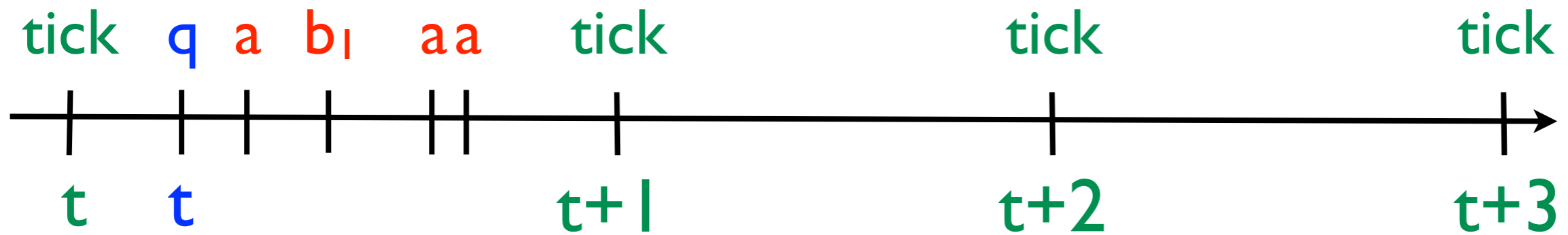
Encoding runs

q		
1	3	0



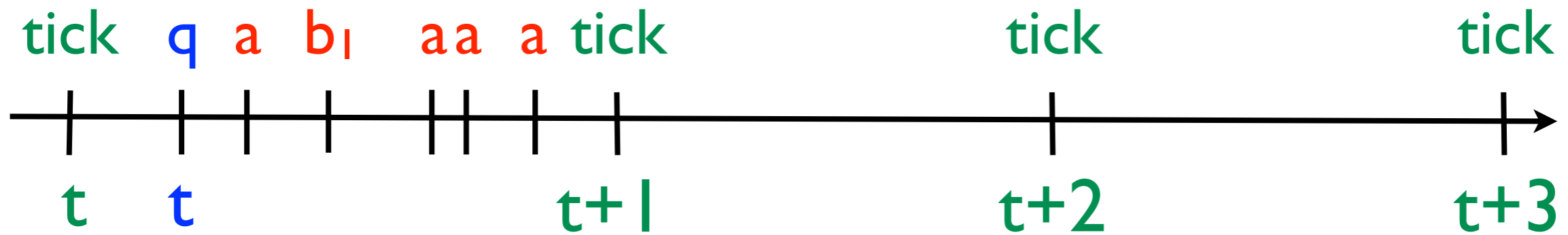
Encoding runs

q		
1	3	0



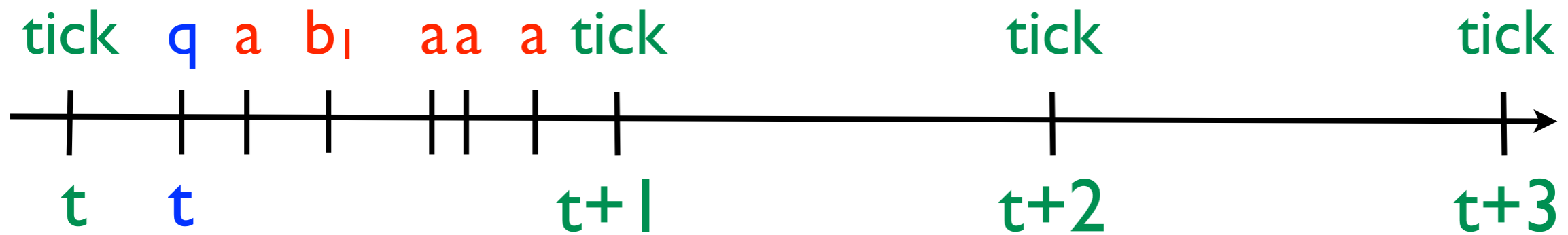
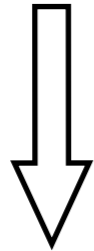
Encoding runs

q		
1	3	0



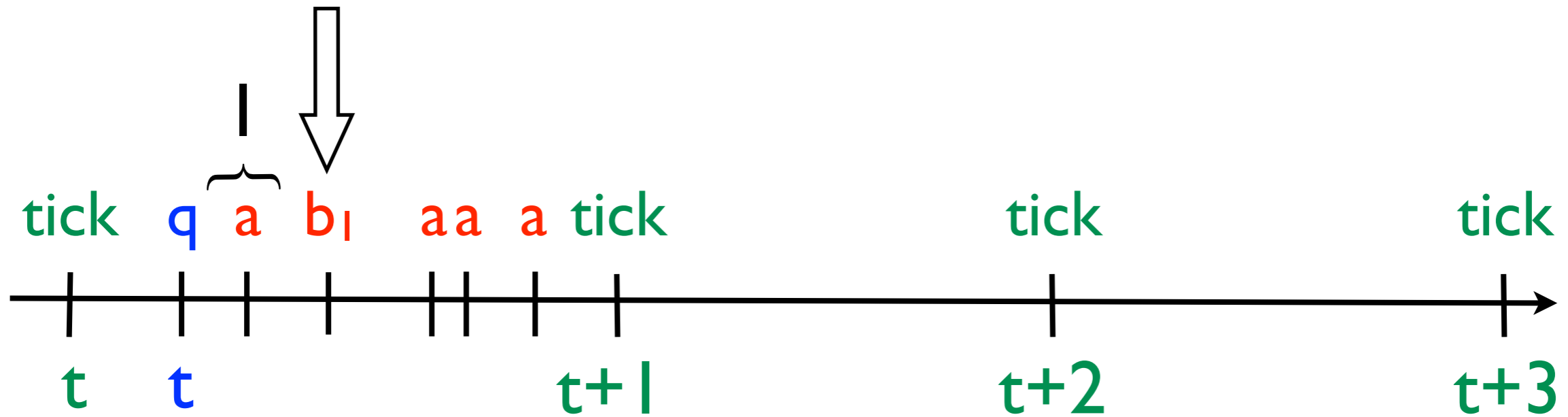
Encoding runs

q		
1	3	0

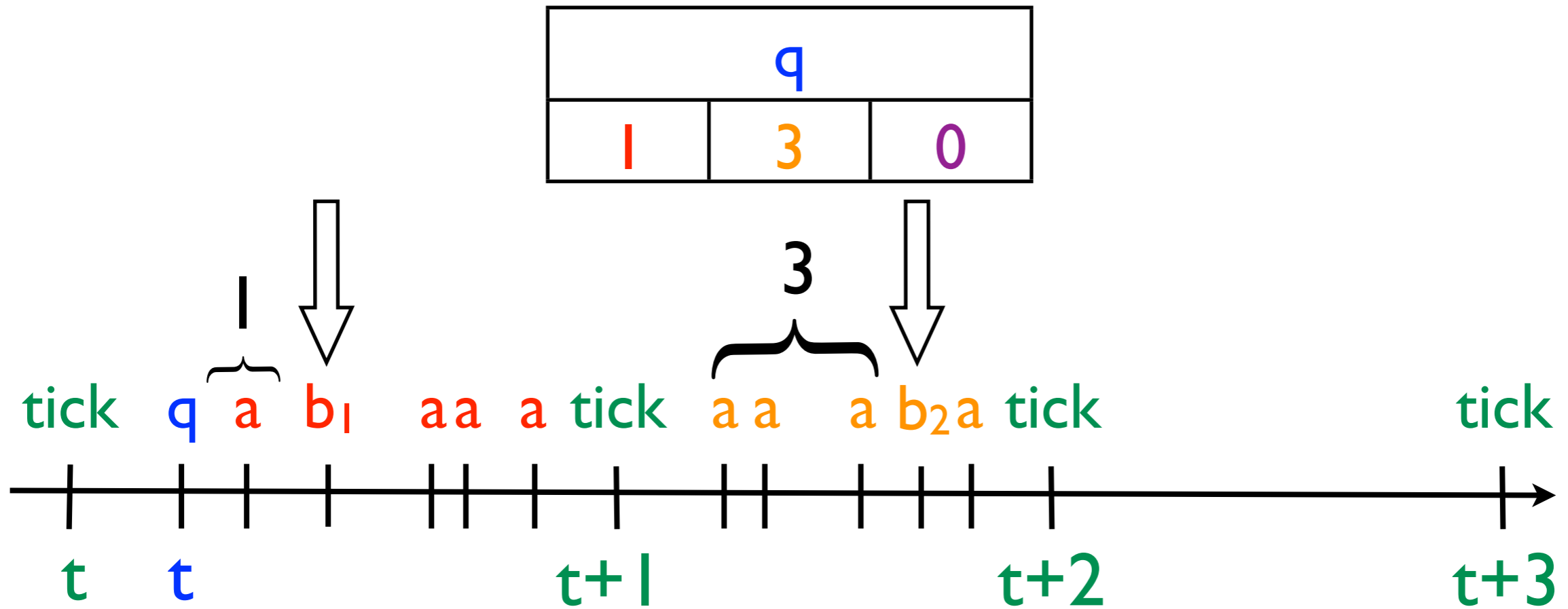


Encoding runs

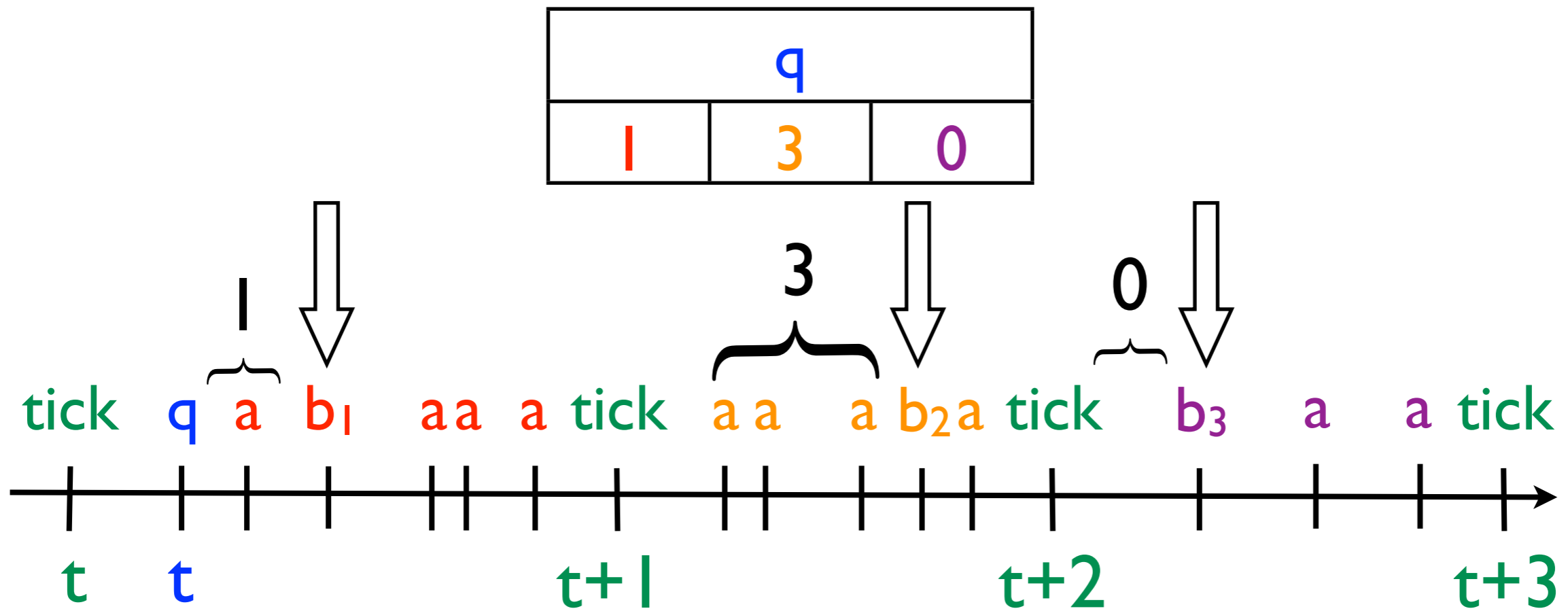
q		
1	3	0



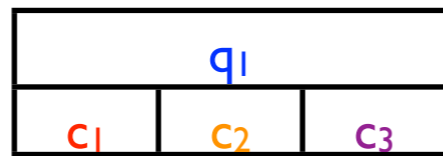
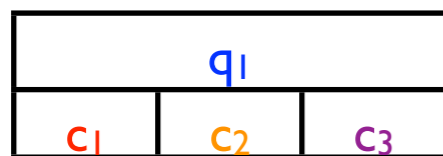
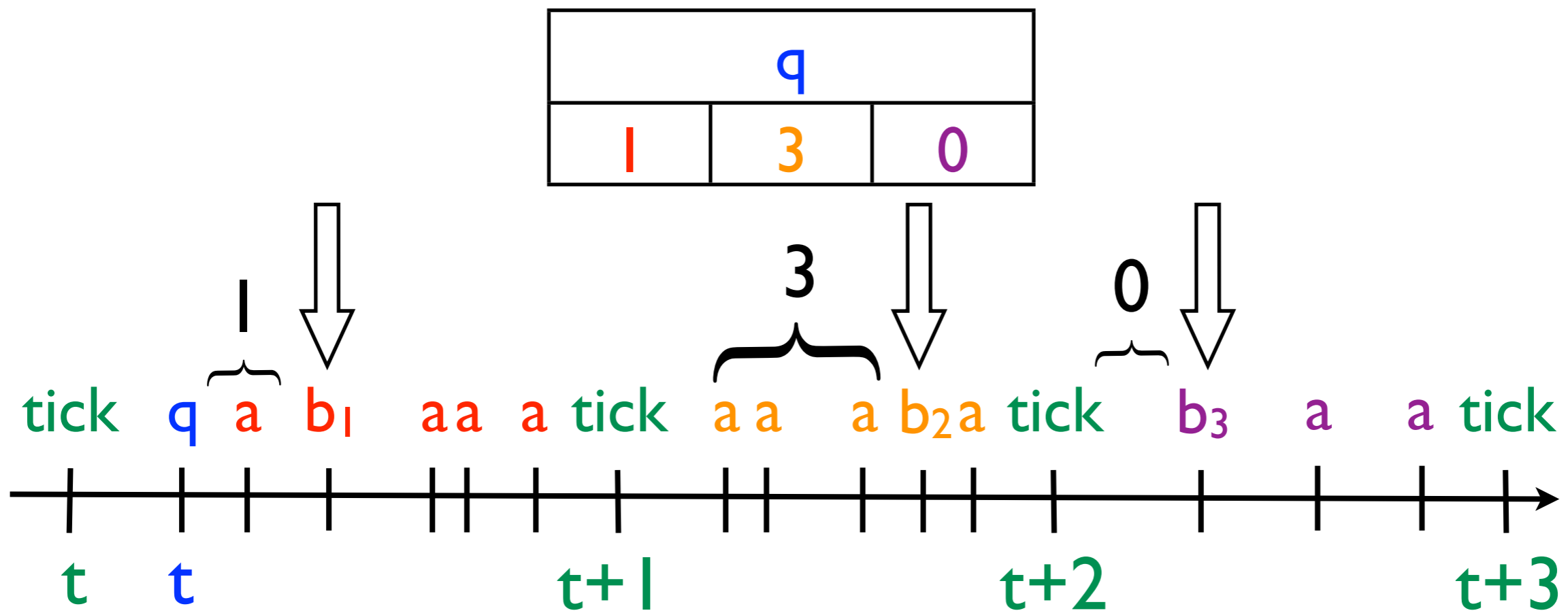
Encoding runs



Encoding runs

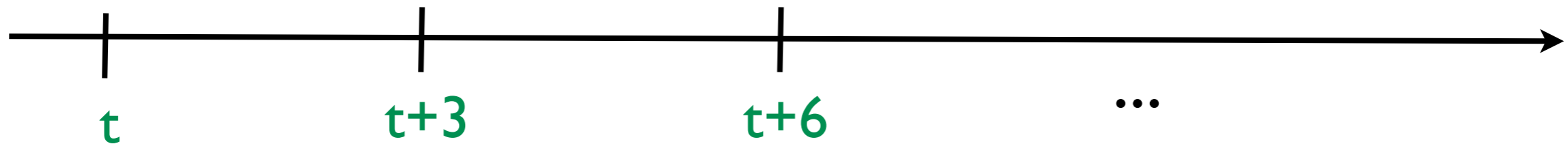
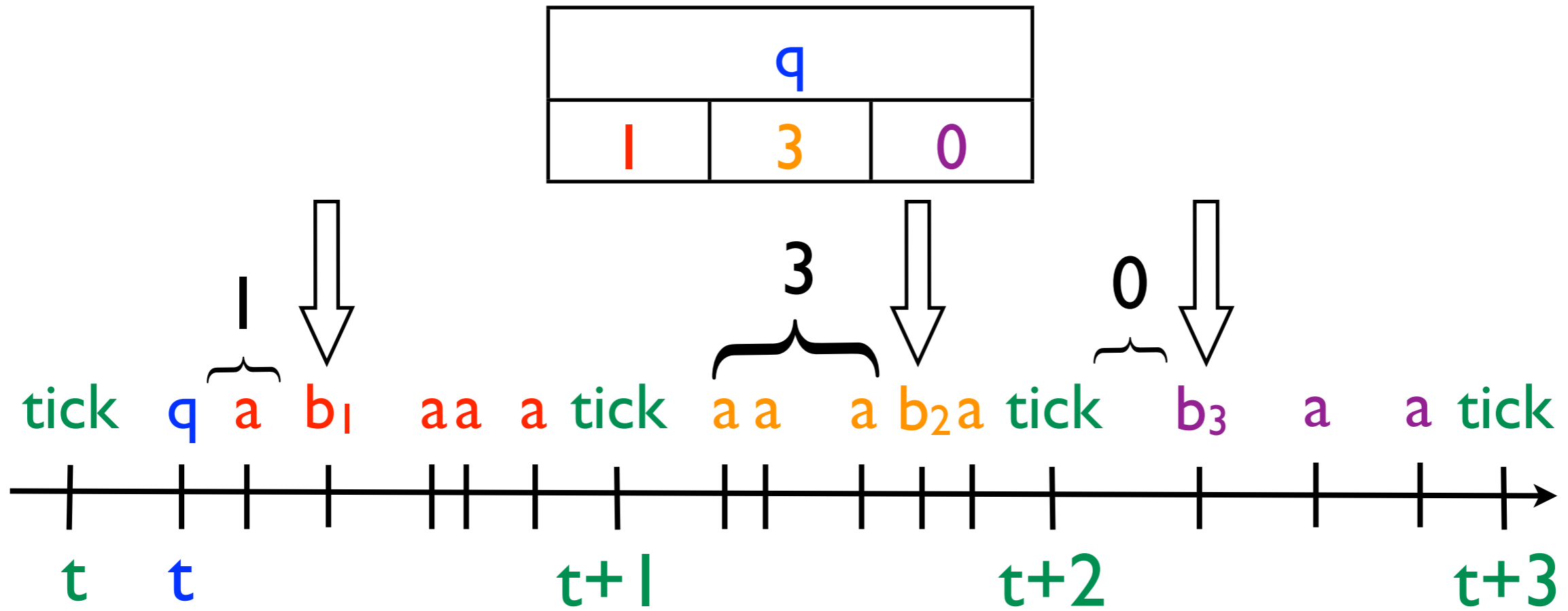


Encoding runs

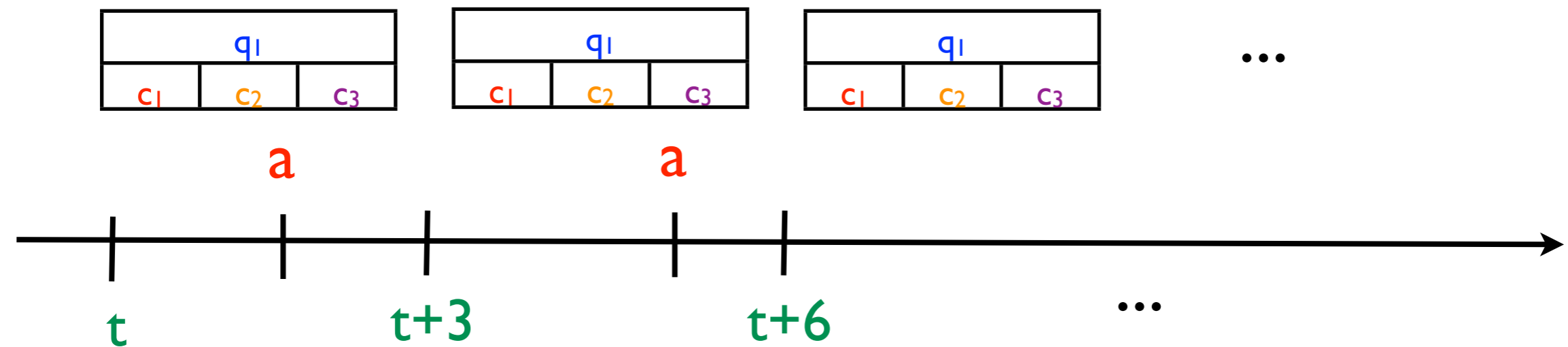
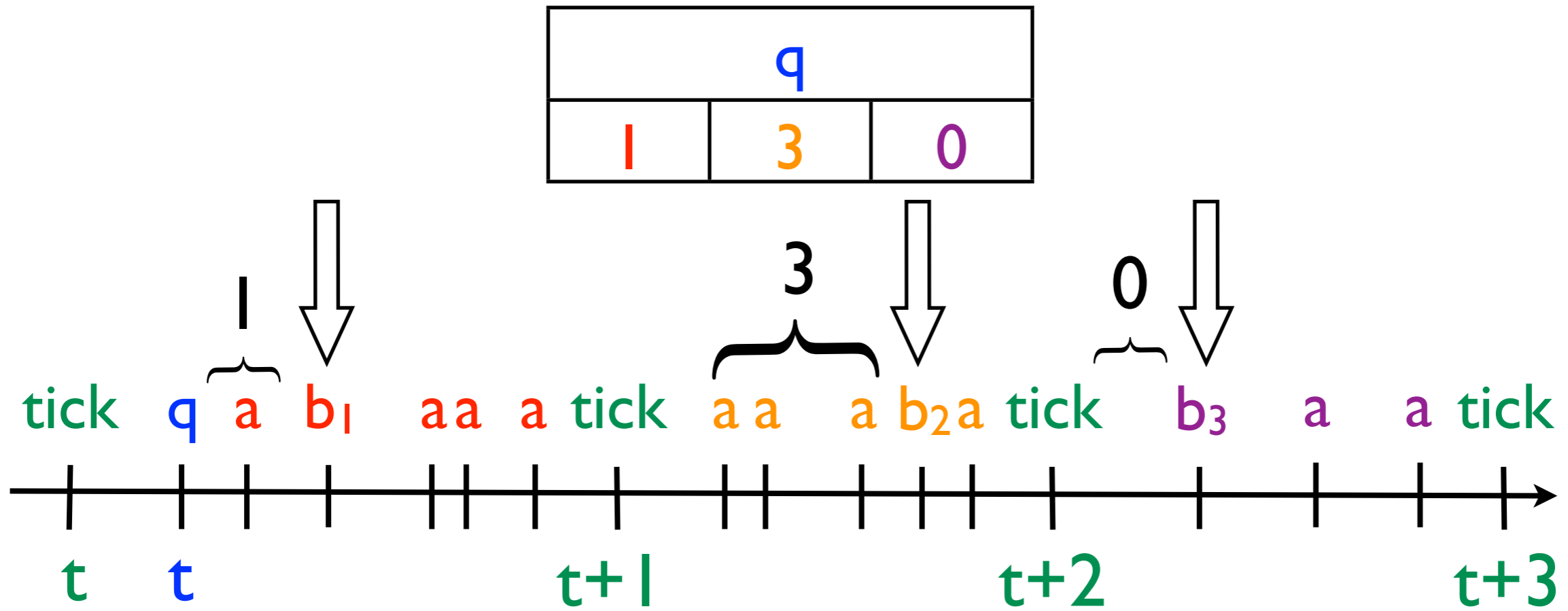


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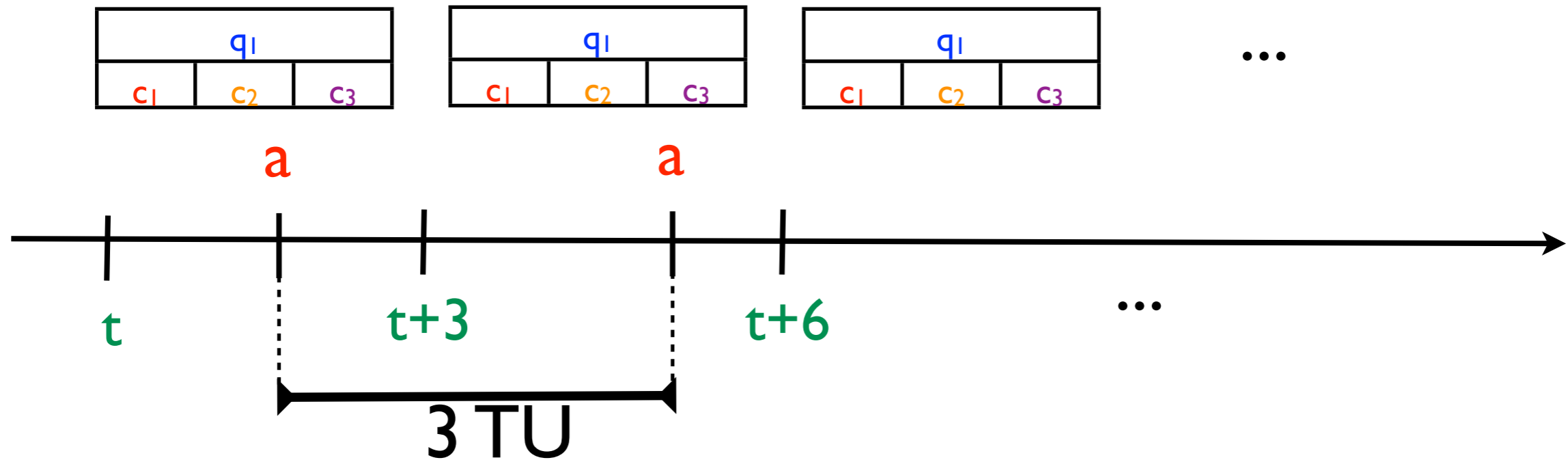
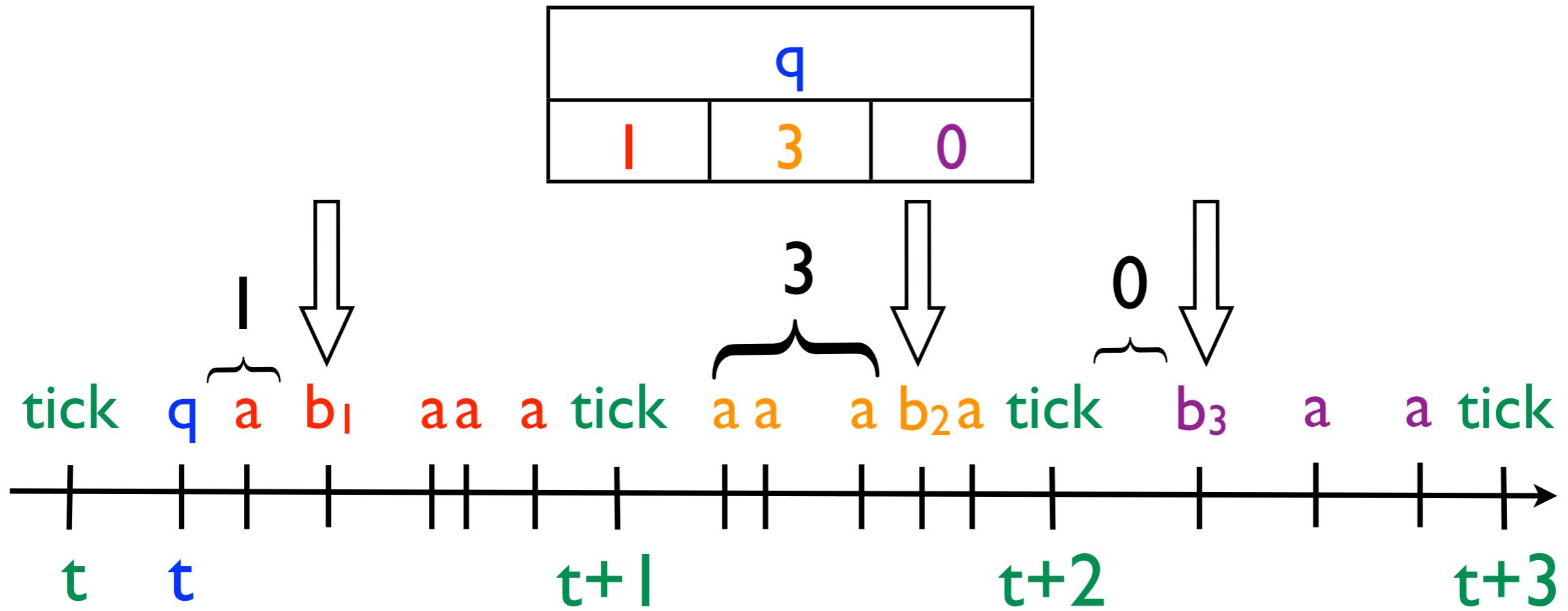
Encoding runs



Encoding runs



Encoding runs

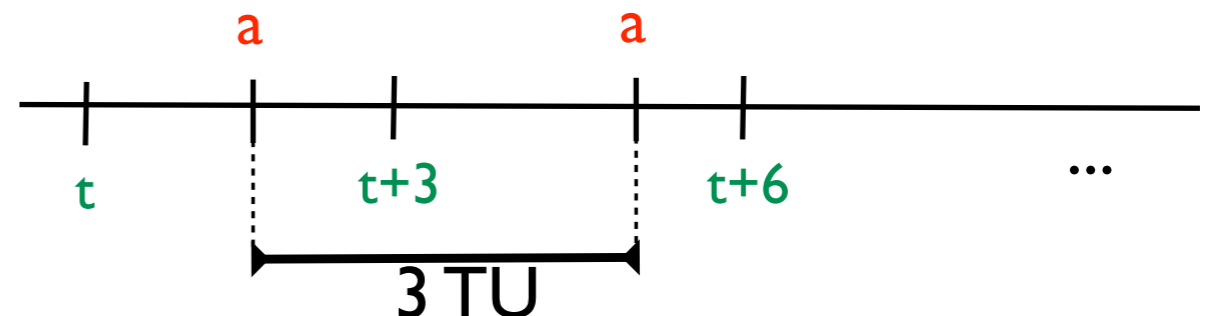


Reduction

- Given a 3CM M
- Can we devise an ECL formula φ_M s.t.

φ_M is satisfiable
iff
 M admits an infinite bounded run ?

- **NO !**
- Otherwise ECL satisfiability would be **undecidable**
- We can't use ECL to **specify** that «every a or b should be preceded by an a or b 3 T.U. before» requirement

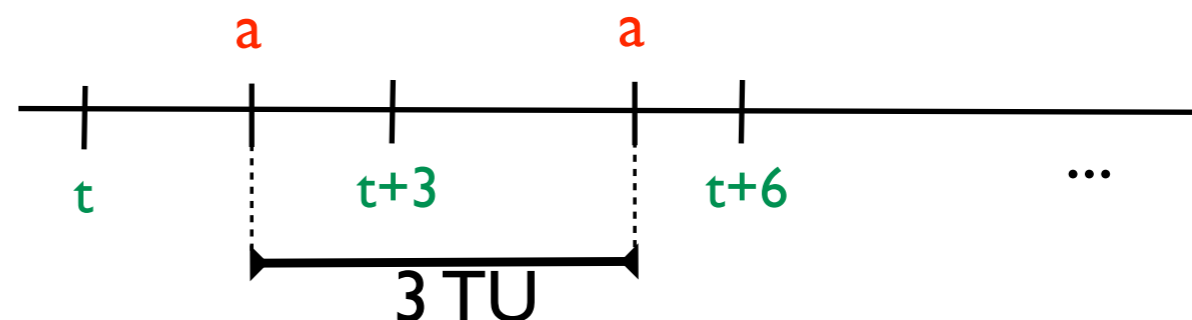


Reduction

- Given a 3CM M
- Can we devise a **timed game** $\langle \Sigma_1, \Sigma_2, \llbracket \varphi_M \rrbracket \rangle$, where φ_M is an ECL formula s.t.

Player 1 has a winning strategy
iff
 M admits an infinite bounded run ?

- **YES !**
- Player 1 controls the **encoding symbols**
- We use Player 2 as an arbiter to check that Player 1 respects:

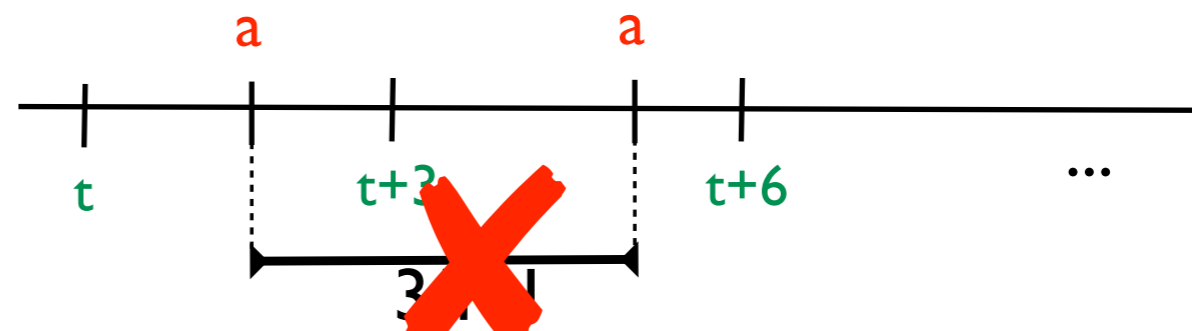


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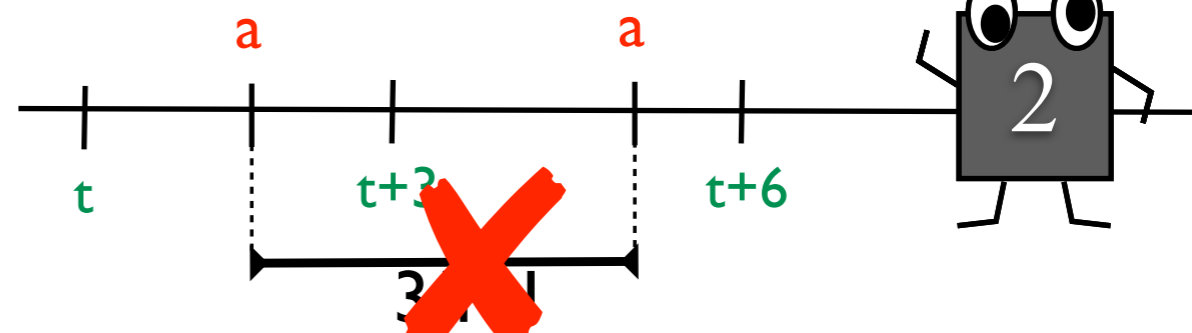


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Deterministic ?

$$\Sigma = \Sigma_1 \cup \Sigma_2$$

Spec.
 Φ
LTL \triangleleft

$$?(\Sigma_1) \parallel \text{Env}(\Sigma_2) \models \Phi$$

$\exists \lambda_1 \cdot \forall \lambda_2 \cdot \exists \text{run } r \text{ of } A_\Phi \cdot r \text{ accepts Outcome}(\lambda_1, \lambda_2)$

Remove second alternation by **determinization** of A_Φ .

$\exists \lambda_1 \cdot \forall \lambda_2 \cdot \underline{\text{unique } r \text{ of } A^d} \text{ on Outcome}(\lambda_1, \lambda_2) \text{ is accepting}$

Universal co-Büchi ERA

- Instead of considering classical Büchi condition, we will consider Universal co-Büchi condition
- Büchi = \exists a run on w that visits accepting states infinitely often
- co-Büchi = all runs on w visit accepting states finitely often
- These conditions are dual !

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φ

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$\varphi \longrightarrow$

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$$\varphi \longrightarrow \neg\varphi$$

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Then: $L_{UcoB}(A_{\neg\varphi}) = \llbracket \varphi \rrbracket$