

A Semantic PSPACE Criterion for Coalgebraic Modal Logic

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Introduction

- Modal logics (ideally) combine
 - the right (tailored) level of **expressivity**
 - relative computational **tractability**
- Large zoo of **non-normal** modal logics
- Upper complexity bounds frequently non-trivial and **ad-hoc**
- Coalgebraic modal logic provides **unifying** framework
- Here: semantic PSPACE algorithm for **rank-0-1** logics
- Applications:
 - modal logics of quantitative uncertainty
 - conditional logics

Complexity of Modal Logics

- ‘Next-step’ modal logics are typically *PSPACE*, e.g.
 - K (KB , $S4$, ...): **witness** algorithm for shallow Kripke models (Ladner 77, Halpern/Moses 92)
 - Graded modal logic (GML): constraint set algorithm (Tobies 01)
 - Logic of knowledge and probability: shallow model method based on **local small model property** (Fagin/Halpern 94)
 - **Epistemic logic (Vardi 89)**, coalition logic (Pauly 02): shallow neighbourhood models.
 - Conditional logic: sequent calculus (Olivetti/Schwindt 01)
 - Presburger and regular modal logic: check local models **on the fly** (Demri/Lugiez IJCAR 06).

Coalgebraic Modal Logic

Coalgebraic modal logic **unifies** all these different logics

- Prove meta-theoretic results in the general framework:
 - Hennessy-Milner [Pattinson NDJFL 04, Schröder FOSSACS 05]
 - Completeness [Pattinson TCS 03, Schröder FOSSACS 06]
 - Duality, ultrafilter extensions [Kupke/Kurz/Pattinson CALCO 05]
 - Finite model property [Schröder FOSSACS 06]
- Generic **algorithms** and upper complexity bounds:
 - Obtain *PSPACE* bounds by **uniform** methods
[Schröder/Pattinson LICS 06 and here]
 - clarity, reusability, extendability

Examples

Quantitative Uncertainty

(Fagin, Halpern, Megiddo, Pucella)

$$\phi ::= \perp \mid p \mid \neg\phi \mid \phi_1 \wedge \phi_2 \mid \sum_{i=1}^n a_i w(\phi_i) \geq b \quad (a_i, b \in \mathbb{Q})$$

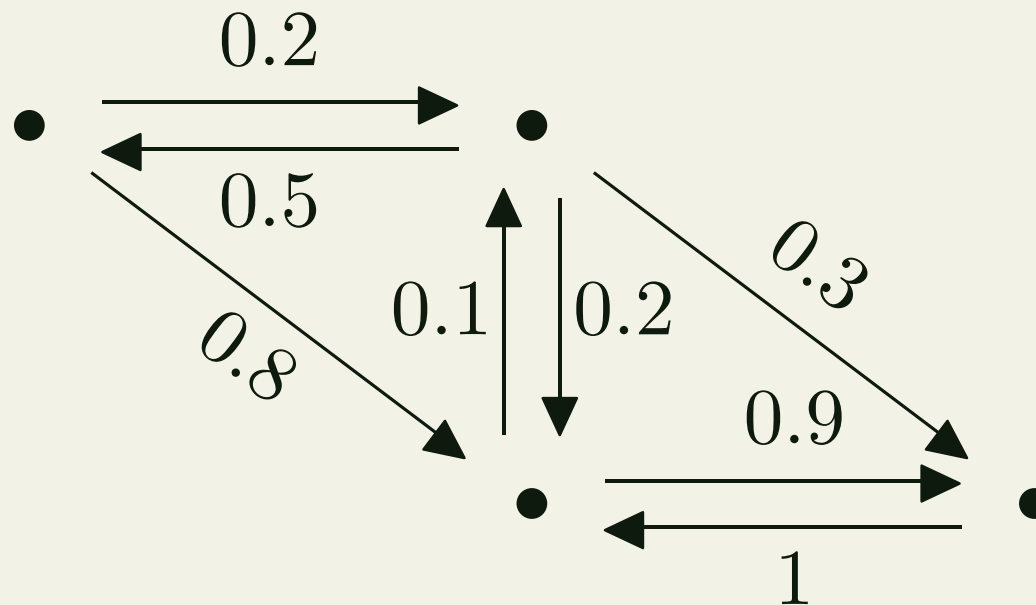
Weights $w(\phi) \in \mathbb{R}$: ‘likelihood’ of ϕ in the **next step**, e.g.

- Probability (FHM IC 1994)
- Upper probability (HP JAI 2002)
- Dempster-Shafer belief (HP UAI 2002)
- Dubois-Prade possibility (HP UAI 2002)

Extension: **Expectations** $e(\sum c_i \phi_i)$ (HP UAI 02)

Quantitative Uncertainty: Semantics

- Set X of states
- For $x \in X$, probability distribution (belief function, . . .) P_x on X describing **uncertain transitions**



- $w(\phi)$ is interpreted in state x as $P_x\{y \mid y \models \phi\}$

Conditional Logics

$$\phi ::= \perp \mid p \mid \neg\phi \mid \phi_1 \wedge \phi_2 \mid \phi_1 \Rightarrow \phi_2$$

- $\phi \Rightarrow \psi$ reads ‘ ψ holds **under condition** ϕ ’
- Basic axioms \rightsquigarrow conditional logic *CK*:
 - Replacement of equivalents on the left
 - Commutation with \wedge on the right
- Relevance logics: $a \Rightarrow a, (a \Rightarrow b) \rightarrow a \rightarrow b$
- Default logics, e.g. Burgess’ System C (generalizing KLM)
 - (REF) $a \Rightarrow a$
 - (OR) $(a \Rightarrow c) \rightarrow (b \Rightarrow c) \rightarrow (a \vee b \Rightarrow c)$
 - (CM) $(a \Rightarrow c) \rightarrow (a \Rightarrow b) \rightarrow ((a \wedge b) \Rightarrow c)$

Conditional Logic CK : Semantics

Conditional Frames:

- Set X of states
- For $x \in X$, function $f_x : \mathcal{P}(X) \rightarrow \mathcal{P}(X)$.
- $x \models \phi \Rightarrow \psi$ iff $f_x[[\phi]] \subseteq [[\psi]]$ (where $[[\phi]] = \{y \mid y \models \phi\}$)

Coalgebra

$T : \mathbf{Set} \rightarrow \mathbf{Set}$

T -Coalgebra $(X, \xi) = \text{map } \xi : X \rightarrow TX$

X : set of **states**

ξ : **transition map**

$\xi(x)$: structured collection of **observations/successor states**

Coalgebraic Modal Logic

[Pattinson NDJFL 04; Schröder FOSSACS 05]

Interpret n -ary modal operator L by **predicate lifting**

$$\llbracket L \rrbracket_X : \mathcal{Q}^n \rightarrow \mathcal{Q} \circ T^{op}$$

(\mathcal{Q} contravariant powerset).

Semantics of L in T -coalgebra (X, ξ) :

$$x \models_{(X, \xi)} L(\phi_1, \dots, \phi_n) \iff \xi(x) \in \llbracket L \rrbracket_X(\llbracket \phi_1 \rrbracket, \dots, \llbracket \phi_n \rrbracket)$$

(where $\llbracket \phi \rrbracket = \{y \mid y \models \phi\}$)

Examples

- **Quantitative Uncertainty:**

- TX = likelihood measures over X
- operators $L(a_1, \dots, a_n; b)(\phi_1, \dots, \phi_n) \equiv \sum a_i w(\phi_i) \geq b$
- $\llbracket L(a_1, \dots, a_n; b) \rrbracket_X(A_1, \dots, A_n) = \{P \in TX \mid \sum a_i P(A_i) \geq b\}$

- **Conditional Logic CK :**

- $TX = \mathcal{Q}(X) \rightarrow \mathcal{P}(X)$
- $\llbracket - \Rightarrow - \rrbracket_X(A, B) = \{f \in TX \mid f(A) \subseteq B\}$.

- **Coalition Logic, majority logic, . . .**

The One-Step Logic

No nesting, no transitions

Formally: equivalent to **one-step pairs** (ϕ, ψ) over V , where

$$\phi \in \text{Prop}(V)$$

ψ conjunctive clause over atoms $L(a_1, \dots, a_n)$, $a_i \in V$

For set X , $\mathcal{P}(X)$ -valuation τ :

- $[[\phi]]\tau \subseteq X$
- $X, \tau \models \phi \iff [[\phi]]\tau = X$
- $[[\psi]]\tau \subseteq TX$, with $[[L(a_1, \dots, a_n)]] = [[L]](\tau(a_1), \dots, \tau(a_n))$

The One-Step Polysize Model Property

One-step model (X, τ, t) of (ϕ, ψ) :

- $X, \tau \models \phi$
- $t \in \llbracket \psi \rrbracket_{\tau} \subseteq TX$

OSPMP: (ϕ, ψ) one-step satisfiable \implies
has one-step model of polynomial size **in** ψ

(**Size** refers to $|X|$ and $size(t)$)

PSPACE semantically

One-step model checking: $t \in \llbracket L \rrbracket(A_1, \dots, A_n)$?

Theorem If \mathcal{L} has the OSPMP, then \mathcal{L} has the **polynomially branching shallow model** property

Corollary If \mathcal{L} has the OSPMP and one-step model-checking is in P , then

- \mathcal{L} is in $PSPACE$
- \mathcal{L}_k (nesting of modal operators bounded by k) is in NP .

Example: Quantitative Uncertainty

- [FHM IC 1994; HP JAI 02; HP UAI 02] prove small model properties for one-step logics (\rightarrow NP)
- From these proofs, **extract** OSPMP
- Obtain polynomially branching shallow models, PSPACE/NP bounds
 - Known for probability [FHM 94]
 - Novel for other cases (only one-step logics considered so far)

Example: CK

Representation of $f : \mathcal{Q}(X) \rightarrow \mathcal{P}(X)$ by lists of maplets,
default: $f(A) = \emptyset$.

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- pick $z_i \in f(\tau(a_i)) \setminus \tau(b_i)$ if $\pm_i = \neg$;
- put $Y = \{y_{ij} \mid \dots\} \cup \{z_i \mid \dots\}$;
- put $\tau'(v) = \tau(v) \cap Y$, $f : \tau'(a_i) \mapsto f(\tau(a_i)) \cap Y$

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→ have **polysize one-step model** (Y, τ', f') , **DONE!**

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(Olivetti et al. ACM TOCL: sequent calculus, 51 pages)

Rank-0-1 Logics

- **Rank-0-1 axioms**: clauses over atoms a or $L(a_1, \dots, a_n)$.
- **Models**: coalgebras satisfying the axioms for all valuations
- **Examples**:
 - KT: $\Box a \rightarrow a$, models: reflexive frames
 - Almost all conditional logics, e.g. CK+MP:

$$(a \Rightarrow b) \rightarrow a \rightarrow b,$$

$$\text{models: } x \in A \implies x \in f_x(A).$$

One-Step Models in Rank-0-1

... are quadruples (X, τ, t, x_0) , where $x_0 \in X$ **present state**

Require that (X, t, x_0) satisfies the axioms for all valuations:

- $(X, \kappa, t, x_0) \models L(a_1, \dots, a_n)$ defined as before
- $(X, \kappa, t, x_0) \models a$ iff $x \in \kappa(a)$

OSPMP:

- Require preservation of τ -theory of x_0 in small model.
- Represent **pairs** $(t, x) \in TX \times X$.

For PSPACE, need 'Is (X, τ, t, x_0) one-step model?' $\in P$.

Example: CK+MP

Everything as for CK, except

- **Default** $f(A) = A \cap \{x_0\}$
- retain x_0 in small one-step model

Conclusion

- Coalgebraic modal logic subsumes ‘all’ modal logics
- Generic algorithms reproduce tight PSPACE bounds and prove new ones
 - Compact, reusable, and clear proofs
- Bounding the nesting depth reduces complexity to NP
- Can now handle all axioms without nested modalities

Future Work

- Coalgebraic CTL
 - Coalgebra automata (Kupke/Venema)? :-|
 - **Pseudomodels** (Emerson/Halpern) :-|
- How do we tackle **rank n** ?
- Optimized automatic reasoners?

Coalition Logic

(Pauly 2002)

$$TX = \exists \overbrace{\Sigma_1 \dots \Sigma_n}^{\text{sets of strategies}} \cdot \underbrace{\prod \Sigma_i \rightarrow X}_{\text{outcome function}},$$

where $N = \{1, \dots, n\}$ set of **agents**.

For **coalition** $C \subset N$, $[C]\phi = 'C \text{ can force } \phi'$.

$$\llbracket [C] \rrbracket_X A = \{f : \prod \Sigma_i \rightarrow X \mid \exists \sigma_C. \forall \sigma_{N-C}. f(\sigma_C, \sigma_{N-C}) \in A\}.$$