

Algebraic type systems

<work-in-progress>

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The calculus

A straight extension of System F

The Scalar Type System

The Additive Type System

The Vectorial Type System

Orthogonality

Summary

Higher-order computation

$\mathbf{t}, \mathbf{r}, \mathbf{s} := x \mid \lambda x. \mathbf{t} \mid (\mathbf{t}) \mathbf{r}$

▶ $(\lambda x. \mathbf{t}) \mathbf{b} \rightarrow \mathbf{t}[\mathbf{b}/x]$

\mathbf{b} an abstraction or a variable.

Linear algebra

$\mathbf{t} + \mathbf{r} \mid \alpha. \mathbf{t} \mid \mathbf{0}$

$\alpha \in (\mathcal{S}, +, \times)$
commutative ring

- ▶ Elementary rules such as $\mathbf{u} + \mathbf{0} \rightarrow \mathbf{u}$ and $\alpha.(\mathbf{u} + \mathbf{v}) \rightarrow \alpha. \mathbf{u} + \alpha. \mathbf{v}$.
- ▶ Factorisation rules such as $\alpha. \mathbf{u} + \beta. \mathbf{u} \rightarrow (\alpha + \beta). \mathbf{u}$.
- ▶ Application rules such as $\mathbf{u} (\mathbf{v} + \mathbf{w}) \rightarrow (\mathbf{u} \mathbf{v}) + (\mathbf{u} \mathbf{w})$.

Higher-order computation

$\mathbf{t}, \mathbf{r}, \mathbf{s} := x \mid \lambda x. \mathbf{t} \mid (\mathbf{t}) \mathbf{r}$

▶ $(\lambda x. \mathbf{t}) \mathbf{b} \rightarrow \mathbf{t}[\mathbf{b}/x]$

\mathbf{b} an abstraction or a variable.

$$(\lambda x. (x) x) (y + z) \rightarrow^*$$

$$(\lambda x. (x) x) y + (\lambda x. (x) x) z \rightarrow^*$$

$$(y) y + (z) z$$

$$(\lambda x. (x) x) (y + z) \rightarrow^* (y + z) (y + z) \rightarrow^*$$

$$(y) y + (y) z + (z) y + (z) z$$

Linear algebra

$\mathbf{t} + \mathbf{r} \mid \alpha. \mathbf{t} \mid \mathbf{0}$

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- ▶ Elementary rules such as $\mathbf{u} + \mathbf{0} \rightarrow \mathbf{u}$ and $\alpha. (\mathbf{u} + \mathbf{v}) \rightarrow \alpha. \mathbf{u} + \alpha. \mathbf{v}$.
- ▶ Factorisation rules such as $\alpha. \mathbf{u} + \beta. \mathbf{u} \rightarrow (\alpha + \beta). \mathbf{u}$.
- ▶ Application rules such as $\mathbf{u} (\mathbf{v} + \mathbf{w}) \rightarrow (\mathbf{u} \mathbf{v}) + (\mathbf{u} \mathbf{w})$.

Higher-order computation

$\mathbf{t}, \mathbf{r}, \mathbf{s} := x \mid \lambda x. \mathbf{t} \mid (\mathbf{t}) \mathbf{r}$

▶ $(\lambda x. \mathbf{t}) \mathbf{b} \rightarrow \mathbf{t}[\mathbf{b}/x]$

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$$\begin{aligned} (\lambda x. (x) x) (y + z) &\rightarrow^* \\ (\lambda x. (x) x) y + (\lambda x. (x) x) z &\rightarrow^* \\ (y) y + (z) z & \end{aligned}$$

$$\begin{aligned} (\lambda x. (x) x) (y + z) &\rightarrow^* (y + z) (y + z) \rightarrow^* \\ (y) y + (y) z + (z) y + (z) z & \end{aligned}$$

Linear algebra

$\mathbf{t} + \mathbf{r} \mid \alpha. \mathbf{t} \mid \mathbf{0}$

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- ▶ Elementary rules such as $\mathbf{u} + \mathbf{0} \rightarrow \mathbf{u}$ and $\alpha. (\mathbf{u} + \mathbf{v}) \rightarrow \alpha. \mathbf{u} + \alpha. \mathbf{v}$.
- ▶ Factorisation rules such as $\alpha. \mathbf{u} + \beta. \mathbf{u} \rightarrow (\alpha + \beta). \mathbf{u}$.
- ▶ Application rules such as $\mathbf{u} (\mathbf{v} + \mathbf{w}) \rightarrow (\mathbf{u} \mathbf{v}) + (\mathbf{u} \mathbf{w})$.

Challenge: Type it!

A straight extension of System F ($\lambda 2^{la}$) [Arrighi, Díaz-Caro 2009]

$$\frac{}{\Gamma, x:U \vdash x:U} \text{ax} \quad \frac{\Gamma \vdash t:U \rightarrow T \quad \Gamma \vdash r:U}{\Gamma \vdash (t) r:T} \rightarrow_E \quad \frac{\Gamma, x:U \vdash t:T}{\Gamma \vdash \lambda x.t:U \rightarrow T} \rightarrow_I$$

$$\frac{\Gamma \vdash t:\forall X.T}{\Gamma \vdash t:T[U/X]} \forall_E \quad \frac{\Gamma \vdash t:T \quad x \notin FV(\Gamma)}{\Gamma \vdash t:\forall X.T} \forall_I$$

$$\frac{}{\Gamma \vdash 0:T} \text{ax}_0 \quad \frac{\Gamma \vdash t:T \quad \Gamma \vdash r:T}{\Gamma \vdash t+r:T} +_I \quad \frac{\Gamma \vdash t:T}{\Gamma \vdash \alpha.t:T} \alpha_I$$

A straight extension of System F ($\lambda 2^{/a}$) [Arrighi, Díaz-Caro 2009]

$$\frac{}{\Gamma, x: U \vdash x: U} \text{ax} \quad \frac{\Gamma \vdash t: U \rightarrow T \quad \Gamma \vdash r: U}{\Gamma \vdash (t) r: T} \rightarrow_E \quad \frac{\Gamma, x: U \vdash t: T}{\Gamma \vdash \lambda x. t: U \rightarrow T} \rightarrow_I$$

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$$\frac{}{\Gamma \vdash 0: T} \text{ax}_0 \quad \frac{\Gamma \vdash t: T \quad \Gamma \vdash r: T}{\Gamma \vdash t + r: T} +_I \quad \frac{\Gamma \vdash t: T}{\Gamma \vdash \alpha. t: T} \alpha_I$$

Strengths

- ▶ Simple
- ▶ Strong normalization: straight

A straight extension of System F ($\lambda 2^{1a}$) [Arrighi, Díaz-Caro 2009]

$$\frac{}{\Gamma, x: U \vdash x: U} \text{ax} \quad \frac{\Gamma \vdash t: U \rightarrow T \quad \Gamma \vdash r: U}{\Gamma \vdash (t) r: T} \rightarrow_E \quad \frac{\Gamma, x: U \vdash t: T}{\Gamma \vdash \lambda x. t: U \rightarrow T} \rightarrow_I$$

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Strengths

- ▶ Simple
- ▶ Strong normalization: straight

Weaknesses

- ▶ Too restrictive
- ▶ Algebraic features not reflected in types

The Scalar Type System [Arrighi, Díaz-Caro 2009]

$$T, R, S := U \mid \forall X. T \mid \alpha. T \mid \bar{0}$$
$$U, V, W := X \mid U \rightarrow T \mid \forall X. U$$

The Scalar Type System [Arrighi, Díaz-Caro 2009]

$$\begin{array}{lll} T, R, S := U \mid \forall X. T \mid \alpha. T \mid \bar{0} & \alpha. \bar{0} \equiv \bar{0} & \alpha. (\beta. T) \equiv (\alpha \times \beta). T \\ U, V, W := X \mid U \rightarrow T \mid \forall X. U & 0. T \equiv \bar{0} & \forall X. \alpha. T \equiv \alpha. \forall X. T \\ & 1. T \equiv T & \end{array}$$

The Scalar Type System [Arrighi, Díaz-Caro 2009]

$$\begin{array}{l}
 T, R, S := U \mid \forall X. T \mid \alpha. T \mid \bar{0} \quad \alpha.\bar{0} \equiv \bar{0} \quad \alpha.(\beta.T) \equiv (\alpha \times \beta).T \\
 U, V, W := X \mid U \rightarrow T \mid \forall X. U \quad 0.T \equiv \bar{0} \quad \forall X. \alpha.T \equiv \alpha.\forall X.T \\
 1.T \equiv T
 \end{array}$$

$$\frac{}{\Gamma, x: U \vdash x: U} \text{ax} \quad \frac{\Gamma \vdash \mathbf{t}: \alpha.(U \rightarrow T) \quad \Gamma \vdash \mathbf{r}: \beta.U}{\Gamma \vdash (\mathbf{t}) \mathbf{r}: (\alpha \times \beta).T} \rightarrow_E \quad \frac{\Gamma, x: U \vdash \mathbf{t}: T}{\Gamma \vdash \lambda x. \mathbf{t}: U \rightarrow T} \rightarrow_I$$

$$\frac{\Gamma \vdash \mathbf{t}: \forall X. T}{\Gamma \vdash \mathbf{t}: T[U/X]} \forall_E \quad \frac{\Gamma \vdash \mathbf{t}: T \quad x \notin FV(\Gamma)}{\Gamma \vdash \mathbf{t}: \forall X. T} \forall_I \quad \frac{\Gamma \vdash \mathbf{t}: T \quad T \equiv R}{\Gamma \vdash \mathbf{t}: R} \equiv$$

$$\frac{}{\Gamma \vdash \mathbf{0}: \bar{0}} \text{ax}_0 \quad \frac{\Gamma \vdash \mathbf{t}: \alpha.T \quad \Gamma \vdash \mathbf{r}: \beta.T}{\Gamma \vdash \mathbf{t} + \mathbf{r}: (\alpha + \beta).T} +_I \quad \frac{\Gamma \vdash \mathbf{t}: T}{\Gamma \vdash \alpha.\mathbf{t}: \alpha.T} \alpha_I$$

The Scalar Type System [Arrighi, Díaz-Caro 2009]

Properties

- ▶ Strong normalization (re-using proof of $\lambda 2^{1a}$)
- ▶ Subject reduction
- ▶ Accounting for scalars

Possible application: A barycentric λ -calculus (\mathfrak{B}):

- ▶ Take scalars in \mathbb{R}
- ▶ Contexts with only \mathcal{C} (classical types)
- ▶ \forall_E : only for \mathcal{C}

Theorem

If $\Gamma \vdash t : \mathcal{C}$, then t reduces to a barycentric term.

The Scalar Type System [Arrighi, Díaz-Caro 2009]

Properties

- ▶ Strong normalization (re-using proof of $\lambda 2^{1a}$)
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Possible application: A barycentric λ -calculus (\mathfrak{B}):

- ▶ Take scalars in \mathbb{R}
- ▶ Contexts with only \mathcal{C} (classical types)
- ▶ \forall_E : only for \mathcal{C}

Theorem

If $\Gamma \vdash \mathbf{t} : \mathcal{C}$, then \mathbf{t} reduces to a barycentric term.

Weakness: Still too restrictive!

- ▶ $\Gamma \vdash \mathbf{t} + \mathbf{r} : T$ implies \mathbf{t} and \mathbf{r} have the same type (up to scalars)

The Additive Type System [Díaz-Caro, Petit 2010]

Simplifying the language: Removing scalars

Higher-order computation

$\mathbf{t}, \mathbf{r}, \mathbf{s} := x \mid \lambda x. \mathbf{t} \mid (\mathbf{t}) \mathbf{r}$

▶ $(\lambda x. \mathbf{t}) \mathbf{b} \rightarrow \mathbf{t}[\mathbf{b}/x]$

\mathbf{b} an abstraction or a variable.

Linear algebra

$\mathbf{t} + \mathbf{r} \mid \mathbf{0}$

▶ Elementary rule:

$\mathbf{t} + \mathbf{0} \rightarrow \mathbf{t}$.

▶ Application rules:

$(\mathbf{t} + \mathbf{r}) \mathbf{s} \rightarrow (\mathbf{t}) \mathbf{s} + (\mathbf{r}) \mathbf{s}$

$(\mathbf{t}) (\mathbf{r} + \mathbf{s}) \rightarrow (\mathbf{t}) \mathbf{r} + (\mathbf{t}) \mathbf{s}$

$(\mathbf{0}) \mathbf{t} \rightarrow \mathbf{0}$

$(\mathbf{t}) \mathbf{0} \rightarrow \mathbf{0}$

▶ AC equivalences

$\mathbf{t} + \mathbf{r} \equiv \mathbf{r} + \mathbf{t}$

$\mathbf{t} + (\mathbf{r} + \mathbf{s}) \equiv (\mathbf{t} + \mathbf{r}) + \mathbf{s}$

The Additive Type System [Díaz-Caro, Petit 2010]

$$T, R, S := U \mid T + R \mid \bar{0}$$
$$U, V, W := X \mid U \rightarrow T \mid \forall X. U$$

The Additive Type System [Díaz-Caro, Petit 2010]

$$\begin{array}{l} T, R, S := U \mid T + R \mid \bar{0} \\ U, V, W := X \mid U \rightarrow T \mid \forall X.U \end{array} \quad \begin{array}{l} T + \bar{0} \equiv T \quad T + R \equiv R + T \\ (T + R) + S \equiv T + (R + S) \end{array}$$

The Additive Type System [Díaz-Caro, Petit 2010]

$$\begin{array}{l}
 T, R, S := U \mid T + R \mid \bar{0} \quad T + \bar{0} \equiv T \quad T + R \equiv R + T \\
 U, V, W := X \mid U \rightarrow T \mid \forall X. U \quad (T + R) + S \equiv T + (R + S)
 \end{array}$$

$$\frac{\Gamma \vdash \mathbf{t}: \sum_{i=1}^{\alpha} (U \rightarrow T_i) \quad \Gamma \vdash \mathbf{r}: \sum_{j=1}^{\beta} U}{\Gamma \vdash (\mathbf{t}) \mathbf{r}: \sum_{i=1}^{\alpha} \sum_{j=1}^{\beta} T_i} \rightarrow_E \quad \frac{\Gamma, x: U \vdash \mathbf{t}: T}{\Gamma \vdash \lambda x. \mathbf{t}: U \rightarrow T} \rightarrow_I$$

$$\frac{\Gamma \vdash \mathbf{t}: \forall X. T}{\Gamma \vdash \mathbf{t}: T[U/X]} \forall_E \quad \frac{\Gamma \vdash \mathbf{t}: T \quad x \notin FV(\Gamma)}{\Gamma \vdash \mathbf{t}: \forall X. T} \forall_I \quad \frac{\Gamma \vdash \mathbf{t}: T \quad T \equiv R}{\Gamma \vdash \mathbf{t}: R} \equiv$$

$$\frac{}{\Gamma \vdash \mathbf{0}: \bar{0}} ax_0 \quad \frac{\Gamma \vdash \mathbf{t}: T \quad \Gamma \vdash \mathbf{r}: R}{\Gamma \vdash \mathbf{t} + \mathbf{r}: T + R} +_I \quad \frac{}{\Gamma, x: U \vdash x: U} ax$$

- Strong normalisation ✓
- Subject reduction ✓

The Additive Type System [Díaz-Caro, Petit 2010]

System F with pairs

$$t, u := x \mid \lambda x.t \mid tu \mid \star \mid \langle t, u \rangle \mid \pi_1(t) \mid \pi_2(t)$$

$$A, B := X \mid A \Rightarrow B \mid \forall X.A \mid \mathbf{1} \mid A \times B$$

$$(\lambda x.t) u \rightarrow t[u/x] \quad \pi_i(\langle t_1, t_2 \rangle) \rightarrow t_i$$

$$\frac{}{\Delta, x : A \vdash_F x : A} A_x \quad \frac{}{\Delta \vdash_F \star : \mathbf{1}} \mathbf{1} \quad \frac{\Delta \vdash_F t : A \quad \Delta \vdash_F u : B}{\Delta \vdash_F \langle t, u \rangle : A \times B} \times_I$$

$$\frac{\Delta \vdash_F t : A \times B}{\Delta \vdash_F \pi_1(t) : A} \times_{E_l} \quad \frac{\Delta \vdash_F t : A \times B}{\Delta \vdash_F \pi_2(t) : B} \times_{E_r} \quad \frac{\Delta \vdash_F t : A \Rightarrow B \quad \Delta \vdash_F u : A}{\Delta \vdash_F tu : B} \Rightarrow_E$$

$$\frac{\Gamma, x : A}{\Delta \vdash_F \lambda x.t : A \Rightarrow B} \Rightarrow_I \quad \frac{\Delta \vdash_F t : A \quad x \notin FV(\Gamma)}{\Delta \vdash_F t : \forall X.A} \forall_I \quad \frac{\Delta \vdash_F t : \forall X.A}{\Delta \vdash_F t : A[B/X]} \forall_E$$

The Additive Type System [Díaz-Caro, Petit 2010]

Translation of types

Additive		System F with pairs
X	\rightsquigarrow	X
$U \rightarrow T$	\rightsquigarrow	$ U \Rightarrow T $
$\forall X. U$	\rightsquigarrow	$\forall X. U $
$\bar{0}$	\rightsquigarrow	$\mathbf{1}$
$T + S$	\rightsquigarrow	$ T \times S $

The Additive Type System [Díaz-Caro, Petit 2010]

Sums as Pairs

$+, \bar{0}$ \rightsquigarrow $\times, \mathbf{1}$

$$\begin{array}{ll} T + S \equiv S + T & A \times B \neq B \times A \\ T + (S + R) \equiv (T + S) + R & A \times (B \times C) \neq (A \times B) \times C \\ T + \bar{0} \equiv T & A \times \mathbf{1} \neq A \end{array}$$

The Additive Type System [Díaz-Caro, Petit 2010]

Sums as Pairs

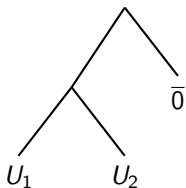
$+, \bar{0} \rightsquigarrow \times, \mathbf{1}$

$$\begin{array}{ll} T + S \equiv S + T & A \times B \neq B \times A \\ T + (S + R) \equiv (T + S) + R & A \times (B \times C) \neq (A \times B) \times C \\ T + \bar{0} \equiv T & A \times \mathbf{1} \neq A \end{array}$$

$$\begin{array}{l} T, R, S := U \mid T + R \mid \bar{0} \\ U, V, W := X \mid U \rightarrow T \mid \forall X.U \end{array}$$

Type \rightsquigarrow Binary tree (leaf: U or $\bar{0}$)

Example: $T = (U_1 + U_2) + \bar{0}$



We first keep structured sum types

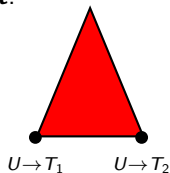
The Additive Type System [Díaz-Caro, Petit 2010]

Structured Arrow-elimination

$$\frac{\Gamma \vdash \mathbf{t}: \sum_{i=1}^{\alpha} (U \rightarrow T_i) \quad \Gamma \vdash \mathbf{r}: \sum_{j=1}^{\beta} U}{\Gamma \vdash (\mathbf{t}) \mathbf{r}: \sum_{i=1}^{\alpha} \sum_{j=1}^{\beta} T_i}$$

$$\frac{\Gamma \vdash \mathbf{t}: \mathcal{A}[\ell \mapsto (U \rightarrow T_\ell)] \quad \Gamma \vdash \mathbf{r}: \mathcal{A}'[\ell' \mapsto U]}{\Gamma \vdash (\mathbf{t}) \mathbf{r}: \mathcal{A} \circ \mathcal{A}'[\ell \ell' \mapsto T_\ell]}$$

t:

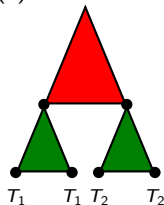


r:



\rightsquigarrow

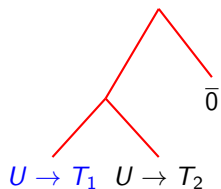
(t) r:



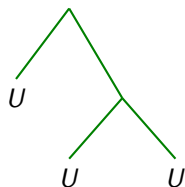
The Additive Type System [Díaz-Caro, Petit 2010]

Structured Arrow-elimination: An example

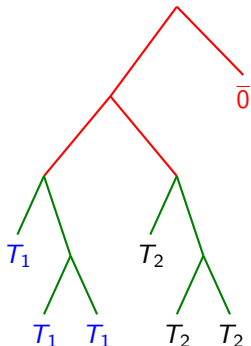
$$\mathbf{t} = (\mathbf{t}_1 + \mathbf{t}_2) + 0$$



$$\mathbf{r} = \mathbf{r}_1 + (\mathbf{r}_2 + \mathbf{r}_3)$$



$$\begin{aligned} (\mathbf{t}) \mathbf{r} &\rightarrow^* (\mathbf{t}_1) (\mathbf{r}_1 + (\mathbf{r}_2 + \mathbf{r}_3)) + \\ &\quad (\mathbf{t}_2) (\mathbf{r}_1 + (\mathbf{r}_2 + \mathbf{r}_3)) + 0 \\ &\rightarrow^* (\mathbf{t}_1) \mathbf{r}_1 + ((\mathbf{t}_1) \mathbf{r}_2 + (\mathbf{t}_1) \mathbf{r}_3) + \\ &\quad (\mathbf{t}_2) \mathbf{r}_1 + ((\mathbf{t}_2) \mathbf{r}_2 + (\mathbf{t}_2) \mathbf{r}_3) + 0 \end{aligned}$$



The Additive Type System [Díaz-Caro, Petit 2010]

Equivalence in System F

What about associativity, commutativity and neutral element?

Theorem

$$T \equiv T' \quad \text{implies} \quad |T| \Leftrightarrow |T'|$$

Where $A \Leftrightarrow B$ means

$$\vdash_F \varepsilon_{A,B} : A \Rightarrow B \quad \text{and} \quad \vdash_F \varepsilon_{B,A} : B \Rightarrow A$$

for some terms $\varepsilon_{A,B}, \varepsilon_{B,A}$ s.t.

$$\varepsilon_{A,B} \circ \varepsilon_{B,A} \approx id_A \quad \text{and} \quad \varepsilon_{B,A} \circ \varepsilon_{A,B} \approx id_B$$

The Additive Type System [Díaz-Caro, Petit 2010]

What happens with linearity?

$$\mathbf{t} + \mathbf{r} \rightsquigarrow \langle [\mathbf{t}], [\mathbf{r}] \rangle$$

$$\begin{array}{l} (\mathbf{t}_1 + \mathbf{t}_2) (\mathbf{r}_1 + \mathbf{r}_2) \rightarrow^* \quad \text{but } \langle \mathbf{t}_1, \mathbf{t}_2 \rangle \langle \mathbf{r}_1, \mathbf{r}_2 \rangle \not\rightarrow \\ \mathbf{t}_1 \mathbf{r}_1 + \mathbf{t}_1 \mathbf{r}_2 + \mathbf{t}_2 \mathbf{r}_1 + \mathbf{t}_2 \mathbf{r}_2 \quad \langle \langle \mathbf{t}_1 \mathbf{r}_1, \mathbf{t}_1 \mathbf{r}_2 \rangle, \langle \mathbf{t}_2 \mathbf{r}_1, \mathbf{t}_2 \mathbf{r}_2 \rangle \rangle \end{array}$$

No linearity in System F with pairs

The Additive Type System [Díaz-Caro, Petit 2010]

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$$\mathbf{t} + \mathbf{r} \rightsquigarrow \langle [\mathbf{t}], [\mathbf{r}] \rangle$$

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No linearity in System F with pairs

Main ideas:

- ▶ The sum is distributed during the translation of application
$$[(\mathbf{t}) \mathbf{r}] = \langle \langle [\mathbf{t}_1][\mathbf{r}_1], [\mathbf{t}_1][\mathbf{r}_2] \rangle, \langle [\mathbf{t}_2][\mathbf{r}_1], [\mathbf{t}_2][\mathbf{r}_2] \rangle \rangle$$
if $\mathbf{t} = \mathbf{t}_1 + \mathbf{t}_2$ and $\mathbf{r} = \mathbf{r}_1 + \mathbf{r}_2$

The Additive Type System [Díaz-Caro, Petit 2010]

What happens with linearity?

$$\mathbf{t} + \mathbf{r} \rightsquigarrow \langle [\mathbf{t}], [\mathbf{r}] \rangle$$

$$\begin{array}{l} (\mathbf{t}_1 + \mathbf{t}_2) (\mathbf{r}_1 + \mathbf{r}_2) \rightarrow^* \quad \text{but } \langle \mathbf{t}_1, \mathbf{t}_2 \rangle \langle \mathbf{r}_1, \mathbf{r}_2 \rangle \not\rightarrow \\ \mathbf{t}_1 \mathbf{r}_1 + \mathbf{t}_1 \mathbf{r}_2 + \mathbf{t}_2 \mathbf{r}_1 + \mathbf{t}_2 \mathbf{r}_2 \quad \langle \langle \mathbf{t}_1 \mathbf{r}_1, \mathbf{t}_1 \mathbf{r}_2 \rangle, \langle \mathbf{t}_2 \mathbf{r}_1, \mathbf{t}_2 \mathbf{r}_2 \rangle \rangle \end{array}$$

No linearity in System F with pairs

Main ideas:

- ▶ The sum is distributed during the translation of application
$$[(\mathbf{t}) \mathbf{r}] = \langle \langle [\mathbf{t}_1][\mathbf{r}_1], [\mathbf{t}_1][\mathbf{r}_2] \rangle, \langle [\mathbf{t}_2][\mathbf{r}_1], [\mathbf{t}_2][\mathbf{r}_2] \rangle \rangle$$
if $\mathbf{t} = \mathbf{t}_1 + \mathbf{t}_2$ and $\mathbf{r} = \mathbf{r}_1 + \mathbf{r}_2$
- ▶ The “sum structure” of a term is known thanks to its type
$$\Gamma \vdash \mathbf{t} : (\mathcal{T}_1 + \mathcal{T}_2) + \mathcal{T}_3 \rightsquigarrow \mathbf{t} \text{ “}\simeq\text{” } (\mathbf{t}_1 + \mathbf{t}_2) + \mathbf{t}_3$$
with $\Gamma \vdash \mathbf{t}_i : \mathcal{T}_i$

The Additive Type System [Díaz-Caro, Petit 2010]

Translation of terms

$$\Gamma \vdash \mathbf{t} : \mathcal{T} \quad \rightsquigarrow \quad |\Gamma| \vdash_F [\mathbf{t}]_{\mathcal{D}} : |\mathcal{T}|$$

$$\Gamma, x : \mathcal{T} \vdash x : \mathcal{T} \quad \rightsquigarrow \quad [x]_{\mathcal{D}} = x$$

$$\Gamma \vdash \mathbf{0} : \bar{0} \quad \rightsquigarrow \quad [\mathbf{0}]_{\mathcal{D}} = \star$$

The Additive Type System [Díaz-Caro, Petit 2010]

Translation of terms

$$\Gamma \vdash \mathbf{t} : T \quad \rightsquigarrow \quad |\Gamma| \vdash_F [\mathbf{t}]_{\mathcal{D}} : |T|$$

$$\begin{array}{l} \Gamma, x : T \vdash x : T \\ \Gamma \vdash \mathbf{0} : \bar{0} \\ \Gamma \vdash \mathbf{t} : T \quad T \equiv T' \\ \hline \Gamma \vdash \mathbf{t} : T' \end{array} \quad \rightsquigarrow \quad \begin{array}{l} [x]_{\mathcal{D}} = x \\ [\mathbf{0}]_{\mathcal{D}} = \star \\ [\mathbf{t}]_{\mathcal{D}} = \varepsilon_{|T|, |T'|} [\mathbf{t}]_{\mathcal{D}'} \end{array}$$

The Additive Type System [Díaz-Caro, Petit 2010]

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$$\frac{\Gamma \vdash \mathbf{t} : T \quad \Gamma \vdash \mathbf{r} : S}{\Gamma \vdash \mathbf{t} + \mathbf{r} : T + S} \quad \rightsquigarrow \quad [\mathbf{t} + \mathbf{r}]_{\mathcal{D}} = \langle [\mathbf{t}]_{\mathcal{D}_1}, [\mathbf{r}]_{\mathcal{D}_2} \rangle$$
$$\frac{\Gamma, x : U \vdash \mathbf{t} : T}{\Gamma \vdash \lambda x. \mathbf{t} : U \rightarrow T} \quad \rightsquigarrow \quad [\lambda x. \mathbf{t}]_{\mathcal{D}} = \lambda x. [\mathbf{t}]_{\mathcal{D}'}$$

The Additive Type System [Díaz-Caro, Petit 2010]

Translation of terms

$$\Gamma \vdash \mathbf{t} : T \quad \rightsquigarrow \quad |\Gamma| \vdash_F [\mathbf{t}]_{\mathcal{D}} : |T|$$

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$$\frac{\Gamma, x : U \vdash \mathbf{t} : T}{\Gamma \vdash \lambda x. \mathbf{t} : U \rightarrow T} \quad \rightsquigarrow \quad [\lambda x. \mathbf{t}]_{\mathcal{D}} = \lambda x. [\mathbf{t}]_{\mathcal{D}'}$$

$$\frac{\Gamma \vdash \mathbf{t} : \mathcal{A}[w \mapsto (U \rightarrow T_w)] \quad \Gamma \vdash \mathbf{r} : \mathcal{A}'[v \mapsto U]}{\Gamma \vdash (\mathbf{t}) \mathbf{r} : \mathcal{A} \circ \mathcal{A}'[wv \mapsto T_w]} \quad \rightsquigarrow \quad [(\mathbf{t}) \mathbf{r}]_{\mathcal{D}} = \mathcal{A} \circ \mathcal{A}'[wv \mapsto \pi_{\bar{w}}([\mathbf{t}]_{\mathcal{D}_1}) \pi_{\bar{v}}([\mathbf{r}]_{\mathcal{D}_2})]$$

The Additive Type System [Díaz-Caro, Petit 2010]

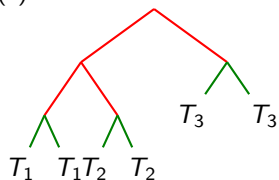
Translation of terms: An example

$$\frac{\Gamma \vdash \mathbf{t} : \left((U \rightarrow T_1) + (U \rightarrow T_2) \right) + (U \rightarrow T_3) \quad \Gamma \vdash \mathbf{r} : U + U}{\Gamma \vdash (\mathbf{t}) \mathbf{r} : \left((T_1 + T_1) + (T_2 + T_2) \right) + (T_3 + T_3)}$$

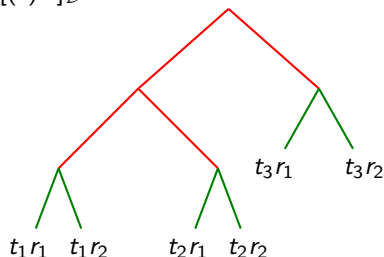
$$t_1 = \pi_{11}([\mathbf{t}]); t_2 = \pi_{12}([\mathbf{t}]); t_3 = \pi_2([\mathbf{t}]);$$

$$r_1 = \pi_1([\mathbf{r}]); r_2 = \pi_2([\mathbf{r}]);$$

$(\mathbf{t}) \mathbf{r} :$



$[(\mathbf{t}) \mathbf{r}]_{\mathcal{D}} =$



The Additive Type System [Díaz-Caro, Petit 2010]

Translation of terms: Correctness

Correctness of typing:

Theorem

$$\Gamma \vdash t : T \quad \Longrightarrow \quad |\Gamma| \vdash_F [t]_{\mathcal{D}} : |T|$$

Correctness of reduction:

Theorem

$$\Gamma \vdash t : T \text{ and } t \rightarrow t' \quad \text{implies} \quad [t]_{\mathcal{D}} \rightarrow^* [t']_{\mathcal{D}'}, \quad \text{for some } \mathcal{D}'$$

The Vectorial Type System [Arrighi, Díaz-Caro, Valiron 2010]

Grammar

Types grammar:

$$\begin{aligned} T, R, S &:= U \mid T + R \mid \alpha.T && \text{(no type } \bar{0}\text{!)} \\ U, V, W &:= X \mid U \rightarrow T \mid \forall X.U \end{aligned}$$

Equivalences:

$$\begin{aligned} 1.T &\equiv T \\ \alpha.(\beta.T) &\equiv (\alpha \times \beta).T \\ \alpha.T + \alpha.R &\equiv \alpha.(T + R) \\ \alpha.T + \beta.T &\equiv (\alpha + \beta).T \\ T + R &\equiv R + T \\ T + (R + S) &\equiv (T + R) + S \end{aligned}$$

The Vectorial Type System [Arrighi, Díaz-Caro, Valiron 2010]

Not **one** zero... a lot of them

$$\frac{\Gamma \vdash \lambda x.x : U \rightarrow U \quad \frac{\Gamma \vdash \mathbf{r} : R \quad \Gamma \vdash -\mathbf{r} : -R}{\Gamma \vdash \mathbf{r} - \mathbf{r} : \bar{0}}}{\Gamma \vdash \lambda x.x + \mathbf{r} - \mathbf{r} : U \rightarrow U} \quad \frac{}{\Gamma \vdash \mathbf{t} : U}$$
$$\frac{}{\Gamma \vdash (\lambda x.x + \mathbf{r} - \mathbf{r}) \mathbf{t} : U}$$

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$$\frac{\frac{\Gamma \vdash \lambda x.x : U \rightarrow U}{\Gamma \vdash \lambda x.x + \mathbf{r} - \mathbf{r} : U \rightarrow U} \quad \frac{\Gamma \vdash \mathbf{r} : R \quad \Gamma \vdash -\mathbf{r} : -R}{\Gamma \vdash \mathbf{r} - \mathbf{r} : \bar{0}}}{\Gamma \vdash (\lambda x.x + \mathbf{r} - \mathbf{r}) \mathbf{t} : U} \quad \frac{}{\Gamma \vdash \mathbf{t} : U}$$

However, $(\lambda x.x + \mathbf{r} - \mathbf{r}) \mathbf{t} \rightarrow (\lambda x.x) \mathbf{t} + (\mathbf{r}) \mathbf{t} - (\mathbf{r}) \mathbf{t}$.

The Vectorial Type System [Arrighi, Díaz-Caro, Valiron 2010]

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However, $(\lambda x.x + \mathbf{r} - \mathbf{r}) \mathbf{t} \rightarrow (\lambda x.x) \mathbf{t} + (\mathbf{r}) \mathbf{t} - (\mathbf{r}) \mathbf{t}$.

We need to keep track of the zeros... where they came from!

The Vectorial Type System [Arrighi, Díaz-Caro, Valiron 2010]

Not **one** zero... a lot of them

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However, $(\lambda x.x + \mathbf{r} - \mathbf{r}) \mathbf{t} \rightarrow (\lambda x.x) \mathbf{t} + (\mathbf{r}) \mathbf{t} - (\mathbf{r}) \mathbf{t}$.

We need to keep track of the zeros... where they came from!

Instead of $\bar{0}$, we have $0.R$ and $T + 0.R \neq T$

The **Vectorial** Type System [Arrighi, Díaz-Caro, Valiron 2010]

The factorisation rule problem

$$\frac{\Gamma \vdash \mathbf{t} : T \quad \Gamma \vdash \mathbf{t} : T'}{\Gamma \vdash \alpha.\mathbf{t} + \beta.\mathbf{t} : \alpha.T + \beta.T'}$$

- ▶ However, $\alpha.\mathbf{t} + \beta.\mathbf{t} \rightarrow (\alpha + \beta).\mathbf{t}$
- ▶ In general $\alpha.T + \beta.T' \neq (\alpha + \beta).T \neq (\alpha + \beta).T'$

The Vectorial Type System [Arrighi, Díaz-Caro, Valiron 2010]

The factorisation rule problem

Several possible solutions:

- ▶ Remove factorisation rule (Done. SR and SN both work)
 - ▶ + in scalars not used anymore. Scalars \Rightarrow Monoid
 - ▶ It works!... but it is no so expressive, no so useful

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- ▶ Add several typing rules to allow typing $(\alpha + \beta).u$ with $\alpha.A + \beta.B$
 - ▶ As soon as we add one, we have to add many to make it work
 - ▶ Too complex and inelegant

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 - ▶ Seems to be the natural solution
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- ▶ **Church style** (work-in-progress)
 - ▶ Seems to be the natural solution
 - ▶ Big complexness with polymorphism and distributivity
- ▶ **Weaker subject reduction** (this presentation)

The Vectorial Type System [Arrighi, Díaz-Caro, Valiron 2010]

Typing rules

$$\frac{}{\Gamma, x: U \vdash x: U} \text{ax} \quad \frac{\Gamma \vdash \mathbf{t}: T}{\Gamma \vdash \mathbf{0}: \mathbf{0}.T} \text{0}_I \quad \frac{\Gamma \vdash \mathbf{t}: T}{\Gamma \vdash \alpha.\mathbf{t}: \alpha.T} \alpha_I$$
$$\frac{\Gamma \vdash \mathbf{t}: \sum_{i=1}^n \alpha_i. \forall \vec{X}. (U \rightarrow T_i) \quad \Gamma \vdash \mathbf{r}: \sum_{j=1}^m \beta_j. V_j \quad \forall V_j, \exists \vec{W}_j / U[\vec{W}_j / \vec{X}] = V_j}{\Gamma \vdash (\mathbf{t}) \mathbf{r}: \sum_{i=1}^n \sum_{j=1}^m \alpha_i \times \beta_j. T_i[\vec{W}_j / \vec{X}]} \rightarrow_E$$
$$\frac{\Gamma, x: U \vdash \mathbf{t}: T}{\Gamma \vdash \lambda x. \mathbf{t}: U \rightarrow T} \rightarrow_I \quad \frac{\Gamma \vdash \mathbf{t}: T \quad \Gamma \vdash \mathbf{r}: R}{\Gamma \vdash \mathbf{t} + \mathbf{r}: T + R} +_I$$
$$\frac{\Gamma \vdash \mathbf{t}: U \quad x \notin FV(\Gamma)}{\Gamma \vdash \mathbf{t}: \forall X. U} \forall_I \quad \frac{\Gamma \vdash \mathbf{t}: \forall X. U}{\Gamma \vdash \mathbf{t}: U[V/X]} \forall_E$$

Vectorial type system

Example

$$\Gamma \vdash \mathbf{b}_1 : V_1$$
$$\Gamma \vdash \mathbf{b}_2 : V_2$$

Vectorial type system

Example

$$\begin{array}{l} \Gamma \vdash \mathbf{b}_1 : V_1 \\ \Gamma \vdash \mathbf{b}_2 : V_2 \end{array} \Rightarrow \Gamma \vdash \beta_1 \cdot \mathbf{b}_1 + \beta_2 \cdot \mathbf{b}_2 : \beta_1 \cdot V_1 + \beta_2 \cdot V_2$$

Vectorial type system

Example

$$\begin{array}{l} \Gamma \vdash \mathbf{b}_1 : V_1 \\ \Gamma \vdash \mathbf{b}_2 : V_2 \end{array} \Rightarrow \Gamma \vdash \beta_1.\mathbf{b}_1 + \beta_2.\mathbf{b}_2 : \beta_1.V_1 + \beta_2.V_2$$

$$\Gamma \vdash \lambda x_1.\mathbf{t}_1 : \forall X.(U \rightarrow T_1)$$

$$\Gamma \vdash \lambda x_2.\mathbf{t}_2 : \forall X.(U \rightarrow T_2)$$

$$\Rightarrow \Gamma \vdash (\alpha_1.\lambda x_1.\mathbf{t}_1) + (\alpha_2.\lambda x_2.\mathbf{t}_2) : (\alpha_1.\forall X.(U \rightarrow T_1)) + (\alpha_2.\forall X.(U \rightarrow T_2))$$

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Example

$$\begin{array}{l} \Gamma \vdash \mathbf{b}_1 : V_1 \\ \Gamma \vdash \mathbf{b}_2 : V_2 \end{array} \Rightarrow \Gamma \vdash \beta_1 \cdot \mathbf{b}_1 + \beta_2 \cdot \mathbf{b}_2 : \beta_1 \cdot V_1 + \beta_2 \cdot V_2$$

$U[W_1/X] = V_1$
$U[W_2/X] = V_2$

$$\begin{array}{l} \Gamma \vdash \lambda x_1. \mathbf{t}_1 : \forall X. (U \rightarrow T_1) \\ \Gamma \vdash \lambda x_2. \mathbf{t}_2 : \forall X. (U \rightarrow T_2) \end{array}$$

$$\Rightarrow \Gamma \vdash (\alpha_1 \cdot \lambda x_1. \mathbf{t}_1) + (\alpha_2 \cdot \lambda x_2. \mathbf{t}_2) : (\alpha_1 \cdot \forall X. (U \rightarrow T_1)) + (\alpha_2 \cdot \forall X. (U \rightarrow T_2))$$

$$\begin{array}{l} \Gamma \vdash \blacktriangle + \blacktriangledown : \alpha_1 \cdot \forall X. (U \rightarrow T_1) + \alpha_2 \cdot \forall X. (U \rightarrow T_2) \\ \Gamma \vdash \triangle + \nabla : \beta_1 \cdot V_1 + \beta_2 \cdot V_2 \end{array}$$

$$\Gamma \vdash (\blacktriangle + \blacktriangledown) (\triangle + \nabla) : \sum_{i=1}^2 \sum_{j=1}^2 \alpha_i \times \beta_j \cdot T_i[W_j/X] \quad \rightarrow_E$$

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$$\begin{array}{l} \Gamma \vdash \mathbf{b}_1 : V_1 \\ \Gamma \vdash \mathbf{b}_2 : V_2 \end{array} \Rightarrow \Gamma \vdash \beta_1 \cdot \mathbf{b}_1 + \beta_2 \cdot \mathbf{b}_2 : \beta_1 \cdot V_1 + \beta_2 \cdot V_2$$

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$$\Rightarrow \Gamma \vdash (\alpha_1 \cdot \lambda x_1. \mathbf{t}_1) + (\alpha_2 \cdot \lambda x_2. \mathbf{t}_2) : (\alpha_1 \cdot \forall X. (U \rightarrow T_1)) + (\alpha_2 \cdot \forall X. (U \rightarrow T_2))$$

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$$\Gamma \vdash (\blacktriangle + \blacktriangledown) (\blacktriangle + \blacktriangledown) : \sum_{i=1}^2 \sum_{j=1}^2 \alpha_i \times \beta_j \cdot T_i[W_j/X] \quad \rightarrow_E$$

$$(\blacktriangle + \blacktriangledown) (\blacktriangle + \blacktriangledown) \rightarrow^* (\blacktriangle) \blacktriangle + (\blacktriangle) \blacktriangledown + (\blacktriangledown) \blacktriangle + (\blacktriangledown) \blacktriangledown$$

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Example

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e.g.

$$\begin{array}{l} (\blacktriangledown) \Delta = (\alpha_2 \cdot \lambda x_2 \cdot \mathbf{t}_2) \beta_1 \cdot \mathbf{b}_1 \rightarrow^* \\ (\alpha_2 \times \beta_1) \cdot (\lambda x_2 \cdot \mathbf{t}_2) \mathbf{b}_1 \end{array}$$

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Example

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The Vectorial Type System [Arrighi, Díaz-Caro, Valiron 2010]

A weaker subject reduction

$$(\alpha + \beta).T \sqsubseteq \alpha.T + \beta.T' \quad \text{if } \Gamma \vdash \alpha.\mathbf{t}:\alpha.T \text{ and } \Gamma \vdash \beta.\mathbf{t}:\beta.T' \\ \text{(and its contextual closure)}$$

The **V**ectorial Type System [Arrighi, Díaz-Caro, Valiron 2010]

A weaker subject reduction

$$(\alpha + \beta).T \sqsubseteq \alpha.T + \beta.T' \quad \text{if } \Gamma \vdash \alpha.\mathbf{t} : \alpha.T \text{ and } \Gamma \vdash \beta.\mathbf{t} : \beta.T' \\ \text{(and its contextual closure)}$$

Theorem (Weak subject reduction)

$$\left. \begin{array}{l} \mathbf{t} \rightarrow_R \mathbf{s} \\ \Gamma \vdash \mathbf{t} : T \end{array} \right\} \exists S \sqsubseteq T / \Gamma \vdash \mathbf{s} : S$$

Moreover, if R is not a factorisation, then $\Rightarrow S \equiv T$.

▶ Extra: orthogonality

▶ Conclusion

Orthogonality

Why

Now, say we would like normalised terms

$$\alpha.\mathbf{t} + \beta.\mathbf{s}$$

with $|\alpha|^2 + |\beta|^2 = 1$.

Orthogonality

Why

Now, say we would like normalised terms

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So, we want to allow $\frac{1}{\sqrt{2}}.\mathbf{t} + \frac{1}{\sqrt{2}}.\mathbf{s}$ and disallow $\frac{1}{2}.\mathbf{t} + \frac{1}{2}.\mathbf{s}$

Orthogonality

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Or do we? What happens if $\mathbf{t} \rightarrow^* \mathbf{s}$?

Orthogonality

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Or do we? What happens if $\mathbf{t} \rightarrow^* \mathbf{s}$?

We need a notion of orthogonality between terms (and also a way to check it).

Orthogonality

Inner product

Definition (Terms inner product)

Let $\mathbf{t}, \mathbf{s}, \mathbf{r}$ be any term, and let \mathbf{u}, \mathbf{v} be terms in normal form which are not sum of terms nor a scalar times a term. We define the function 'delta' as follows:

$$\delta_{\mathbf{t}, \mathbf{s}} = \begin{cases} 0 & \text{if } \mathbf{t} \neq \mathbf{s} \vee \mathbf{t} = \mathbf{0} \vee \mathbf{s} = \mathbf{0} \\ 1 & \text{in any other case} \end{cases}$$

Then, we define the inner product between terms recursively by

$$\langle \mathbf{u} | \mathbf{v} \rangle = \langle \mathbf{v} | \mathbf{u} \rangle = \delta_{\mathbf{u}, \mathbf{v}}$$

$$\langle \mathbf{t} | \mathbf{s} \rangle = \overline{\langle \mathbf{s} | \mathbf{t} \rangle} = \langle \mathbf{t} \downarrow | \mathbf{s} \downarrow \rangle$$

$$\langle \alpha \cdot \mathbf{t} + \beta \cdot \mathbf{s} | \mathbf{r} \rangle = \alpha \times \langle \mathbf{t} | \mathbf{r} \rangle + \beta \times \langle \mathbf{s} | \mathbf{r} \rangle$$

Orthogonality

Inner product

Definition (Terms inner product)

Let $\mathbf{t}, \mathbf{s}, \mathbf{r}$ be any term, and let \mathbf{u}, \mathbf{v} be terms in normal form which are not sum of terms nor a scalar times a term. We define the function 'delta' as follows:

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Examples

$$\langle (\lambda x x) \mathbf{v} | \mathbf{v} \rangle = 1$$

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Examples

$$\langle (\lambda x x) \mathbf{v} | \mathbf{v} \rangle = 1$$

$$\langle \mathbf{true} | \mathbf{false} \rangle = 0$$

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Examples

$$\langle (\lambda x x) \mathbf{v} | \mathbf{v} \rangle = 1$$

$$\langle \mathbf{true} | \mathbf{false} \rangle = 0$$

$$\left| \begin{aligned} & \langle \frac{1}{\sqrt{2}} \cdot \mathbf{true} + \frac{1}{\sqrt{2}} \cdot \mathbf{false} | \mathbf{true} \rangle = \\ & \frac{1}{\sqrt{2}} \times \langle \mathbf{true} | \mathbf{true} \rangle + \frac{1}{\sqrt{2}} \times \langle \mathbf{false} | \mathbf{true} \rangle = \frac{1}{\sqrt{2}} \end{aligned} \right.$$

Orthogonality

How to check it

Let $\Gamma \vdash \mathbf{u} : T$ and $\Gamma \vdash \mathbf{v} : S$.

Does $\mathbf{u} \perp \mathbf{v} \Leftrightarrow T \perp S$?

(for some definition of orthogonality between types)

Orthogonality

How to check it

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► $\mathbf{u} \perp \mathbf{v} \not\Rightarrow T \perp S$

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Counterexample

$\vdash \text{true} : \text{Bool}$

$\vdash \text{false} : \text{Bool}$

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Counterexample

$y : W \vdash \lambda x. y : U \rightarrow W$

$y : W \vdash \lambda x. y : V \rightarrow W$

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Does $\mathbf{u} \perp \mathbf{v} \Leftrightarrow T \perp S$?

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Counterexample

$y : W \vdash \lambda x. y : U \rightarrow W$

$y : W \vdash \lambda x. y : V \rightarrow W$

Workaround

▶ Church-style $\Rightarrow T \perp S \Rightarrow \mathbf{u} \perp \mathbf{v}$

Summary

- ▶ The **Scalar** TS : Accounts for scalars. Barycentric calculus ✓
- ▶ The **Additive** TS: Intuitions about sums ✓
- ▶ The **Vectorial** TS: Curry not compatible with vectors ✓
- ▶ Church-version: subject reduction & orthogonality (**work-in-progress**)
- ▶ May lead to a *quantum computational logic*