# Bounds on the Topology of Tropical Prevarieties 

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Tropical monomial $x^{\otimes i}:=x \otimes \cdots \otimes x, Q=a \otimes x_{1}^{\otimes i_{1}} \otimes \cdots \otimes x_{n}^{\otimes i_{n}}$, its tropical degree trdeg $=i_{1}+\cdots+i_{n}$. Then $Q=a+i_{1} \cdot x_{1}+\cdots+i_{n} \cdot x_{n}$.

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## Historical sources of the tropical algebra

Logarithmic scaling of the reals (mathematical physics)
Define two operations on positive reals, replacing addition and multiplication:
$a, b \rightarrow t \cdot \log (\exp (a / t)+\exp (b / t)), \quad \lim _{t \rightarrow 0}=\max \{a, b\}$
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The field of Puiseux series
$F\left(\left(t^{1 / \infty}\right)\right) \ni a_{0} \cdot t^{\prime / q}+a_{1} \cdot t^{(i+1) / q}+\cdots, 0<q \in \mathbb{Z}$ over an algebraically closed field $F$ is algebraically closed.

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## Minimal weights of paths in a graph (computer science)

For a graph with weights $w_{i j}$ on edges $(i, j)$ for any $k$ to compute for each pair of vertices $i, j$ the minimal weight of paths between $i$ and $j$.
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This approach is employed in scheduling of Dutch and Korean railways.

## Tropical Varieties and Prevarieties



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Any tropical prevariety is a polyhedral fan. Moreover, when ideal I is prime the tropical variety $\overline{\operatorname{Trop}(U(I))}$ has at any point the same local dimension equal dim/.

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$f_{1}, \ldots, f_{k} \in I$ such that
$\operatorname{Trop}(U(I))=\overline{\operatorname{Trop}\left(U\left(f_{1}\right)\right)}$

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(Bogart, Jensen, Speyer, Sturmfels, Thomas), i. e. any tropical variety is a tropical prevariety.
Given a tropical basis one can test whether a point $v \in \mathbb{R}^{n}$ belongs to the tropical variety $\overline{\operatorname{Trop}(U(I))}$ since for tropical hypersurfaces $\overline{\operatorname{Trop}(U(f))}=U(\operatorname{Trop}(f))$ holds (Kapranov) where $\operatorname{Trop}\left(\sum_{J} f_{J} \cdot X^{J}\right):=\min _{J}\left\{\operatorname{Trop}\left(f_{J}\right)+\langle J, X\rangle\right\}, f_{J} \in K$.

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$n \times n$ matrix $\left(a_{i, j}\right)$ is tropically non-singular if the minimum $\min _{\pi \in S_{n}}\left\{a_{1, \pi(1)}+\cdots+a_{n, \pi(n)}\right\}\left(=\operatorname{Trop}\left(\operatorname{det}\left(a_{i, j}\right)\right)\right)$ is attained for a unique permutation $\pi$

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Open Problem. Can one test solvability of a tropical linear system within the polynomial complexity, so within $(m \cdot n \cdot \log M)^{O(1)}$ ?

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Tropical rank trk (A) of matrix $A$ is the maximal size of its tropically nonsingular square submatrices.
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- For $n \times n$ matrix $B$ testing $\operatorname{trk}(B)=n$ ( $\Leftrightarrow B$ is tropically nonsingular) has polynomial complexity due to Hungarian algorithm (Butkovic-Hevery);
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\section*{Computing dimension of a tropical linear system}

\section*{Proposition}

One can test uniqueness (in the tropical projective space) of a solution of a tropical linear system (i. e. whether the dimension of a tropical linear prevariety equals 0 ) within complexity polynomial in \(n, m, M\).

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(a part of this theorem answers a question of V.Voevodsky)

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\section*{Theorem}

The following 4 problems are equivalent: mean payoff games, min-atom, min-plus linear systems and tropical linear systems (Bezem-Nieuwenhuis-Rodriguez-Carbonell, Akian-Gaubert-Guterman).

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\section*{"Dual" (classical) Nullstellensatz}

For polynomials \(g_{1}, \ldots, g_{k} \in \mathbb{C}\left[X_{1}, \ldots, X_{n}\right]\) consider an infinite Macauley matrix \(C\) with the columns indexed by monomials \(X^{\prime}\) and the rows by shifts \(X^{J} \cdot g_{i}\) for all \(J\), \(i\) with their coefficients being entries of \(C\).

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Nullstellensatz deals with ideal \(\left\langle g_{1}, \ldots, g_{k}\right\rangle\), while dual Nullstellensatz forgets the ideal, therefore, gives a hope to hold in the tropical setting

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Let \(g_{0}, \ldots, g_{k} \in \mathbb{C}\left[X_{0}, \ldots, X_{n}\right]\) be homogeneous polynomials with \(\operatorname{deg}\left(g_{0}\right) \geq \operatorname{deg}\left(g_{1}\right) \geq \cdots\).

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In the dual form this means that system \(g_{0}=\cdots=g_{k}=0\) has a solution in the projective space iff the homogeneous linear system with submatrix \(C_{N_{0}}^{(\text {hom })}\) of the Macauley matrix \(C\) generated by the columns with the degrees of monomials equal \(N_{0}\), has a non-zero solution.

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In the dual form this means that system \(g_{0}=\cdots=g_{k}=0\) has a solution in the projective space iff the homogeneous linear system with submatrix \(C_{N_{0}}^{(\text {hom })}\) of the Macauley matrix \(C\) generated by the columns with the degrees of monomials equal \(N_{0}\), has a non-zero solution.
Thus, the bound on the degrees of monomials in the Macauley matrix in the affine Nullstellensatz is roughly the product of the degrees (Bezout number) of the polynomials in the system,

\section*{Classical homogeneous (projective) effective Nullstellensatz}

Let \(g_{0}, \ldots, g_{k} \in \mathbb{C}\left[X_{0}, \ldots, X_{n}\right]\) be homogeneous polynomials with \(\operatorname{deg}\left(g_{0}\right) \geq \operatorname{deg}\left(g_{1}\right) \geq \cdots\).

\section*{Theorem}

System \(g_{0}=\cdots=g_{k}=0\) has a solution in the projective space iff the ideal generated by \(g_{0}, \ldots, g_{k}\) does not contain the power \(\left(X_{0}, \ldots, X_{n}\right)^{N_{0}}\) of the coordinate ideal for \(N_{0}=\operatorname{deg}\left(g_{0}\right)+\cdots+\operatorname{deg}\left(g_{n}\right)-n\). (Lazard)

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Thus, the bound on the degrees of monomials in the Macauley matrix in the affine Nullstellensatz is roughly the product of the degrees (Bezout number) of the polynomials in the system, while the bound in the projective Nullstellensatz is roughly the sum of the degrees,

\section*{Tropical dual effective Nullstellensatz: finite case} Assume w.l.o.g. that for tropical polynomials \(h=\bigoplus_{J}\left(a_{J} \otimes X^{\otimes J}\right)\) in \(n\) variables which we consider, function \(J \rightarrow a_{J}\) is concave on \(\mathbb{R}^{n}\).

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Tropical polynomials \(h_{1}, \ldots, h_{k}\) have a solution over \(\mathbb{R}\) iff tropical linear system \(H_{N} \otimes\left(z_{0}, \ldots, z_{L}\right)\) has a solution over \(\mathbb{R}\) where \(H_{N}\) is (finite) submatrix of \(H\) generated by its rows \(X^{\otimes /} \otimes h_{i}, 1 \leq i \leq k\) for \(|I| \leq N=(n+2) \cdot\left(\operatorname{trdeg}\left(h_{1}\right)+\cdots+\operatorname{trdeg}\left(h_{k}\right)\right) \cdot\) (G.-Podolskii)

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\(\operatorname{Prevariety}(\operatorname{Trop}(f))=\operatorname{Trop}(\operatorname{Variety}(f))\)

\section*{(Convex)-geometrical rephrasing of the tropical dual Nullstellensatz over \(\mathbb{R}\) (finite case)}

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(Convex)-geometrical rephrasing of the tropical dual Nullstellensatz over \(\mathbb{R}\) (finite case)
}

For a tropical polynomial \(h=\bigoplus_{J}\left(a_{J} \otimes X^{\otimes J}\right)\) consider its extended Newton polyhedron \(G\) being the convex hull of the graph \(\left\{(J, a): a \leq-a_{J}\right\} \subset \mathbb{R}^{n+1}\). As vertices of \(G\) consider all the points of the form \((I, c), I \in \mathbb{Z}^{n}\) on the boundary of \(G\).

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The tropical dual (infinite) Nullstellensatz over \(\mathbb{R}\) is equivalent to the following.
For any \(I, i\) take the maximal \(b:=b_{l, i}\) such that a vertical shift \(G_{i}^{(I)}+(0, b) \leq Y\) (pointwise as graphs on \(\mathbb{Z}^{n}\) ).

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Assume that \(G_{i}^{(I)}+(0, b)\) has at least two common points with \(Y\).

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Assume that \(G_{i}^{(I)}+(0, b)\) has at least two common points with \(Y\). Then there is a hyperplane in \(\mathbb{R}^{n+1}\) (not containing the vertical line) which supports (after a parallel shift) each \(G_{i}, 1 \leq i \leq k\) at least at two points.

\section*{Tropical dual effective Nullstellensatz over \(\mathbb{R}_{\infty}\)}
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Theorem
\Delta systom ni tropical polynomials h_ ..... hk has a zero over Ros iff the
tropical non-homogeneous linear system with a finite submatrix H}\mp@subsup{H}{N}{}\mathrm{ of
the Macauley matrix H generated by its rows X\otimes1\otimeshi,1\leqi\leqk has a
tropical solution over }\mp@subsup{\mathbb{R}}{\infty}{}\mathrm{ where tropical deqrees
||<N=O(kn2}(2\mp@subsup{\operatorname{max}}{1\leqj\leqk{trdeg}{\prime}(\mp@subsup{h}{j}{})}\mp@subsup{)}{}{O(min{n,k})})\mathrm{ (G.-Podolskii)

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Thus, the following table of bounds for effective Nullstellensätze
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Theorem
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\(\square\)

\section*{Tropical dual effective Nullstellensatz over \(\mathbb{R}_{\infty}\)}

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A system of tropical polynomials \(h_{1}, \ldots, h_{k}\) has a zero over \(\mathbb{R}_{\infty}\) iff the tropical non-homogeneous linear system with a finite submatrix \(H_{N}\) of the Macauley matrix \(H\) generated by its rows \(X^{\otimes I} \otimes h_{i}, 1 \leq i \leq k\) has a tropical solution over \(\mathbb{R}_{\infty}\) where tropical degrees \(|l|<N=O\left(k n^{2}\left(2 \max _{1 \leq j \leq k}\left\{\operatorname{trdeg}\left(h_{j}\right)\right\}\right)^{O(\min \{n, k\})}\right)\) (G.-Podolskii)

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Thus, the following table of bounds for effective Nullstellensätze demonstrates a similarity of tropical geometry with the complex one
\begin{tabular}{lcc} 
Classical & Projective & Affine \\
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Bound & Sum of degrees & Product of degrees
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What is the reason of this analogy between projective vs. affine and finite vs. infinite?

\section*{Sharpness of the bounds in tropical effective Nullstellensätze}
```

Finite case
Svstem of n+1 tropical (quadratic) polynomials
has no tropical zeroes. On the other hand, submatrix }\mp@subsup{H}{n-1}{}\mathrm{ of the
Macauley matrix H has a finite (over \mathbb{R}) tropical solution (the sum of
the tropical degrees equals 2n).

```
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infinite (over \(\mathbb{R}_{\infty}\) ) tropical solution (the product of the tropical degrees
equals \(2 d^{n-1}\) ).

\section*{Sharpness of the bounds in tropical effective Nullstellensätze}

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System of \(n+1\) tropical (quadratic) polynomials
\(0 \oplus X_{1}, \quad X_{i}^{\otimes 2} \oplus X_{i+1}, 1 \leq i<n, \quad 1 \oplus X_{n}\)
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\section*{Bound on the number of connected components of a tropical prevariety}

\section*{Theorem}

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For (complex) algebraic varieties the number of isolated points is bounded by \(d^{n}\) (Bezout number) regardless of \(k\).

\section*{Table of minima of a tropical system at a point}

For a system \(A\) of tropical polynomials \(f_{i}=\oplus_{J} f_{i J} \otimes X^{\otimes J}, 1 \leq i \leq k\) of degrees \(|J| \leq d\) in \(n\) variables denote by \(V:=V(A) \subset \mathbb{R}^{n}\) the tropical prevariety of its finite solutions.

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\section*{Lemma}

For \(x, y \in V\) if tables \(A^{* x}=A^{* y}\) then some neighborhoods of \(V\) at \(x\) and at \(y\) are homeomorphic.

\section*{Generalized vertices of a tropical system}

We call \(x \in V\) a generalized vertex of a tropical system \(A\) if for any other \(\mathbb{R}^{n} \ni y \neq x\) table \(A^{* y}\) does not contain \(A^{* x}\), in other words \(A^{* x}\) is strictly maximal wrt inclusion among the tables for all the points.

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\section*{Lemma}

Any vertex of a tropical prevariety \(V(A)\) is a generalized vertex of \(A\).

\section*{Connected components and generalized vertices}

There exists \(R\) such that the intersection \(W\) of \(V:=V(A)\) with cube \(\left\{\left(x_{1}, \ldots, x_{n}\right) \in \mathbb{R}^{n}:\left|x_{p}\right| \leq R, 1 \leq p \leq n\right\}\) is homotopy equivalent to \(V\).

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\section*{Corollary}

The number of connected components of \(V\) does not exceed the number of generalized vertices of system \(B\).

\section*{Stable solutions and tropical Bezout theorem}

For system \(C\) of \(n\) tropical polynomials \(h_{1}, \ldots, h_{n}\) in \(n\) variables of degrees \(d_{1}, \ldots, d_{n}\) defining a tropical prevariety \(V\) a point \(x \in V\) is called a stable solution of \(C\) if for any sufficiently small perturbation of the coefficients of \(C\) there exists a point in the perturbed tropical prevariety in a neighborhood of \(x\).

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\section*{Theorem}
(Tropical Bezout theorem)
The sum of multiplicities of all stable solutions of \(C\) equals \(d_{1} \cdots d_{n}\) (Sturmfels).

\section*{Criterion of stability of a solution}

\section*{Lemma}
\(x \in V\) is a stable solution of system \(C=\left\{h_{1}, \ldots, h_{n}\right\}\) in \(n\) variables iff for each \(1 \leq i \leq n\) there exist marked by \(*\) in the table \(C^{* x}\) entries \(\left(i, J_{1}\right),\left(i, J_{2}\right)\) such that \(n\) vectors \(J_{1}-J_{2} \in \mathbb{Z}^{n}\) are linearly independent.

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\section*{Corollary}

If \(x\) is a generalized vertex of a system A of tropical polynomials \(f_{1}, \ldots, f_{k}\) in \(n\) variables then \(x\) is a stable solution of a suitable multisubset \(f_{l_{1}}, \ldots, f_{I_{n}}, 1 \leq I_{1}, \ldots, I_{n} \leq k\) of \(A\).

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\section*{Bezout inequality for tropical prevarieties}

\section*{Lemma}

If \(x\) is an isolated solution of system \(A\) of tropical polynomials \(f_{1}, \ldots, f_{k}\) then one can pick out a subset of \(n\) tropical polynomials \(f_{h_{1}}, \ldots, f_{l_{n}}, 1 \leq l_{1}<\cdots I_{n} \leq n\) of \(A\)

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Therefore, \(x\) is a stable solution of system \(f_{h_{1}}, \ldots, f_{l_{n}}\).

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If \(x\) is an isolated solution of system \(A\) of tropical polynomials \(f_{1}, \ldots, f_{k}\) then one can pick out a subset of \(n\) tropical polynomials \(f_{f_{1}}, \ldots, f_{f_{n}}, 1 \leq I_{1}<\cdots I_{n} \leq n\) of \(A\) and for each \(1 \leq i \leq n\) entries \(\left(i_{i}, J_{1}\right),\left(l_{i}, J_{2}\right)\) marked by \(*\) in the table \(A^{* x}\) such that \(n\) vectors \(J_{1}-J_{2} \in \mathbb{Z}^{n}\) are linearly independent.

Therefore, \(x\) is a stable solution of system \(f_{f_{1}}, \ldots, f_{l_{n}}\). Thus, each of \(\binom{k}{n}\) \(n\)-elements subsets of \(A\) has at most \(d^{n}\) stable solutions due to Tropical Bezout theorem, which entails the bound \(\binom{k}{n} \cdot d^{n}\) on the number of isolated solutions of \(A\).

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This bound in the Bezout inequality for tropical prevarieties is close to sharp.

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The sum of Betti numbers is less than
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The proof involves the general Tropical Bezout Theorem in terms of mixed Minkowski volumes (Bertran-Bihan, Steffens-Theobald).

\section*{Construction of a tropical polynomial system with many isolated points} solutions.

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\section*{Theorem}

One can construct a tropical system with \(k(n-1), k \geq 3\) polynomials in \(n \geq 2\) variables of degrees \(4 d, d \geq 1\) with \(2(k-1)^{n-1} d^{n}\) isolated solutions.
projection of \(n=2\)
Newton polytope Tropical curve


System A: \(k\) tropical curves shifted down by 3,6,.., \(3(k-1)\); isolated points of \(A\) :
\[
\alpha, \beta-3 j), 0 \leq j \leq k-2
\]

projection of
\[
n=2
\]
pret of \(n=2\)

\[
\delta-x>3 k
\]


System B: the curve is shifted down by \(3,6, \ldots, 3(k-1)\). The resulting \(k\) curves have \(2(k-1) d^{2}\) isolated intersection points.

\section*{Construction for an arbitrary number \(n\) of variables}

\section*{Take \(n-1\) copies of system \(B\) in variables \(x_{1}, y\), and in \(i\)-th copy, \(1 \leq i \leq n-1\) replace \(y\) by \(x_{i+1}\). The resulting tropical system has desired \(2(k-1)^{n-1} d^{n}\) isolated solutions.}

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\section*{Algorithm for solving tropical linear systems: finite coefficients}

First assume that the coefficients of a tropical linear system \(A=\left(a_{i, j}\right)\) are finite: \(0 \leq a_{i, j} \leq M, 1 \leq i \leq n, 1 \leq j \leq m\).

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If \(a_{i, j}+x_{j}=\min _{1 \leq 1 \leq n}\left\{a_{i, l}+x_{l}\right\}\) mark entry \(i, j\) with \(*\). The first row contains a single \(*\) (otherwise, \(x\) is a solution of \(A\) and every other row contains at least two *.

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\[
B=\left(\begin{array}{ll}
B_{1} & B_{2} \\
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Modify vector \(x_{1}, \ldots, x_{n}\) adding (classically) to it a vector \((b, \ldots, b, 0, \ldots, 0)\) for integer \(b=\max _{i}\left\{a_{i, j}+x_{j}-a_{i, l}-x_{l}\right\}\) where \(j\) runs right columns, \(I\) runs left columns, \(i\) runs rows from matrices \(\left(B_{1} B_{2}\right)\) and \(\left(B_{3} B_{4}\right)\).

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Construct recursively a set \(L\) of the left columns by augmenting. As a base of recursion the first column belongs to \(L\).


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To estimate the number of steps of the algorithm define a tropical norm of a vector (in the tropical projective space) \(\left(y_{1}, \ldots, y_{n}\right)\) as
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\section*{Solving tropical linear systems over \(\mathbb{Z}_{\infty}\)}

For the inductive (again on \(m\) ) hypothesis assume that ( \(m-1\) ) \(\times n\) matrix \(A^{\prime}\) (obtained from \(A\) by removing its first row) has a block form (after permuting its rows and columns)


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\cdots & \cdots & \cdots & \cdots & \cdots \\
A_{t-1,1} & A_{t-1,2} & \cdots & A_{t-1, t-1} & \infty \\
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A finite vector \(y=\left(y_{1}, \ldots, y_{n}\right)=:\left(y^{(1)}, \ldots, y^{(t)}\right) \in \mathbb{Z}^{n}\) is produced (where \(y^{(1)}, \ldots, y^{(t)}\) is its partition corresponding to the block structure) such that each diagonal block \(A_{p, p}, 1 \leq p \leq t-1\) has * (with respect to vector \(y^{(p)}\) ) everywhere on its diagonal and no \(*\) above the diagonal. Matrix \(A_{p, p}\) is of size \(u_{p} \times v_{p}\) with \(u_{P} \geq v_{p}\).

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\section*{Continuation: modifying candidate for a solution}

To be closer to the finite case \(\mathbb{Z}\) extend the lowest block \(\overline{A_{t, 1}} \overline{A_{t, 2}} \cdots \overline{A_{t, t-1}} \overline{A_{t, t}}\) of \(A^{\prime}\) by joining to it the first row of \(A\) as its first row. The resulting extension of matrix \(\overline{A_{t, t}}\) denote by \(C\).

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The algorithm modifies vector \(y^{(t)}\) keeping it to be a solution of \(\overline{A_{t, t}}\) and keeping the same notation for the modified vectors.

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To be closer to the finite case \(\mathbb{Z}\) extend the lowest block \(\overline{A_{t, 1}} \overline{A_{t, 2}} \cdots \overline{A_{t, t-1}} \overline{A_{t, t}}\) of \(A^{\prime}\) by joining to it the first row of \(A\) as its first row. The resulting extension of matrix \(\overline{A_{t, t}}\) denote by \(C\). Again as in the finite case assume (after a permutation of the columns) that a single \(*\) (with respect to vector \(y^{(t)}\) ) in the first row of \(C\) is located in the first column.

The algorithm modifies vector \(y^{(t)}\) keeping it to be a solution of \(\overline{A_{t, t}}\) and keeping the same notation for the modified vectors. If \(y^{(t)}\) is a solution of \(C\) then vector \(\left(\infty, \ldots, \infty, y^{(t)}\right)\) is a solution of \(A\) and the algorithm terminates the inductive step.

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In a similar way as in the finite case the algorithm recursively constructs a set \(L\) of the left columns of \(C\) and accordingly modifies vector \(y^{(t)}\).

\section*{Continuation of modifying a candidate: graph of possibly infinite coordinates}

In addition, the algorithm considers an oriented graph with the nodes being the coordinates of vector \(y^{(t)}=:\left(y_{1}^{(t)}, \ldots, y_{s}^{(t)}\right)\) and with an edge from node \(y_{j}^{(t)}\) to \(y_{l}^{(t)}\) when \(y_{j}^{(t)}-y_{l}^{(t)} \leq M\) (remind that all finite coefficients of matrix \(A\) satisfy \(0 \leq a_{i, j} \leq M\) ).

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C_{1} & \infty \\
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C_{3} & C_{4}
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\section*{- Lare columns of a square matrix C. - (tropically nonsingular) \(C_{1}\) contains * everywhere on the diagonal}

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This completes the inductive step of the algorithm and constructing a new block structure of matrix \(A\).

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The algorithm terminates if either all the columns or all the rows are exhausted. If all the columns are exhausted then \(A\) has no solution.
Otherwise, if first all the rows are exhausted then \(\left(\infty, \ldots, \infty, y^{(t+1)}\right)\) is a solution of \(A\).```

