

17/11/2023

Introducing string field theory from a geometrical perspective

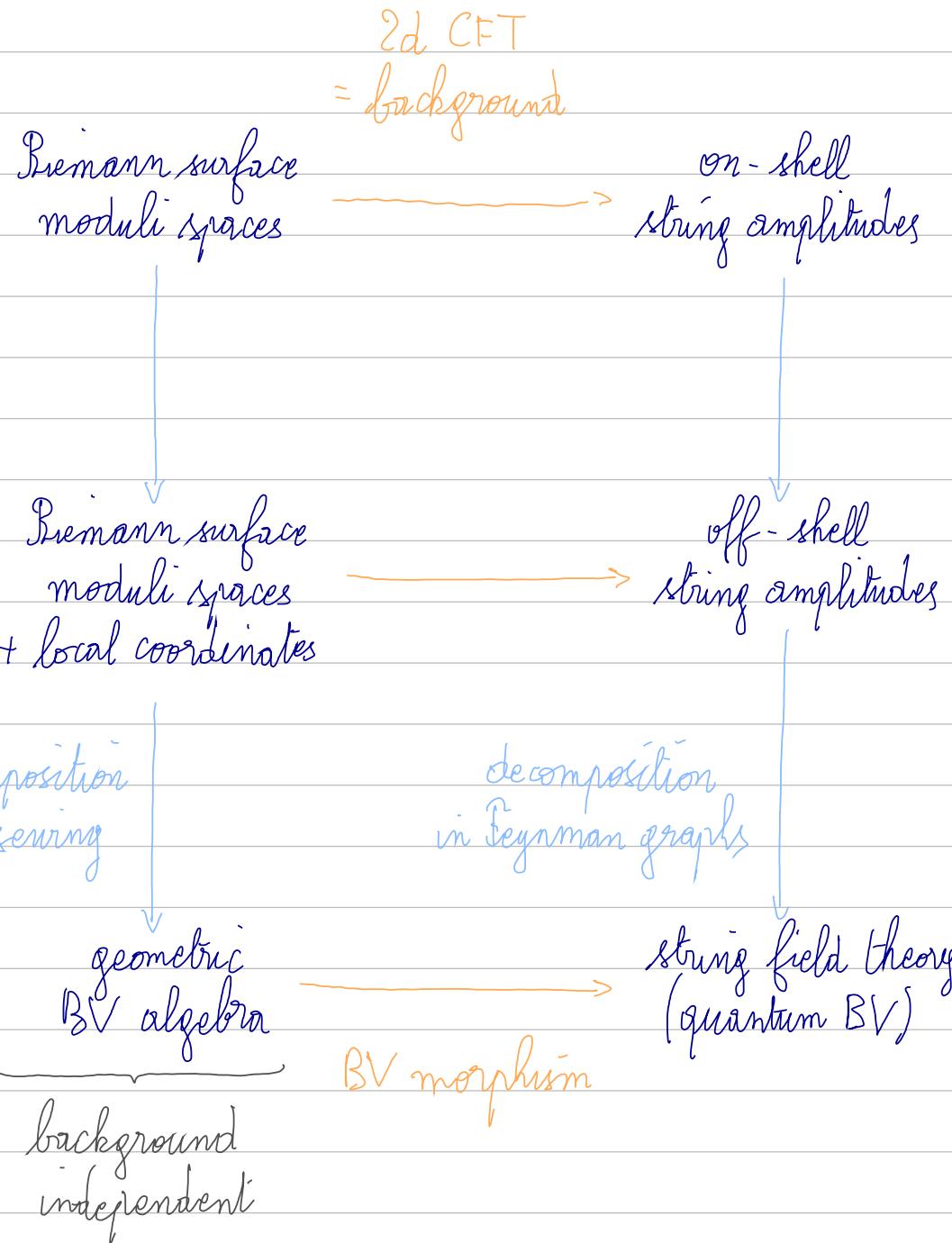
- Harold ERBIN

SFT:

- 2nd quantization of string theory
- standard QFT with: $\propto \#$ of fields, non-polynomial, non-locality $\propto e^{-k}$
- constructive: makes clear geometry, symmetries, UV finiteness
- use QFT tools: off-shell, renormalization, analyticity...
- consistency properties: background independence, Fuchsby rules, unitarity, crossing symmetry, IR finiteness

Difficulties:

- non-locality (problems with position representation)
 - interactions not constructed explicitly
- two directions with Neman Shlomi Sefat
- machine learning [2211.09128]
 - cubic theory [2308.08587]

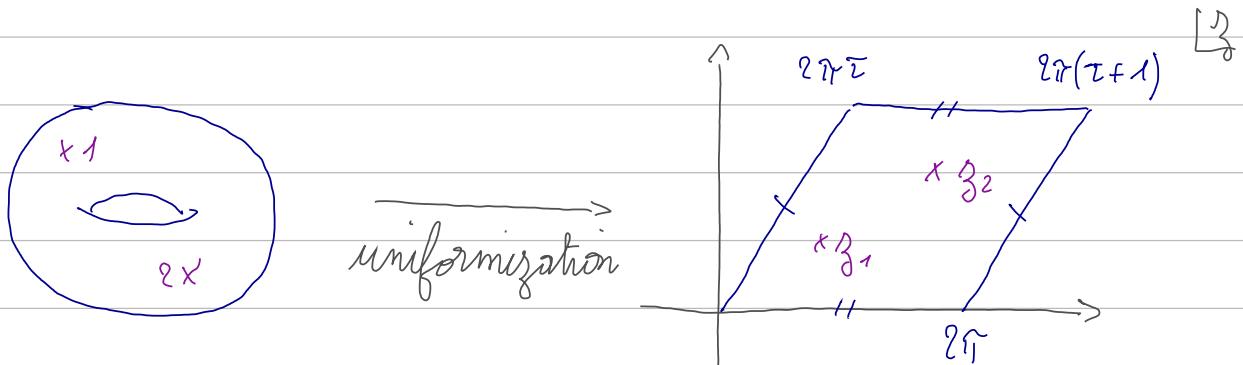


Goal: explain this diagram

1. Riemann surface moduli spaces

Ex: torus with two punctures, $\Sigma_{1,2}$

= genus-1 Riemann surfaces with 2 marked points



Uniformization coordinate:

$$ds^2 = |dz|^2 \quad z \sim z + 2\pi \sim z + 2\pi i$$

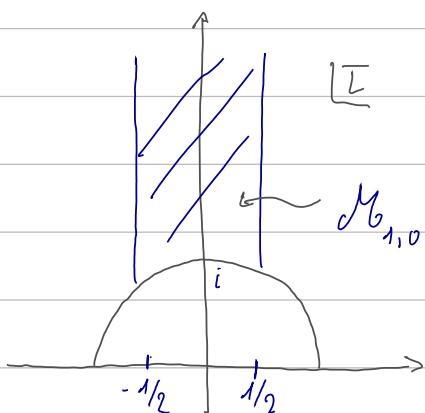
todo: read more

Symmetry (CKV): $U(1)$

$$z \rightarrow z + \xi$$

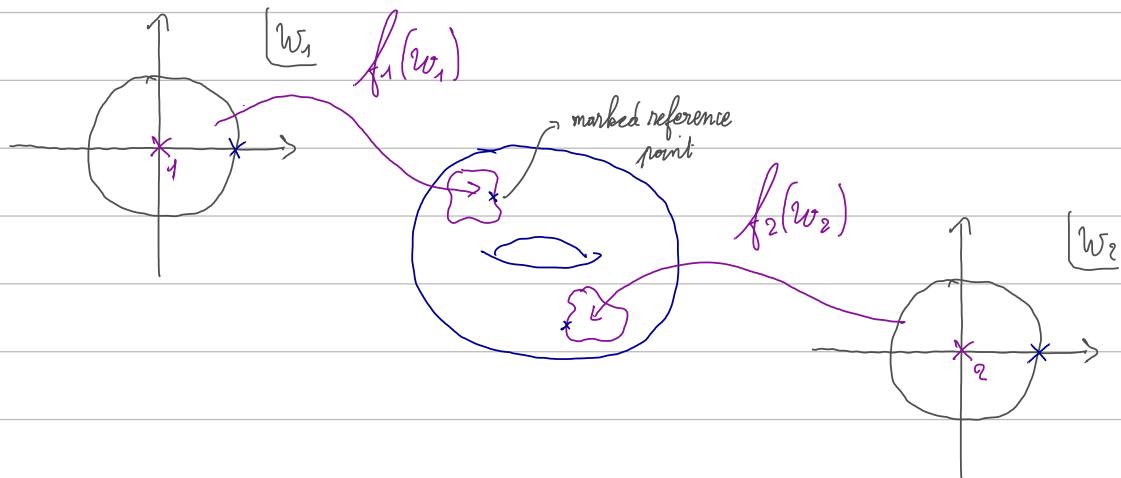
\Rightarrow can fix the position of one puncture, say $z_2 = 1$

Moduli parameters $(\tau, z_1) \in \mathcal{M}_{1,2}$
 = parametrize surfaces which are topologically inequivalent



In general: moduli space $\mathcal{M}_{g,n}$ for n -punctured genus- g Riemann surfaces $\Sigma_{g,n}$

2 Riemann surface moduli spaces with local coordinates



$f_i(w_i)$: transition functions between surface coordinate patches and local coordinate patches w_i .

Puncture locations: $f_i(0) = p_i$

Motivations:

1. punctures are sources of negative curvature, so cannot work with flat metric: introduce local coordinates w_i s.t metric is locally flat $|dw_i|^2$

(in fact, metric is $|dw_i|^2 / [w_i]^2$, semi-infinite cylinder conformally equiv to $|dw_i|^2$)

2. decouple action of CKV ($SL(2, \mathbb{C})$ or sphere) from punctures:

$$f_i \rightarrow \frac{af_i + b}{cf_i + d} \quad w_i \rightarrow w_i$$

3. Geometric BV algebra

Plumbing fixture = sewing:

- pick two punctures on two surfaces $\sum_{g_1, n_1}^{(1)}$ and $\sum_{g_2, n_2}^{(2)}$
- identify coordinate patches by cutting and gluing

$$w_{n_1}^{(1)} w_{n_2}^{(2)} = q \quad |q| < 1$$

new surface: $\sum_{g_1+g_2, n_1+n_2-2} := \sum_{g_1, n_1} \# \sum_{g_2, n_2}$

parametrization:

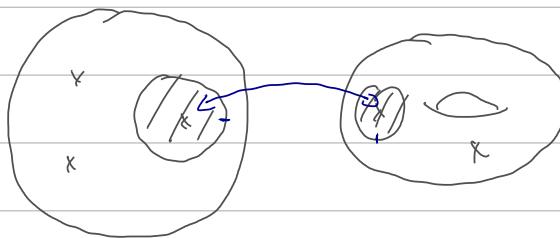
$$q = e^{-s+i\theta} \quad s > 0, \theta \in [0, 2\pi) \quad \text{serves as moduli}$$

equivalent to connecting surfaces by a long tube

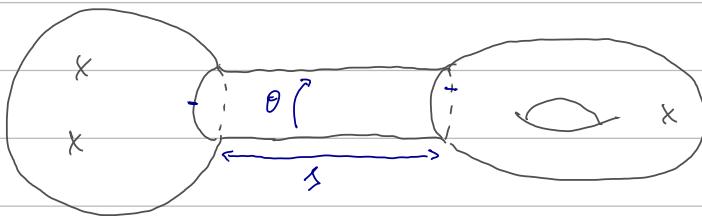
- s : length

- θ : twist

"separating degeneration" (can have non-sep. using punctures on same surface)



$s \rightarrow \infty$ limit:



But: not all surfaces can be obtained by gluing

→ decomposition of $\mathcal{M}_{g,n}$:

- $\mathbb{F}_{g,n}$: Feynman region

surfaces with tubes (close to degeneration)

- $V_{g,n}$: fundamental vertex region
other surfaces

Note: decomposition depends on choice of local coord.

Given two subspaces $\mathcal{V}_{g_1, n_1}^{(1)}$ and $\mathcal{V}_{g_2, n_2}^{(2)}$ (separating):

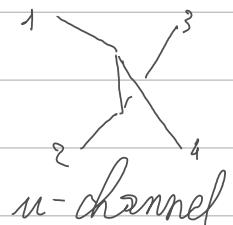
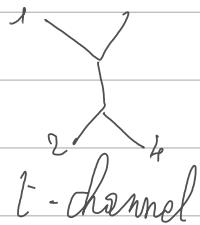
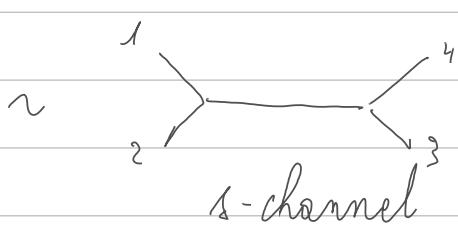
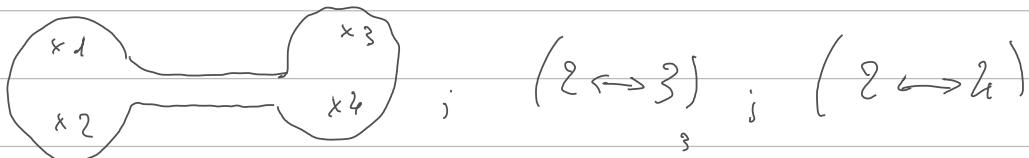
- $\mathcal{V}_{g_1, n_1}^{(1)} \# \mathcal{V}_{g_2, n_2}^{(2)}$: sewing between all surfaces in subspaces, with symmetrization over punctures
- $\{\mathcal{V}_{g_1, n_1}^{(1)}, \mathcal{V}_{g_2, n_2}^{(2)}\}$: twist sewing, same as $\#$ but keep $s=0$

Given a single subspace $\mathcal{V}_{g, n}$ (non-separating):

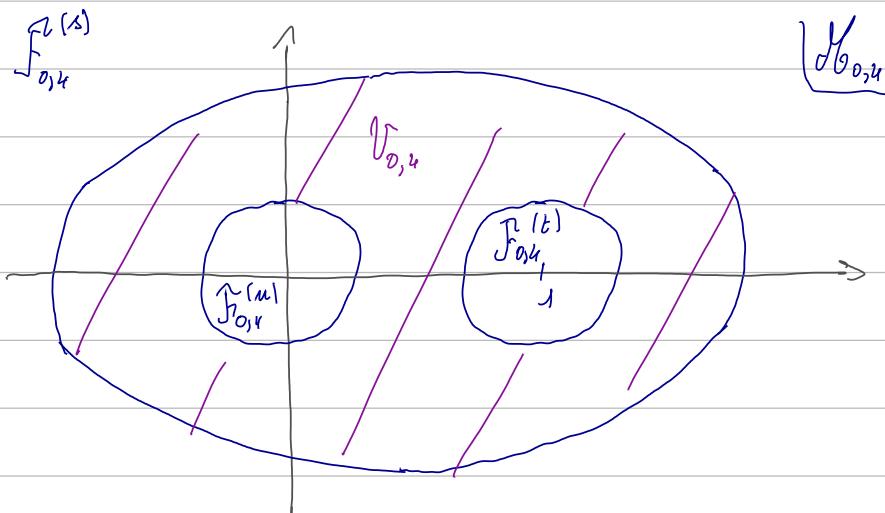
- $\# \mathcal{V}_{g, n}$: gluing
- $\Delta \mathcal{V}_{g, n}$: twist sewing

Recursive construction:

- $g=0, n=3$: $\mathcal{V}_{0,3} = \mathcal{M}_{0,3} = 1$
- $g=0, n=4$: 3 different ways of gluing



$$\mathcal{M}_{0,4} = \mathcal{F}_{0,4} + \mathcal{V}_{0,4} \quad \text{where } \mathcal{F}_{0,4} = \mathcal{F}_{0,4}^{(s)} + \mathcal{F}_{0,4}^{(t)} + \mathcal{F}_{0,4}^{(u)} \\ = \mathcal{V}_{0,3} \# \mathcal{V}_{0,3}$$

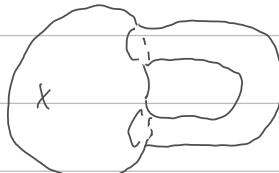


\mathcal{C}_{sc} : with $SL(2, \mathbb{C})$ local coordinates:

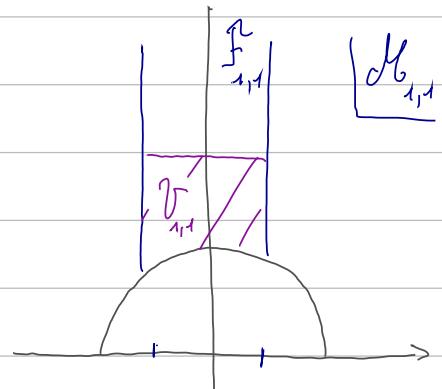
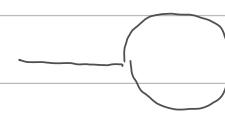
- s -boundary: ellipse
- t, u -boundaries: limacons of Pascal

We have: $\delta V_4 + \{V_3, V_3\} = 0$

- $g = l, n = l$:

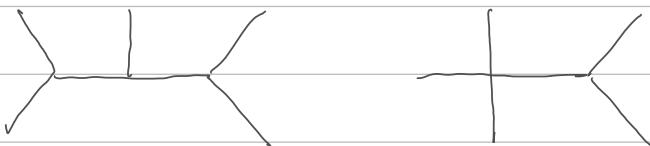


\sim



$$\tilde{F}_{1,1} = \# V_{0,3}$$

- $g = 0, n = 5$: $\tilde{F}_{0,5} = V_{0,3} \# V_{0,3} \# V_{0,3} + V_{0,3} \# V_{0,4}$



Define formal sum:

$$V = \sum_{g,n} V_{g,n}$$

Then V solves the geometric BV identity:

$$\delta V + \frac{1}{2} \{V, V\} + \Delta V = 0$$

4. String theory

String theory spacetime background:

matter CFT_m
 $C_m = 26, h_i, c_{ijk}$

ghost CFT_{gh}
 $c_{gh} = -26$
 (universal)

string coupling
 g_s

[Bergman-Zwiebach, hep-th/9411047]

Note: $\{h_i, c_{ijk}\}$ constrained by: [Sonoda '88]

- $g=0, n=4$ crossing symmetry
- $g=1, n=1$ modular covariance

Define a map from moduli spaces to string amplitudes

Given a subspace $\mathcal{P}_{g,n} \subset M_{g,n}$ and n states $V_i \in \mathcal{H}_m$, define:

$$S_{g,n}(V_1, \dots, V_n) := \int_{\mathcal{P}_{g,n}} d^{\dim \mathcal{P}_{g,n}} (\dots)_{gh} \times \left\langle \prod_{i=1}^n f_i \circ V_i(0) \right\rangle_m$$

Building blocks:

- ghosts: arise from gauge fixing 26 diffeos of worldsheet
 \rightarrow provides measure on $\mathcal{P}_{g,n}$
- $V_i \in \mathcal{H}_m$ (matter CFT Hilbert space): external states
 defined by quantum numbers (momentum, etc.)
 \rightarrow inserted at origin of local coordinate patches, $w_i = 0$
- f_i : conformal transformation
 ex: for V_i primary (h_i, h'_i):

$$f_i \circ V_i(0) = |f'_i(0)|^{2h_i} V_i(f_i(0))$$

note: on-shell, $h_i = 0 \Rightarrow$ dependence in f_i drops

- CFT correlation functions on $\Sigma_{g,m}$: function of moduli

String theory (n-point, q-loop):

- $\mathcal{M}_{g,n}(V_1, \dots, V_n)$ with V_i (0,0)-primary (on-shell)
(no local coordinates)

→ on-shell amplitudes

- $\mathcal{M}_{g,n}(V_1, \dots, V_n)$ with V_i generic

→ off-shell amplitudes

- $\mathcal{V}_{g,n}(V_1, \dots, V_n)$ with V_i generic

→ Feynman vertices

- $\tilde{\mathcal{F}}_{g,n}(V_1, \dots, V_n)$ with V_i generic

→ sum of Feynman graphs with propagators

5. String field theory

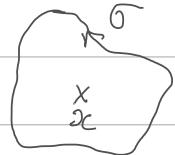
$\Psi \in \mathcal{H}$ general linear combination

$$|\Psi\rangle = \sum_{\alpha} \int \frac{d^d k}{(2\pi)^d} \psi_{\alpha}(k) |k, \alpha\rangle$$

\hookrightarrow basis of \mathcal{H}
 \hookrightarrow spacetime fields

Double Fourier expansion: spacetime and string extension

- k : continuous momentum
centre of mass in spacetime
- α , discrete quantum numbers
string direction σ , compact dimensions



BV quantum action:

$$S = \frac{l}{2} \langle \bar{\Psi}, Q_B \Psi \rangle + \sum_{g,n} \frac{h^{2g}}{n!} \langle \bar{\Psi}, V_{g,n}(\Psi^{\otimes n}) \rangle$$

\hookrightarrow BPZ inner product

Q_B : CFT BRST operator, obtained from free com

(physical state condition: $Q_B |\Psi\rangle = 0$)

Giegel gauge \Rightarrow plumbing fixture

$V_{g,n} : \mathcal{S}^{n+1} \rightarrow \mathbb{C}$ is multilinear, so define string products:

$$V_{g,n+1}(V_0, V_1, \dots, V_n) = (V_0, l_{g,n}(V_1, \dots, V_n))$$

$$l_{g,1} := Q_B$$

$\{l_{g,n}\}$ define quantum L_∞ -algebra (from geometric BV)
 \Rightarrow quantum BV equation

$$\frac{1}{2} \{S, S\} + \hbar \Delta S = 0$$

\hookrightarrow BV bracket \hookrightarrow BV Laplacian

Note: also equivalent to covering moduli spaces by sum of Feynman diagrams

Q_{SC} : classical SFT ($g=0$)

$$\text{com: } Q_B \underline{I} + \sum_{n \geq 2} \frac{1}{n!} l_{0,n}(\underline{I}^{\otimes n}) = 0$$

gauge symmetry:

$$S\underline{I} = Q_B \lambda + \sum_{n \geq 1} \frac{1}{n!} l_{0,n+1}(\underline{I}^{\otimes n}, \lambda)$$

L_∞ relations $\Rightarrow SS = 0$

$$* l_1(l_1(V_1)) = 0$$

Q_B nilpotent

$$* l_1(l_2(V_1, V_2)) \pm l_2(l_1(V_1), V_2) \pm \text{perms} = 0$$

Q_B is a derivative for l_2

$$* l_1(l_3(V_1, V_2, V_3)) \pm l_3(l_1(V_1), V_2, V_3) \pm \text{perms}$$

$$= l_2(l_2(V_1, V_2), V_3) \pm \text{perms}$$

failure of Q_B being derivative of l_2 = failure of Jacobi identity

6. Machine learning for SFT

with: Atakan Filmi Surat

Summary: for SFT vertices, we need:

- vertex regions $V_{g,n}$
- local coordinates $\{f_i^{(g,n)}\}_{i=1,\dots,n}$

- Difficult to find set consistent with geometric BV
- Background-independent problem

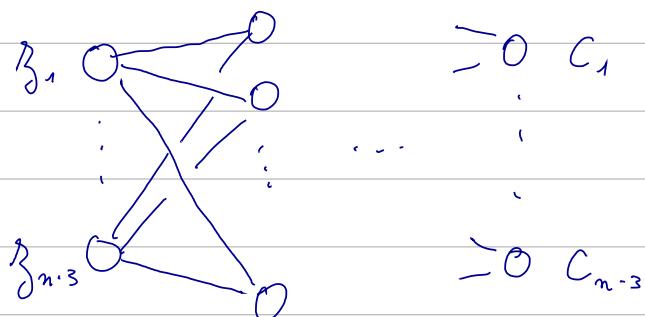
Idea: use deep learning to build $V_{g,n}$ and $f_i^{(g,n)}$

Solution to classical BV: contact vertices, characterized by Gtrelbel differentials
(proof not constructive)

f_i and $V_{g,n}$ are determined by set of moduli-dependent "accessory parameters" (limit from hyperbolic)

$\{c_1, \dots, c_{n-3}\}$
determined by solving complicated constraints $L_{i,j} = 0$
(unique solution)

Neural network:



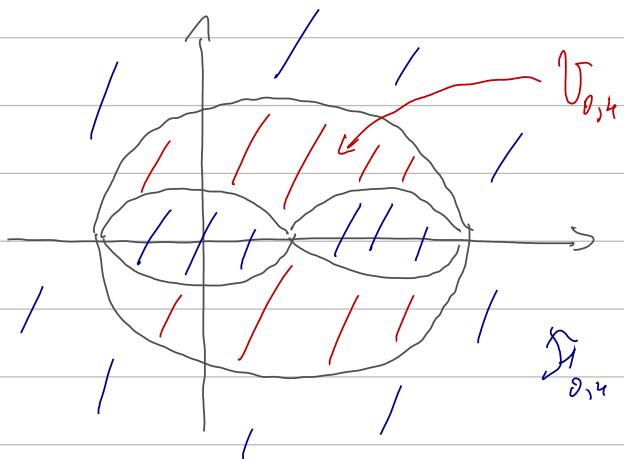
$$\text{Objective function: } \sum_{i,j} |L_{i,j}|^2 = 0$$

$L_{i,j}: g=0, n=4$: precision of 10^{-4} for c_i

$V_{g,n}$: determined by neural network with binary classification

$$\Theta(\xi_1, \dots, \xi_{n-3}) = \begin{cases} 1 & \xi_i \in V_{o,n} \\ 0 & \xi_i \notin V_{o,n} \end{cases}$$

network: outputs probability
→ boundary determined by confusion



Conclusion: deep learning is well-suited to solve geometrical problems.

Offshoot (Atalan): new insights on vertices using hyperbolic geometry and Liouville theory

Backup

Strebel differential: $\varphi = \phi(z) dz^2$

$$\phi(z) = \sum_{i=1}^n \left[\frac{-1}{(z - z_i)^2} + \frac{c_i}{z - z_i} \right]$$

\hookrightarrow punctures

c_i : "accessory" parameters (limit from Liouville acc. param.)

Metric: $ds = |\phi(z)|^2 |dz|^2 \sim \frac{|dw_i|^2}{|w_i|^2}$

\hookrightarrow semi-infinite cylinder

zeros: $\{z_i\} \mid \phi(z_i) = 0\}$

Horizontal trajectory: $\varphi > 0$

Critical graph: hor. traj. between zeros

Constraints: $\Im m \int_{z_i}^{z_d} dz \sqrt{\phi(z)} = 0 \quad \forall (z_i, z_d)$

\rightarrow system of equations for $\{c_i\}$